

ADMISSION TO THE SECOND YEAR

DEVELOPMENT OF MEASUREMENT TECHNIQUES OF STRESS-STRAIN STATE OF LIFTING MACHINERY COMPONENTS

Centro Interdipartimentale di Studi e Attività Spaziali «G. Colombo»

Scuola di Dottorato in Scienze Tecnologie e Misure Spaziali (STMS) CICLO
XXXIII

Curriculum: Misure Meccaniche per l'Ingegneria e lo Spazio (MMIS)

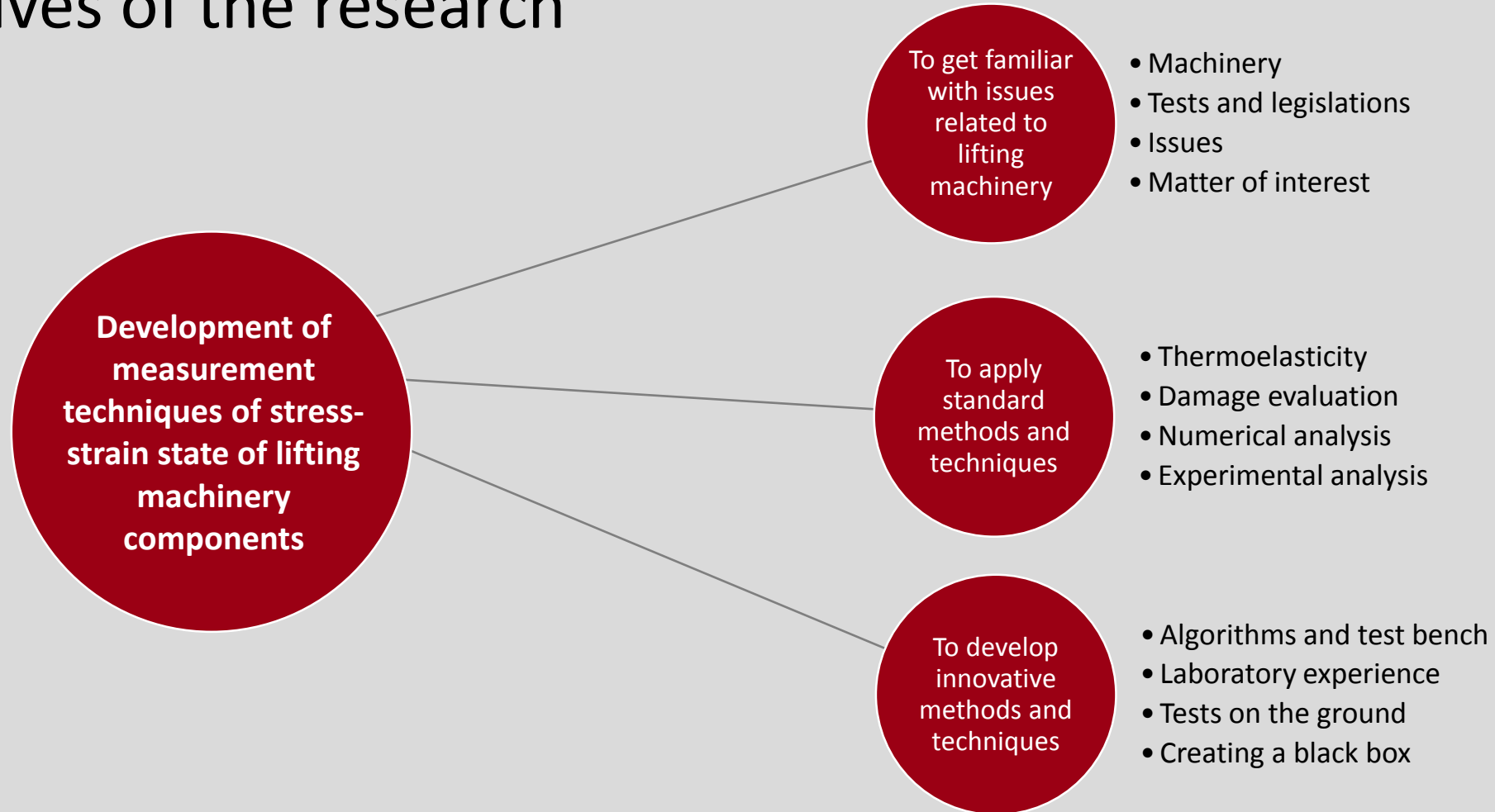
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Supervisor: Prof. Ing. Gianluca Rossi

Overview of the presentation

- Objectives of the research
- Industry
- Numerical and experimental analysis
- Further development

