

UNIVERSITÀ
DEGLI STUDI
DI PADOVA

Development of tether-in-space technology
for propellant-less propulsion and
artificial gravity

Anese Giovanni - 39th Cycle

Supervisor: Prof. Lorenzini Enrico

Admission to the third year – 10/09/2025

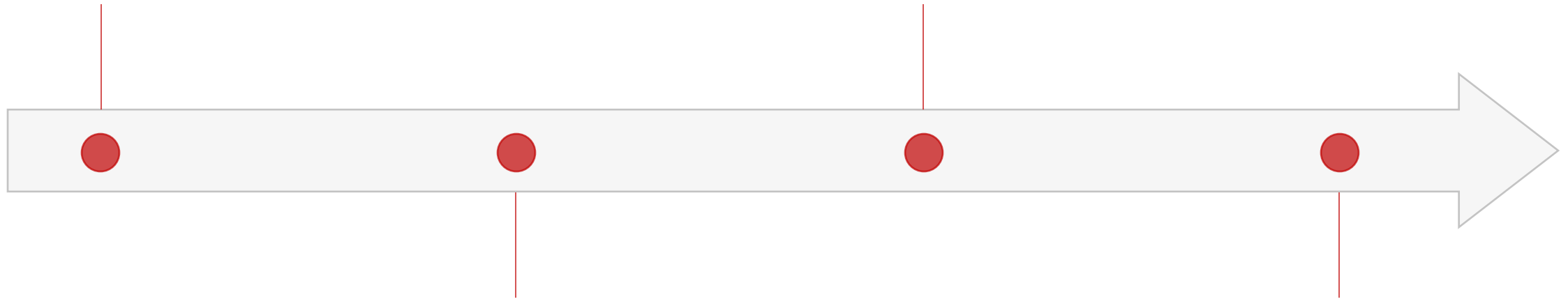


Electrodynamic tethers

- E.T.PACK-F
- Dynamics analysis
- Active EDT

Spinning Tether for Artificial Gravity

- Mission drivers definition
- Experimental test campaign
- Mission design



Spinning EDTs

- E.T.COMPACT
- Spin-up strategies
- Current control

Momentum Exchange Tethers

- Software development
- Orbital maneuvers



E.T.COMPACT project

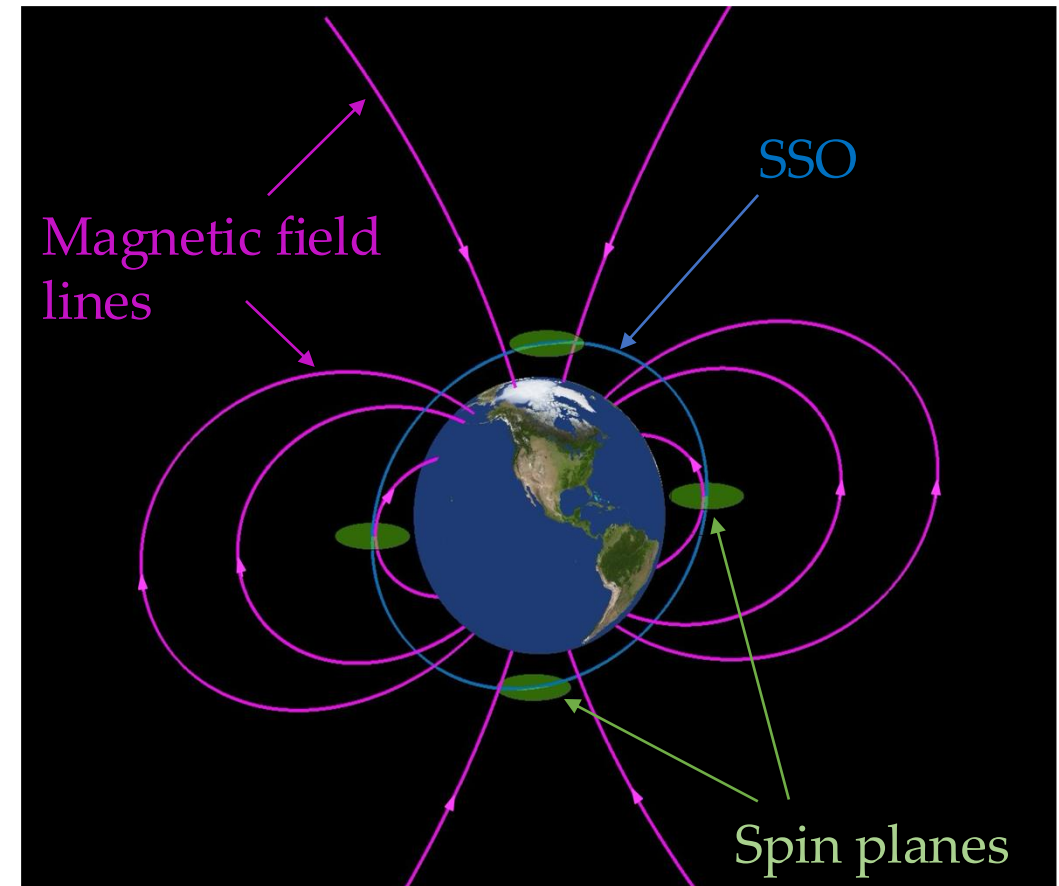
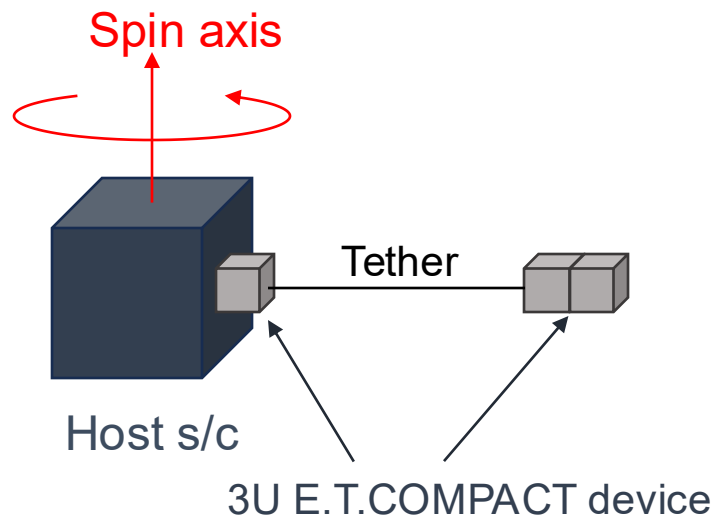


