#### Primo: An Ultra-light Launch Vehicle For Nano & Microsatellites

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The microsatellite problem

1.

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Requirements				
PL mass	50 kg			
Nominal orbit	700 km polar			
Launch rate	20 lc/year			
Stage number	2			
Propulsion tech.	Hybrid			

Flight constraints				
Max longitudinal acceleration 65 m/s <sup>2</sup>				
Max dynamic pressure	35 kPa			
Take Off T/W	1.4			

- Low development, production, operations and disposal costs
- Low production, operations and disposal environmental impact

#### Requirements

ΔV contributions	Value [km/s]
Orbital Velocity (200 km)	7.79
Hohm. Trans. 200-700 km	0.28
Gravity loss	1.3
Drag loss	0.2
Steering losses	0.05
Performance margin (1%)	0.1
Total	9.72



#### Second Stage: Single

 $\bigcirc$ 

#### First Stage: EptaWeb





#### Engines configuration

Feature	ρ	T <sub>b</sub>	€/kg	Ox power	Self-p	Storable	Ignition	Isp	Cat	TNT	Avail.
LOX	1141	90.19	< 0.2	1	No	No	Yes	370	No	0	High
N <sub>2</sub> O	744	P dep.	< 5	0.36	Yes part.	Yes	Yes	320	Yes	Nd	Medium
H <sub>2</sub> O <sub>2</sub>	1440	423	< 1.7	0.94	No	Yes	No	320	Yes	1	Low

1 <sup>st</sup> stage lsp	270 s
2 <sup>nd</sup> stage lsp	310 s

#### Liquid oxidizers

1 <sup>st</sup> stage structural mass fraction	0.1
2 <sup>nd</sup> stage structural mass fraction	0.1

1 <sup>st</sup> stage ΔV	4.025 km/s
2 <sup>nd</sup> stage ΔV	5.695 km/s

#### Mass & $\Delta V$ fraction

GLOW	6360 kg
1 <sup>st</sup> stage initial mass (w/o PL)	5530 kg
1 <sup>st</sup> stage propellant mass	4975 kg
1 <sup>st</sup> stage structural mass	555 kg
2 <sup>nd</sup> stage initial mass (w/o PL)	790 kg
2 <sup>nd</sup> stage propellant mass	710 kg
2 <sup>nd</sup> stage structural mass	80 kg
<b>OF ratio</b>	2.7

Mass budget

1 <sup>st</sup> stage total initial thrust	87.5 kN	
1 <sup>st</sup> stage total initial thrust	12.5 kN	
2 <sup>nd</sup> stage initial thrust	12.5 kN	
1 <sup>st</sup> stage total final thrust	87.5 kN	
2 <sup>nd</sup> stage final thrust	8.35 kN	
Motor throttability	40%	



Fuel grain mass	190 kg
1 <sup>st</sup> stage burning time	184 s
2 <sup>nd</sup> stage burning time	211 s
Oxidizer mass flow rate	2.9 kg/s
Combustion chamber length	1.6 m
Combustion chamber diameter	0.4 m



#### Harlock motor

Pressure-feed	<ul> <li>Higher tank mass</li> <li>Pressurant needed (tanks, pipeline)</li> <li>Low control capability</li> </ul>	0.12	
Turbo-pump	<ul> <li>Liquid fuel needed (tanks, pipeline)</li> <li>Higher oxidizer mass</li> <li>Low control capability</li> <li>High development time and cost</li> </ul>	0.08	
Electric-pump	<ul> <li>Lower tank mass</li> <li>High control capability</li> <li>Low development time and cost</li> </ul>	0 0	t <sub>b</sub> = 120 s, m <sub>p</sub> = 3000 kg, p <sub>c</sub> = 3 MPa 10 20 30 40 <b>p<sub>0</sub> (MPa)</b>

#### Feed system

#### Total mass for different batteries vs Burning time. $P_t k= 10 \text{ bar}, m_d \text{ot}= 20 \text{kg/s}$ Total mass for different batteries vs tank pressure Li-Po Li-Po Li-Ion Li-Ion Total mass [kg] 001 Total mass [kg] Total mass [kg] 001 201 Li-S Li-S Tank pressure [bar] Burning time [s]

#### Electric-pump



### Electric-pump: Rutherford LRE



### Cryo-composite tanks

Fairing	10 kg
PL adapter	2 – 10 kg
Avionics & cabling	10 kg
PW system	2 kg
<b>Pressurization system</b>	2 kg
Tank	20 kg

<b>Electric-pump</b>	6 kg
<b>Feed-line</b>	5 kg
Motor	15 kg
TVC	2 kg
Misc.	6 kg
Total inert mass	80 kg

### Mass breakdown: 2<sup>nd</sup> stage

Interstage & separation sys.	30 kg
PL/stage recovery sys.	30 kg
PW system	10 kg
Avionics & cabling	20 kg
<b>Pressurization system</b>	10 kg
Tank	120 kg

<b>Electric-pump</b>	40 kg
<b>Feed-line</b>	40 kg
Motors	105 kg
TVC	30 kg
Misc.	135 kg
Total inert mass	555 kg

#### Mass breakdown: 1<sup>st</sup> stage







#### Flight simulation



#### Payload



#### Primo configuration

## 1.3 m

Max diameter

13 m Height

# **6.4 T**

# 87.5 kN

Lift-Off Thrust

20 Launches per year 2 M€

Price



- Mass & power budget iterations
- Accurate study on cryo-composite tanks
- Accurate study on ablative composites CC
- Accurate study on TVC and control systems
- 6 DOF flight simulator
- Trajectory optimizer



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