Objectives of the research



Industry overview

Industry

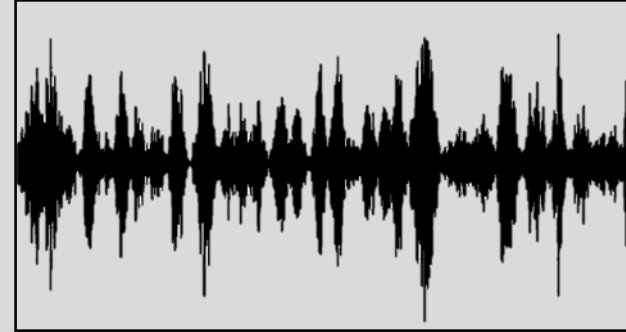


Products



Main Issues

Test and Legislations



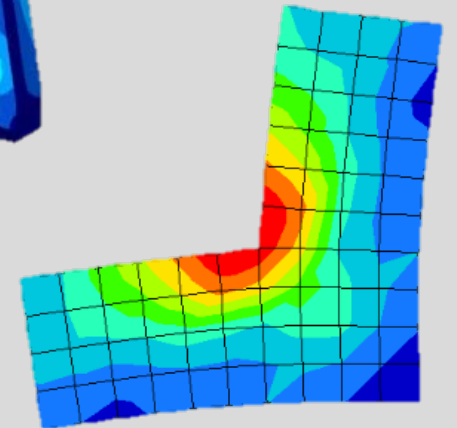
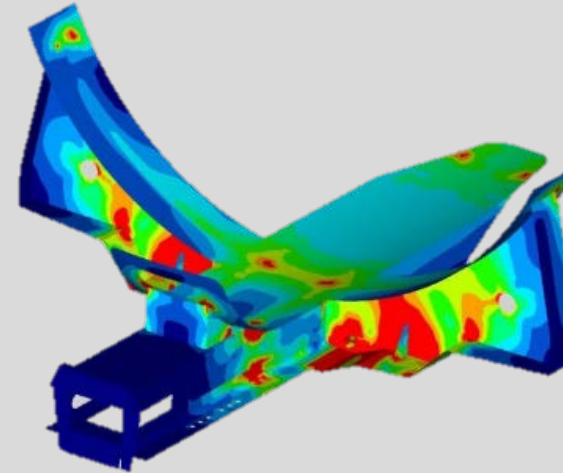
Vibrations

Critical Stress-Strain State

Fatigue Life

Comfort and life quality

Noise



Theoretical Background

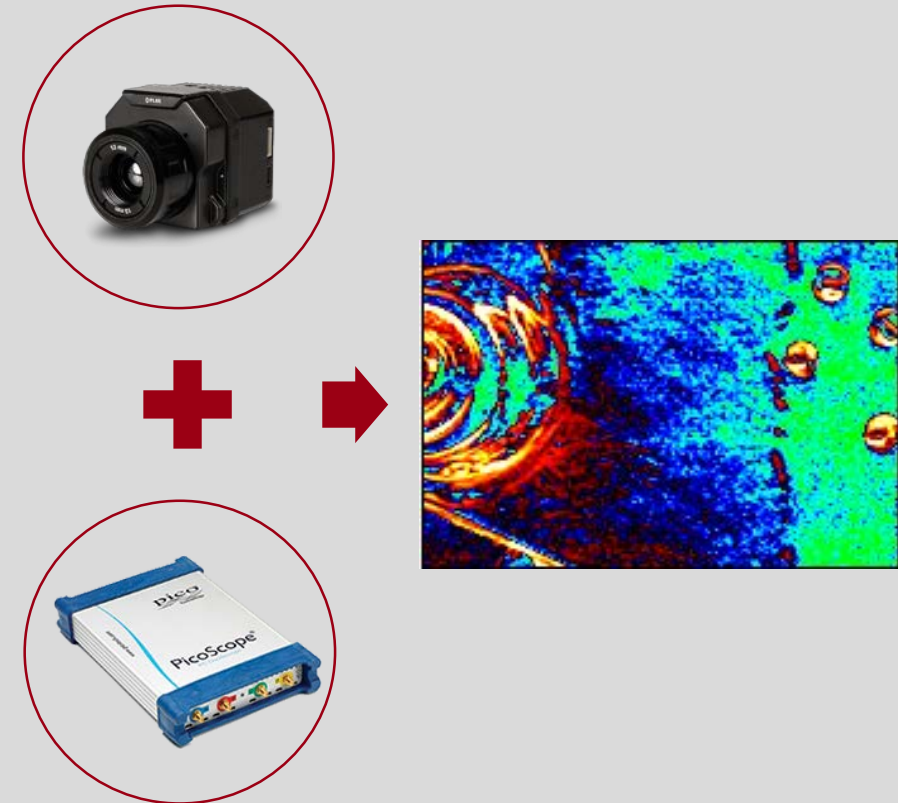
Thermoelastic Stress Analysis

$$\Delta T = \frac{-\alpha T}{\rho C_p} (\Delta\sigma_x + \Delta\sigma_y)$$

- α = Thermal expansion coefficient
- C_p = Specific heat
- ρ = Density
- T = Absolute Temperature
- $\Delta\sigma_{i,j}$ = Variation of surface tension in two orthogonal directions lying on the surface