- EIC Pathfinder Project
- Goals:
 - reach TRL 4 for a miniaturized device with capability for propellant-less propulsion and power generation
 - prepare a bare-photovoltaic tether based with PVK/CIGS thin film solar cell
- Partners: UC3M, DEIMOS, UNIPD, TU Dresden, Hallocell Europe, Sunplugged, and PERSEI Space



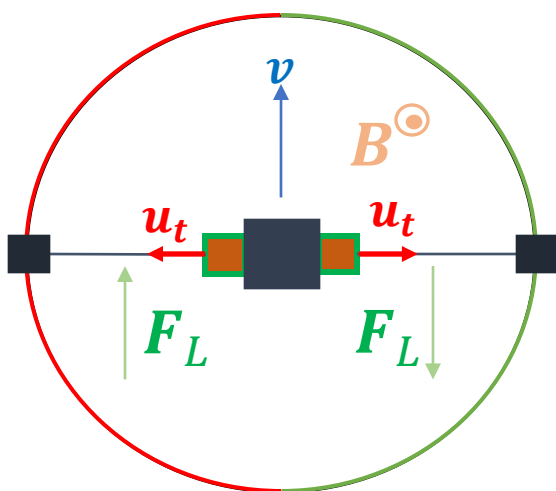
	E.T.PACK-F	E.T.COMPACT
Dimensions	12 U	3 U
Tether length	420 m	~ 300 m
Capabilities	Deorbiting	Deorbiting Reboost Retrieval Spin

- 3U CubeSat divided in 1U for the cathode and 2U for the deployment mechanism.
- Attached to a host satellite of a few hundreds kilos.
- Set to work in Sun-synchronous orbits.
- Spinning system to improve electrodynamic performances.