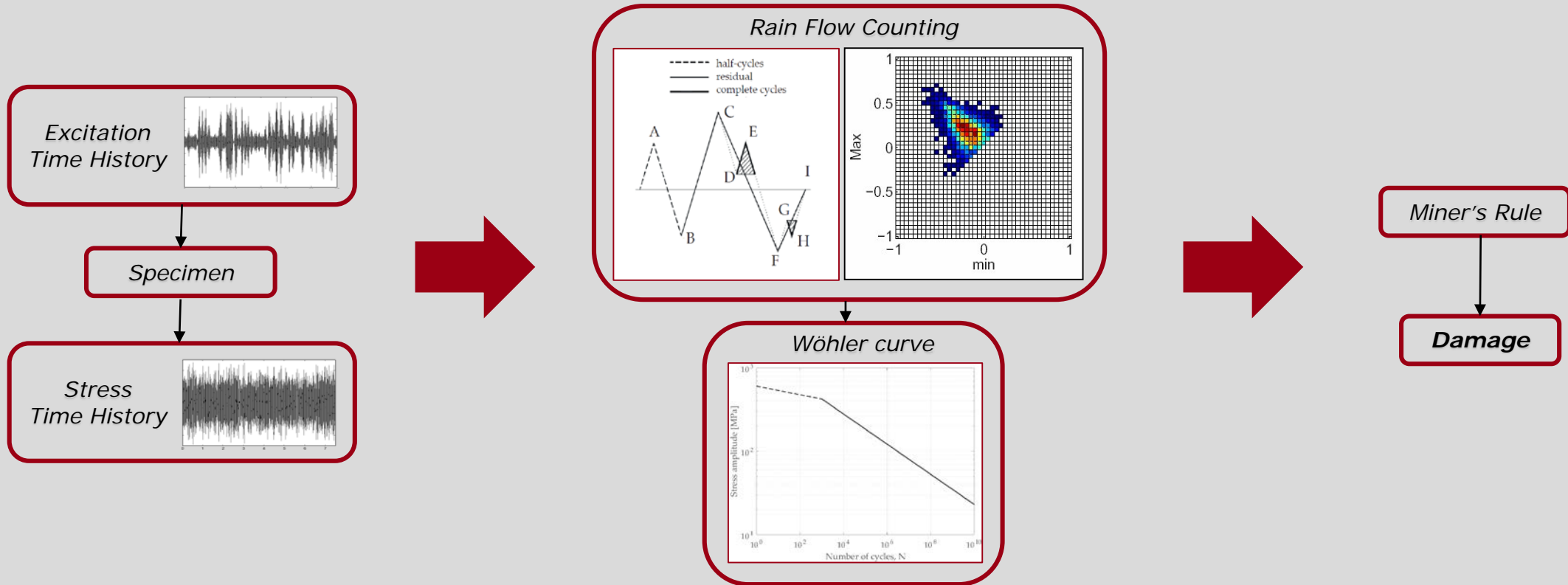
Hypothesis:

- Isotropic, homogeneous and linear elastic behavior
- Adiabatic processes



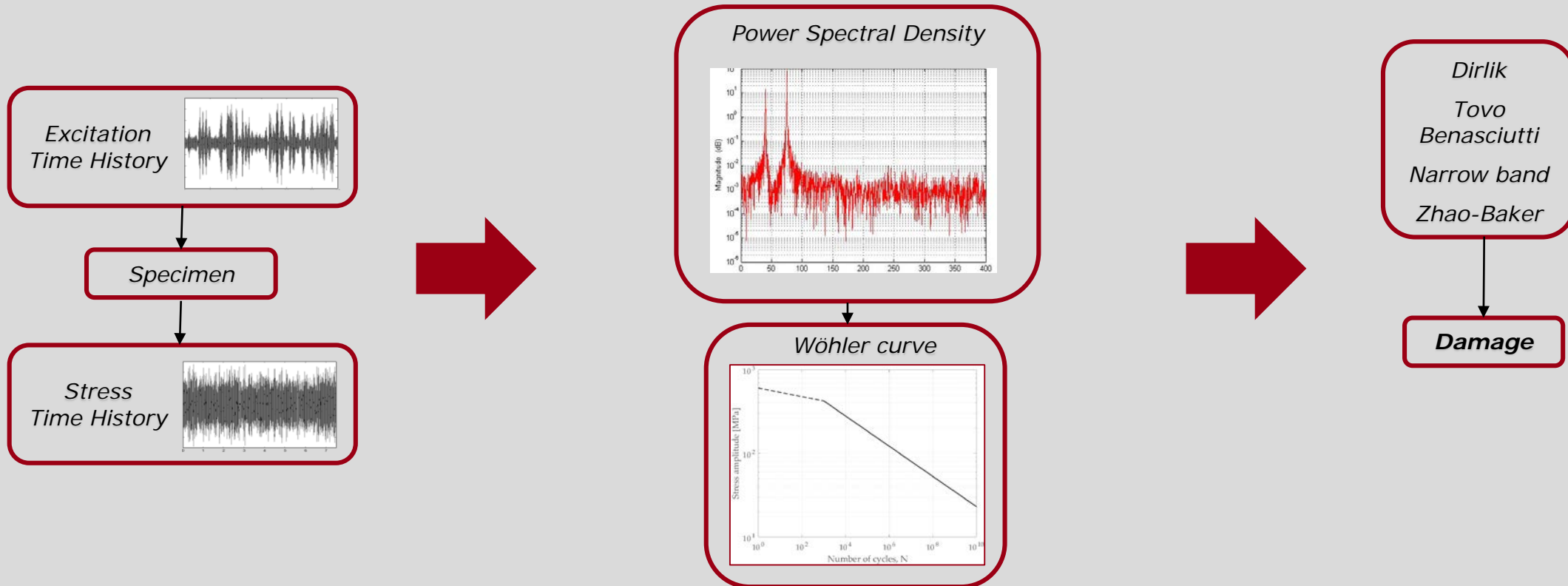
Damage evaluation

Time domain



Damage evaluation

Frequency domain



Preliminary Experimental Analysis

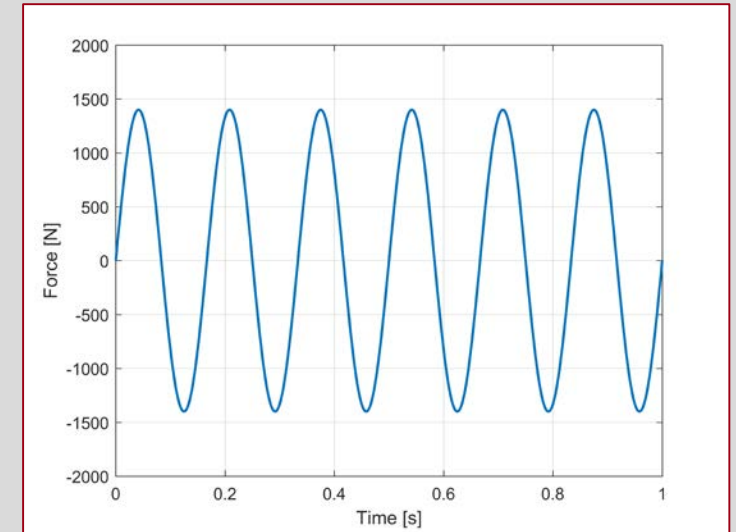
Preliminary Experimental Analysis



Terex Genie S-65



Welded area



Vibrodyne Load



Strain Gauge
Rosette

$$\begin{cases} \epsilon_{xx} = \epsilon_A \\ \epsilon_{yy} = \frac{1}{3}(2(\epsilon_B + \epsilon_C) - \epsilon_A) \\ \gamma_{XY} = \frac{1}{\sqrt{3}}(\epsilon_C - \epsilon_B) \end{cases}$$

$$\begin{cases} \epsilon_1 = \frac{1}{2} \left(\epsilon_x + \epsilon_y + \sqrt{(\epsilon_x - \epsilon_y)^2 + \gamma_{xy}^2} \right) \\ \epsilon_2 = \frac{1}{2} \left(\epsilon_x + \epsilon_y - \sqrt{(\epsilon_x - \epsilon_y)^2 + \gamma_{xy}^2} \right) \end{cases}$$

$$\begin{cases} \sigma_1 = \frac{E}{1 - \nu^2} (\epsilon_1 + \nu \epsilon_2) \\ \sigma_2 = \frac{E}{1 - \nu^2} (\epsilon_2 + \nu \epsilon_1) \end{cases}$$