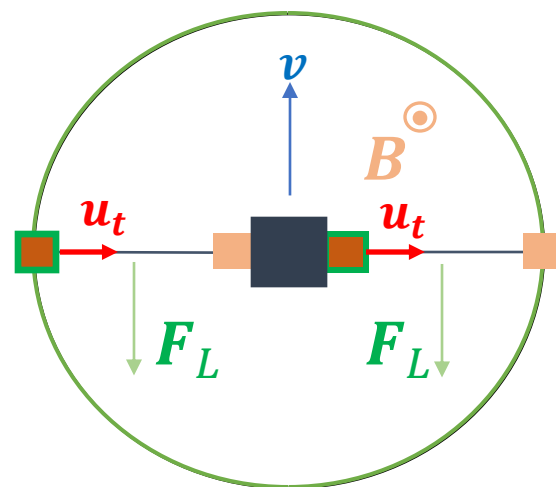


Deorbiting

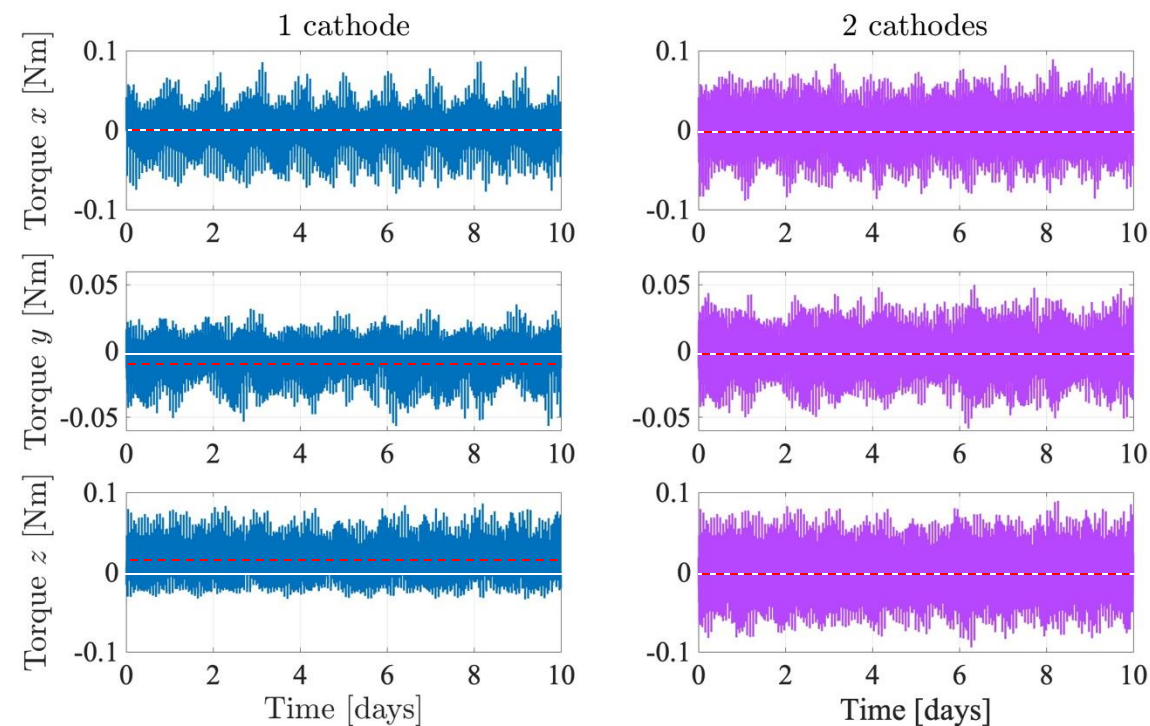
1 cathode



2 cathodes



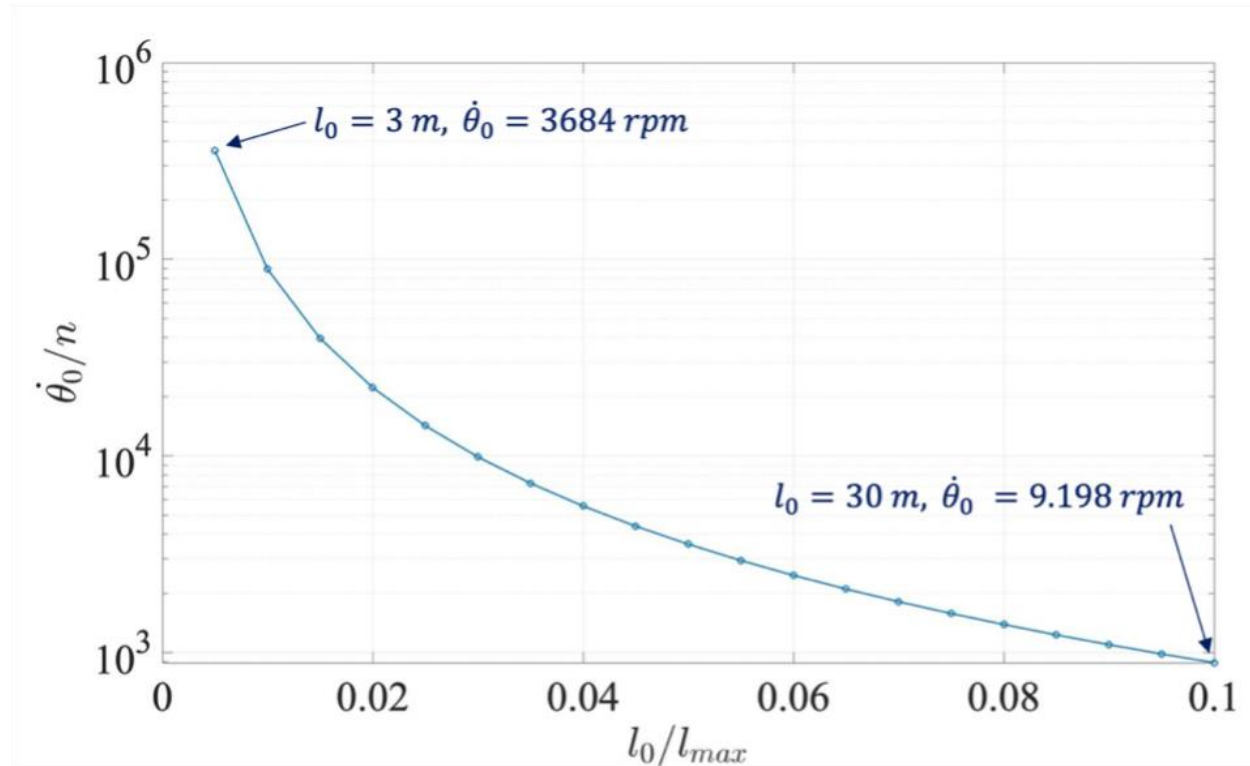
Torques associated to the Lorentz force





Deployment and Spin-up strategies

- Angular momentum conservation
- Deployment and Spin-up in plane + Precession



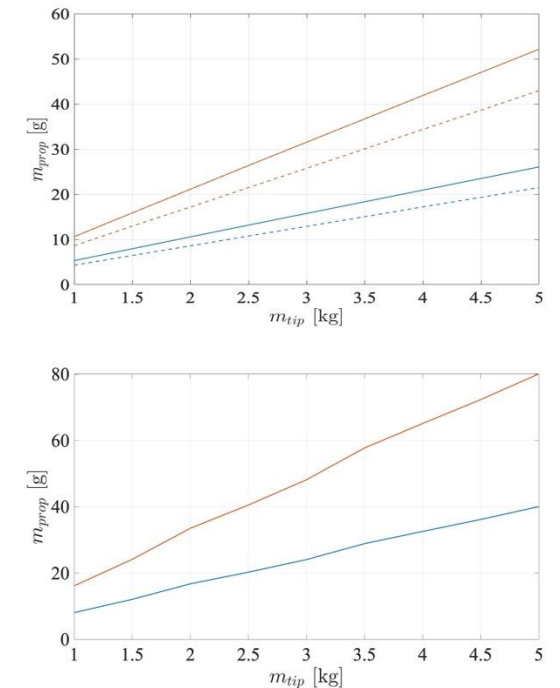