$$K = \frac{\Delta \sigma_x + \Delta \sigma_y}{\Delta T_{avg}}$$

$$K = \frac{E \cdot (\epsilon_x + \epsilon_y)}{\Delta T_{avg} \cdot (1 - \nu)}$$

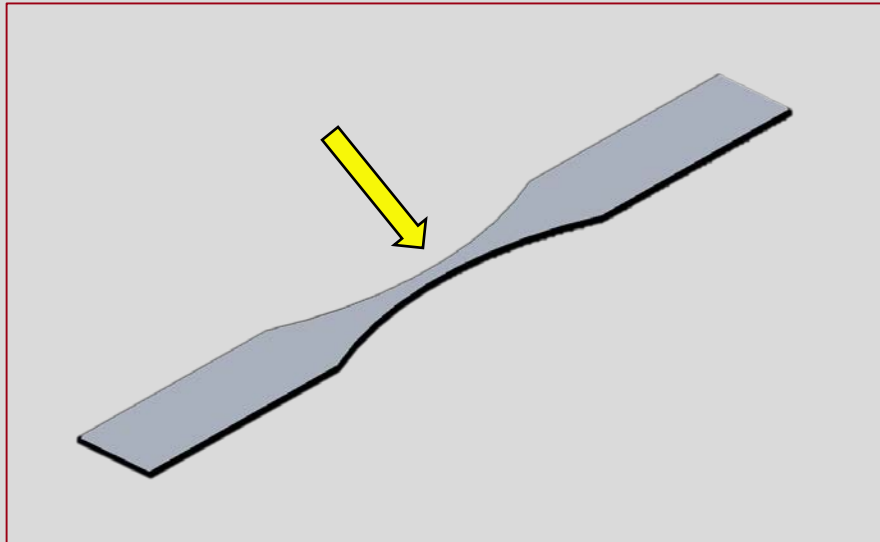


Stress Map

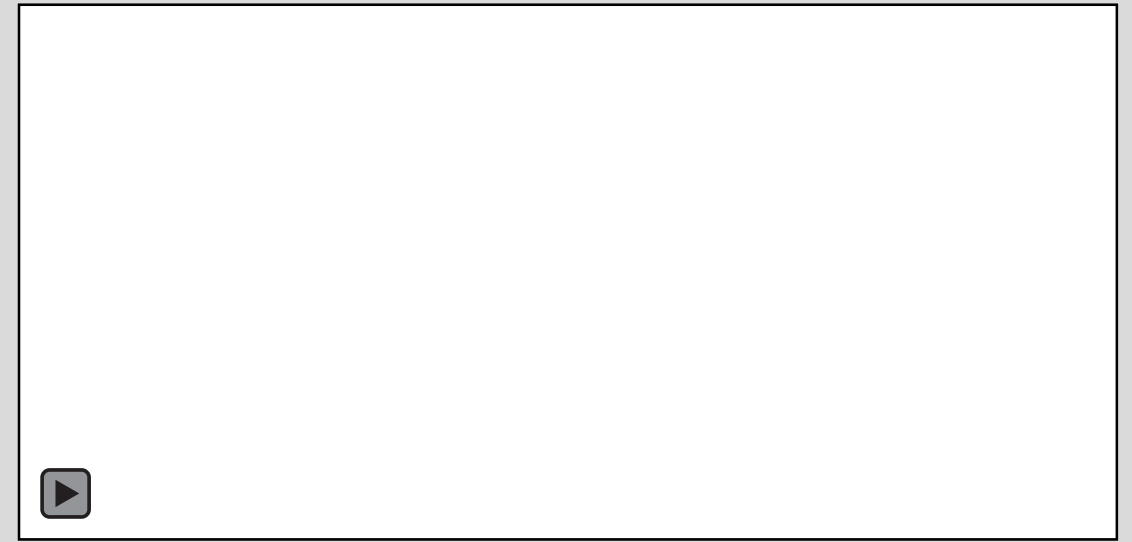
Numerical and Experimental Analysis

Damage evaluation through thermoelasticity

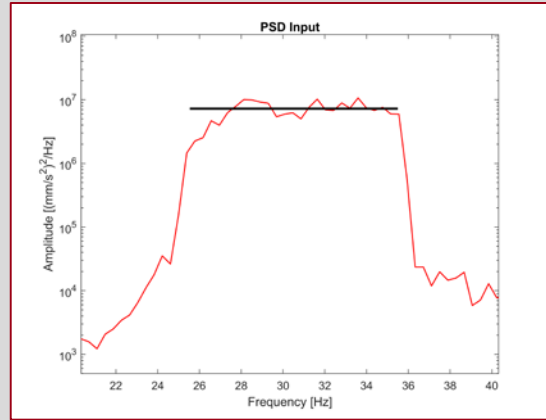
Numerical and Experimental Analysis



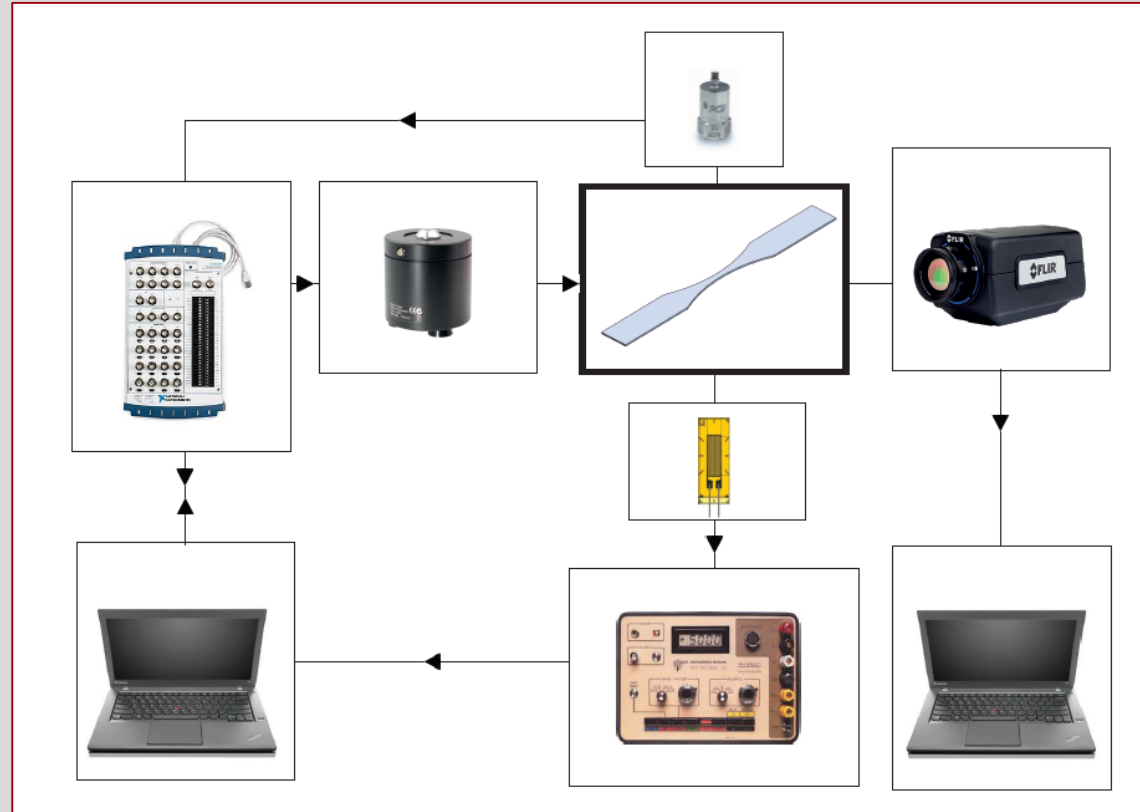
Structural Steel Specimen



Modal Analysis

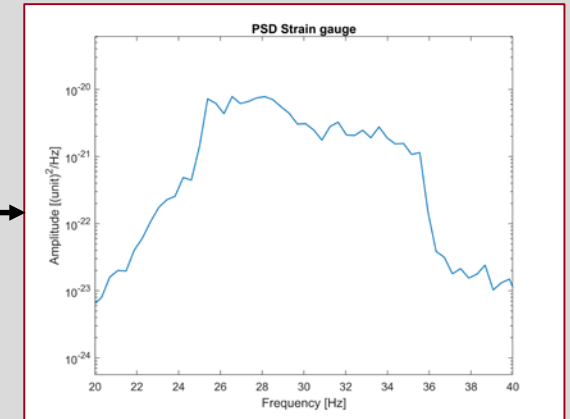
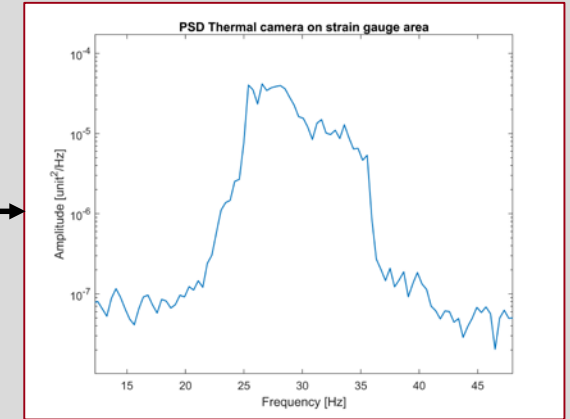