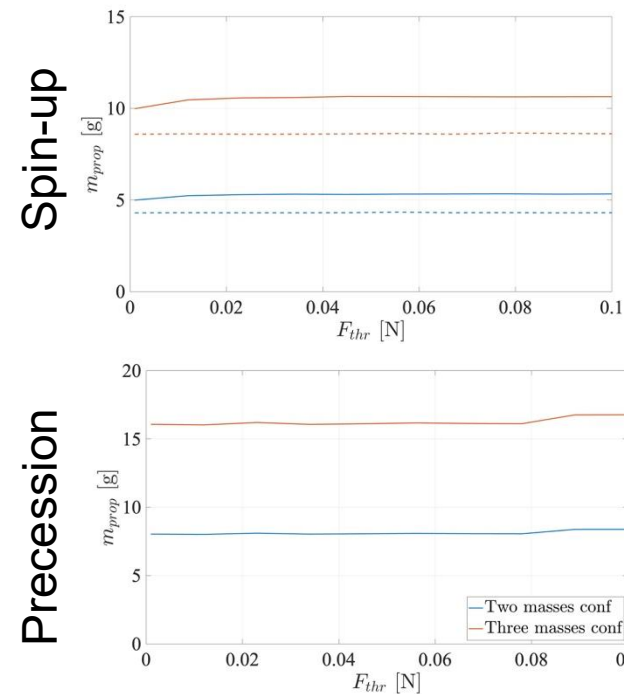
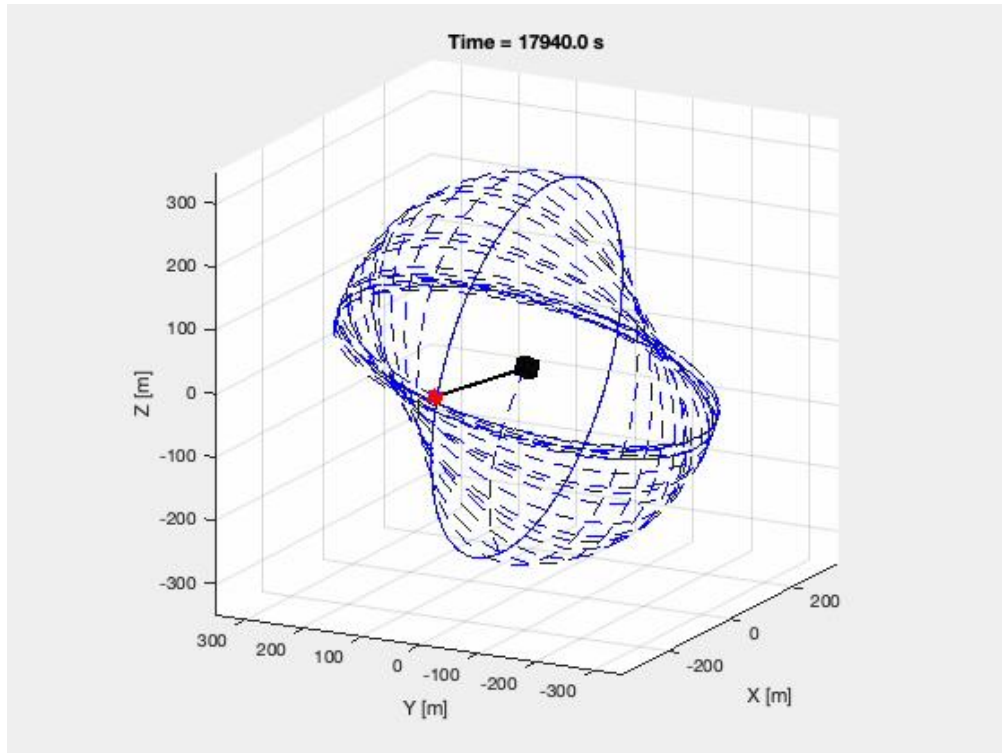
Desired final conditions

- $l = 300 \text{ m}$
- $\dot{\theta} = 8 \text{ rpo}$ (rev per orbit)