PSD Random Input
Excitation

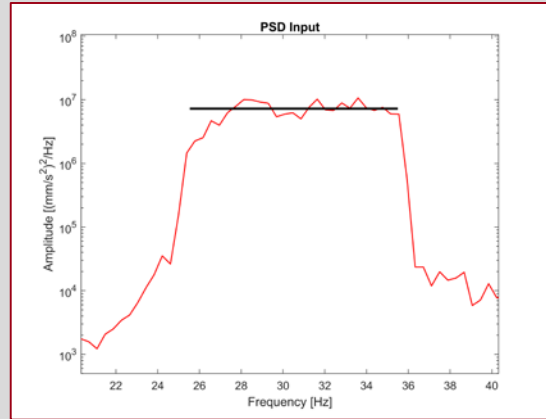


Measurement Chain

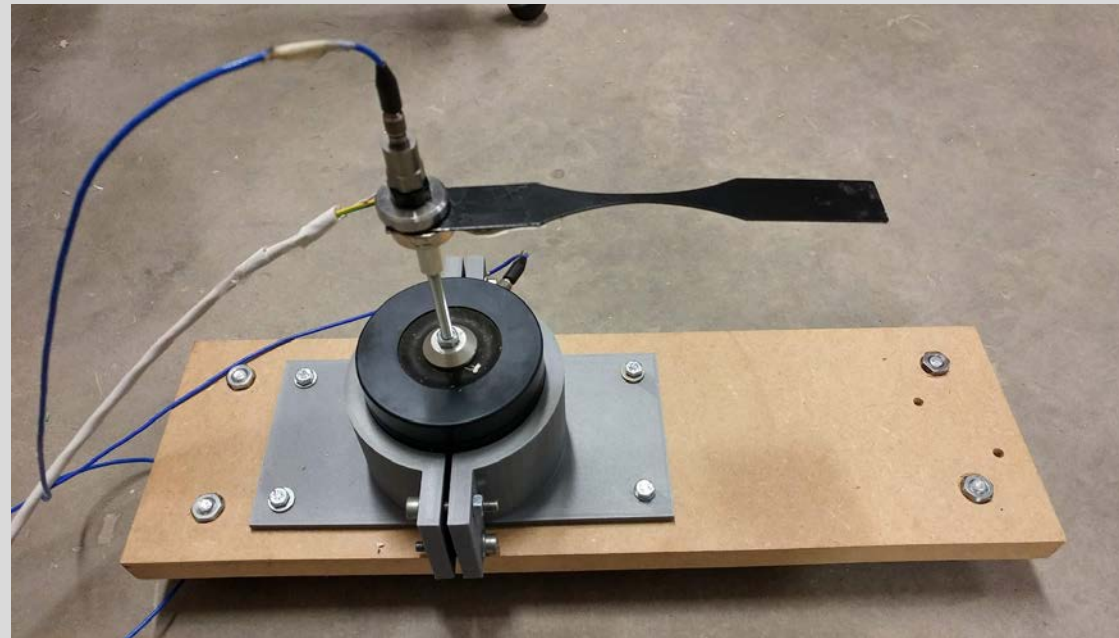
PSD Thermal camera



PSD Strain Gauge

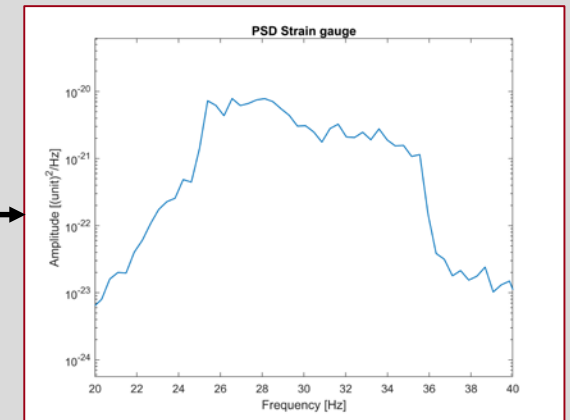
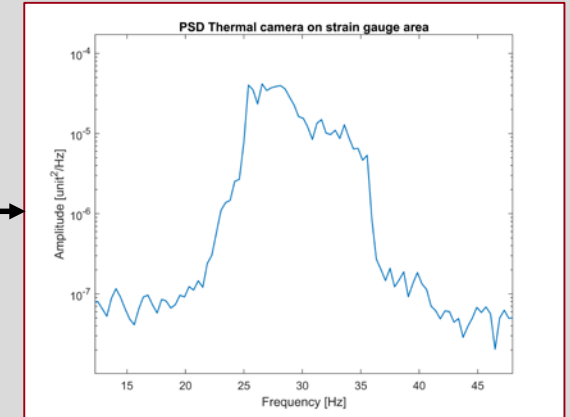