Deployment and Spin-up strategies

- Angular momentum conservation
- Deployment and Spin-up in plane + Precession





Artificial Gravity

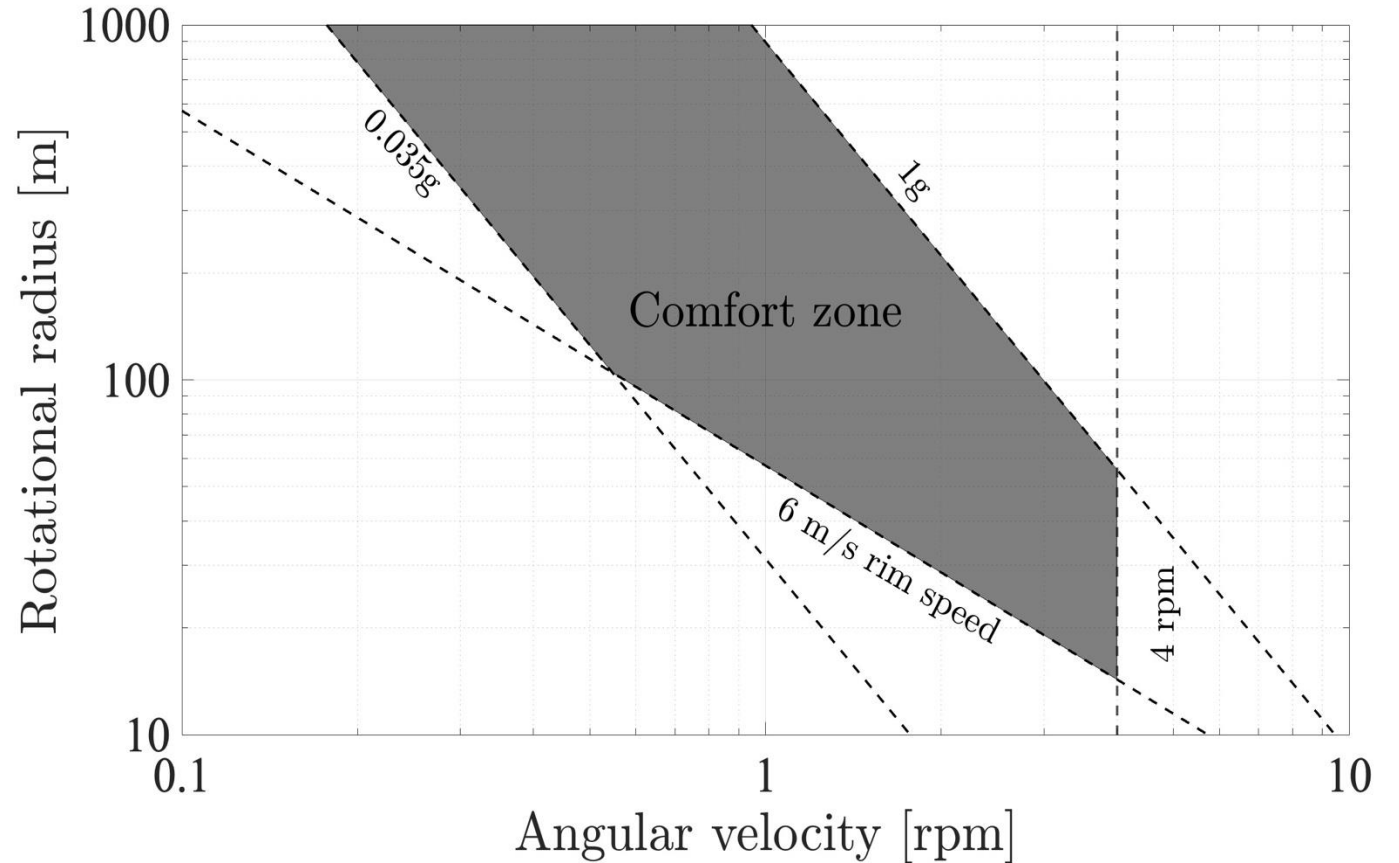


Centrifugal acceleration

$$a_{cent} = r\omega_{spin}^2$$

Short tether
Fast spin

Long tether
Slow spin



Theodore Hall, *Artificial Gravity Visualization, Empathy, and Design*, In Space 2006. DOI: 10.2514/6.2006-7321.



Mission concept

Orbit:

LEO → altitude ~600 km
Dawn-dusk sun-synchronous
(*incl* = 97.8°)

Spin rate:

1-4 rpm (comfort zone)