PSD Random Input
Excitation



Measurement Chain

PSD Thermal camera

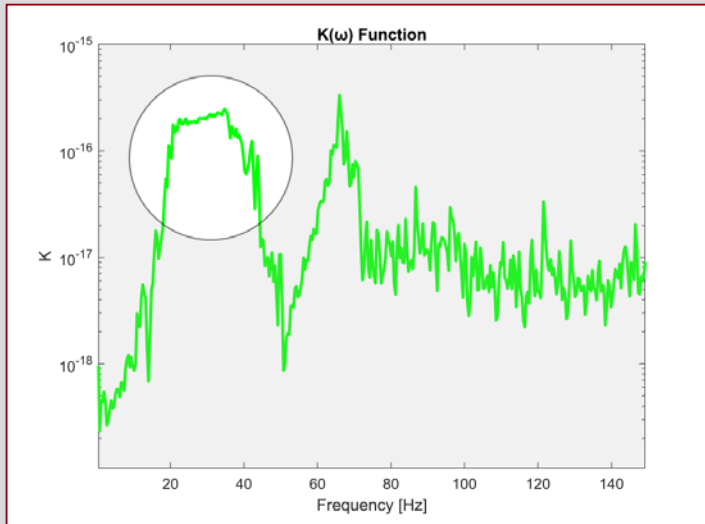


PSD Strain Gauge

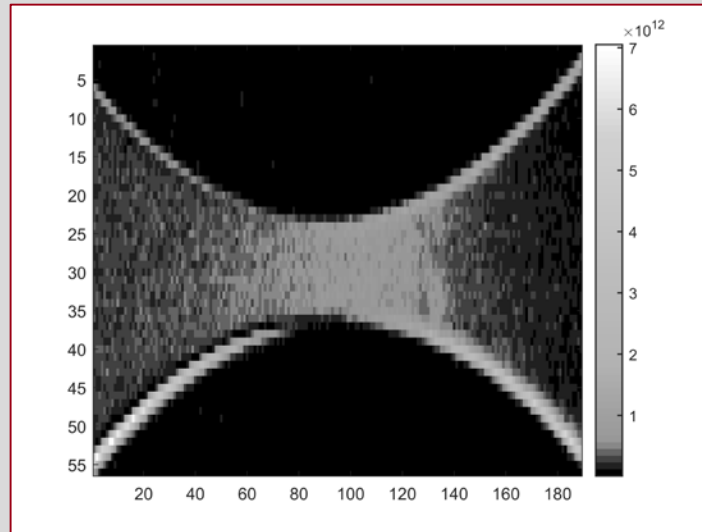
$$K(\omega) = \frac{PSD (Strain\ gauge)}{PSD (avg(thermalcamera)_{SG})}$$

$$\Theta(\omega) = \frac{W(\omega)}{K(\omega)}$$

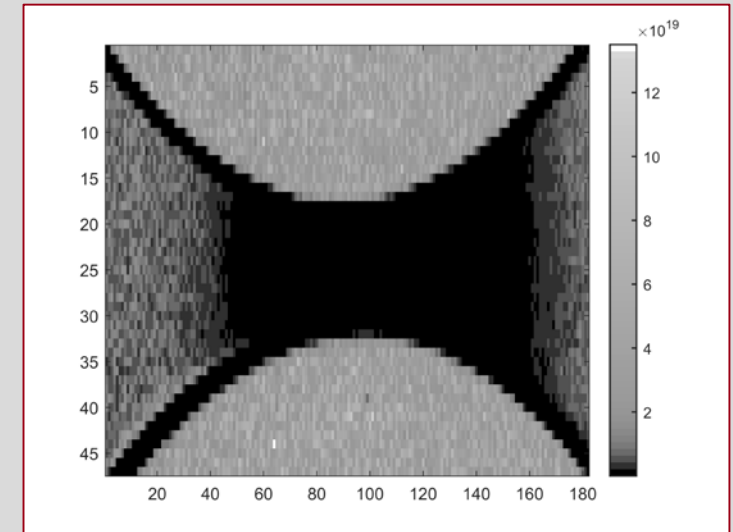
Dirlik Method



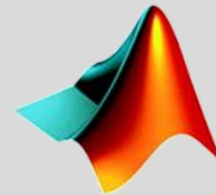
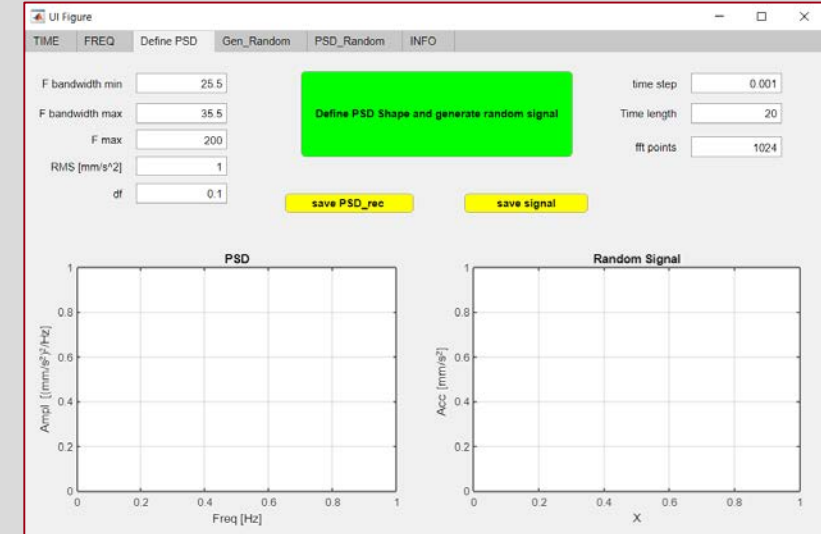
K Function



Stress PSD Response
[MPa²/Hz]

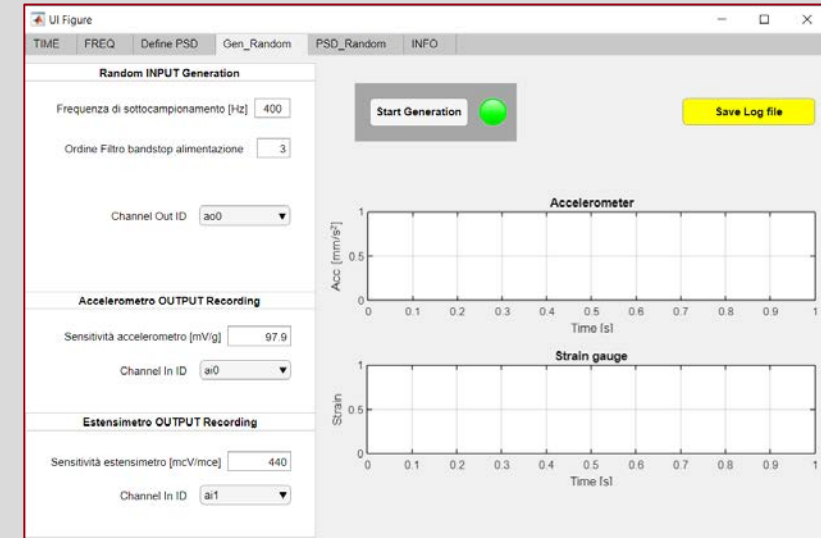
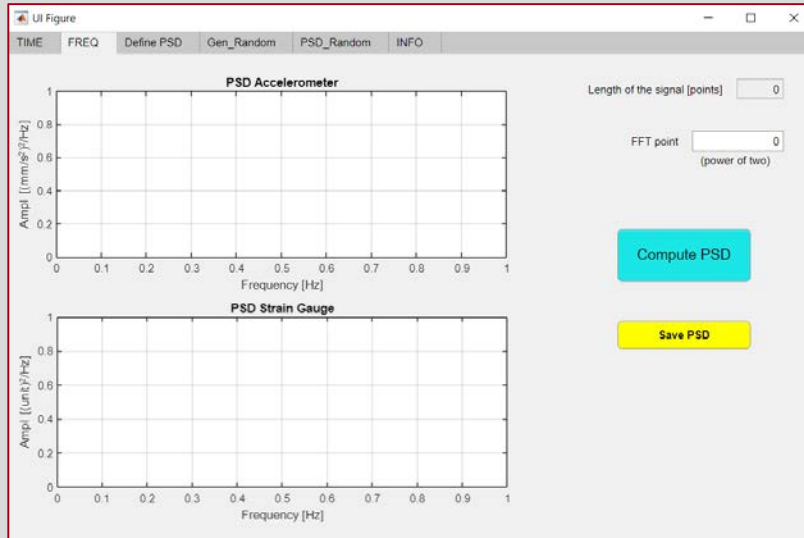


Fatigue Life [s]

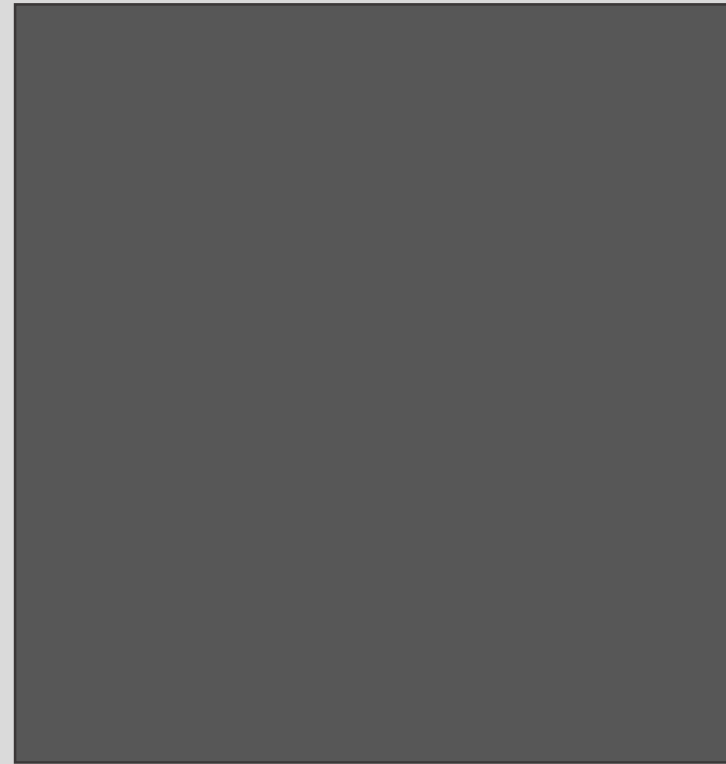


MATLAB

APP DESIGNER



Next steps and further development



Mounting bracket of front axle



Preliminary FEM Analysis

Next steps and further development

- Application of damage evaluation method to lifting machinery components
- Innovative measurement chain (e.g. GPS, gimbal, drones)
- Software development
- Develop a user friendly package

```

1: maxIterations = 1000;
2: gridSize = 2000;
3: xJan = [ 0.74079073022163, 0.74079073022163 ];
4: yJan = [ 0.12364064404492, 0.12364064404492 ];
5:
6: % Setup
7: n = numel(xJan);
8: x = linspace(xJan(1), xJan(2), gridSize);
9: y = linspace(yJan(1), yJan(2), gridSize);
10: [xGrid, yGrid] = meshgrid(x, y);
11: all = zeros(1, gridSize);
12: count = ones(1, gridSize);
13:
14: % calculate
15: z = 20;
16: for n = 1:gridSize
17:     inside = abs(z - z0);
18:     count = count + inside;
19: end
20: % count = log(count);
21:
22: % Show
23: cpTime = toc(' ');
24: assert( cpTime < 1000, 'cpTime > 1000 200 600 000' );
25: imagesc(x, y, count);
26: % axis image;
27: % colormap('jet'); hold on;
28: % title('cpTime: ' + num2str(cpTime) + ' s');
29: % xlabel('x'); ylabel('y');
    
```



Thank you for your attention