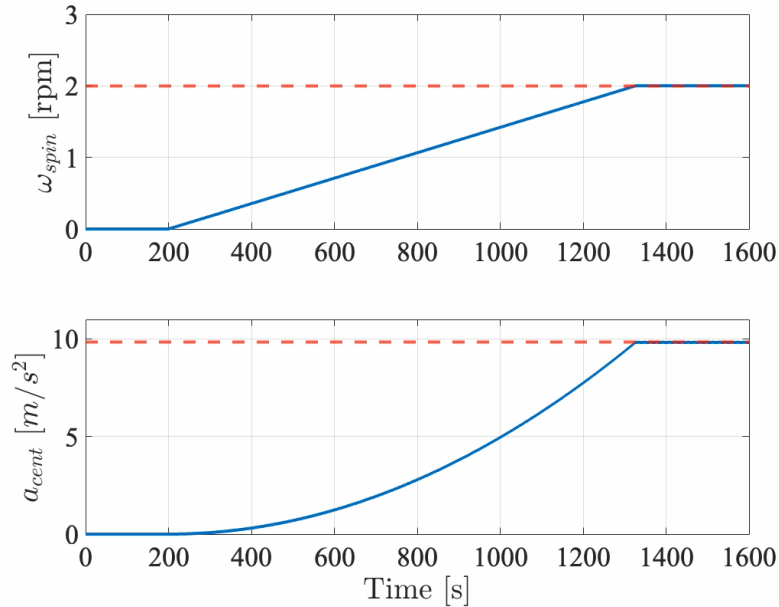
Artificial gravity level:

Earth-g
Mars-g

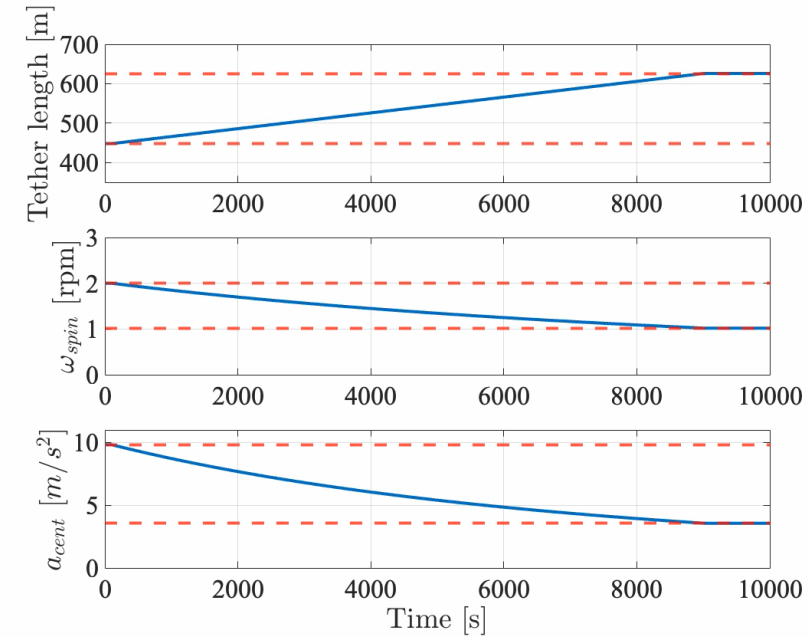
System:

Two 12 U cubesats (24 kg each)

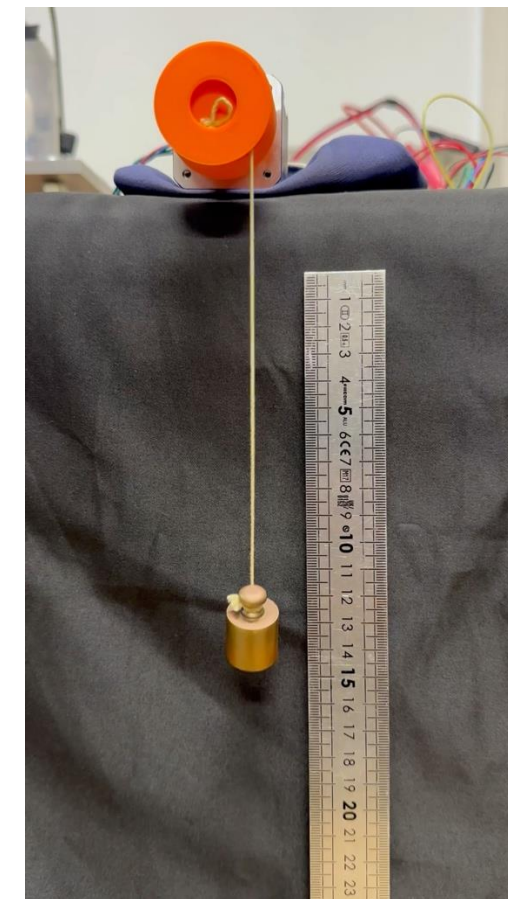
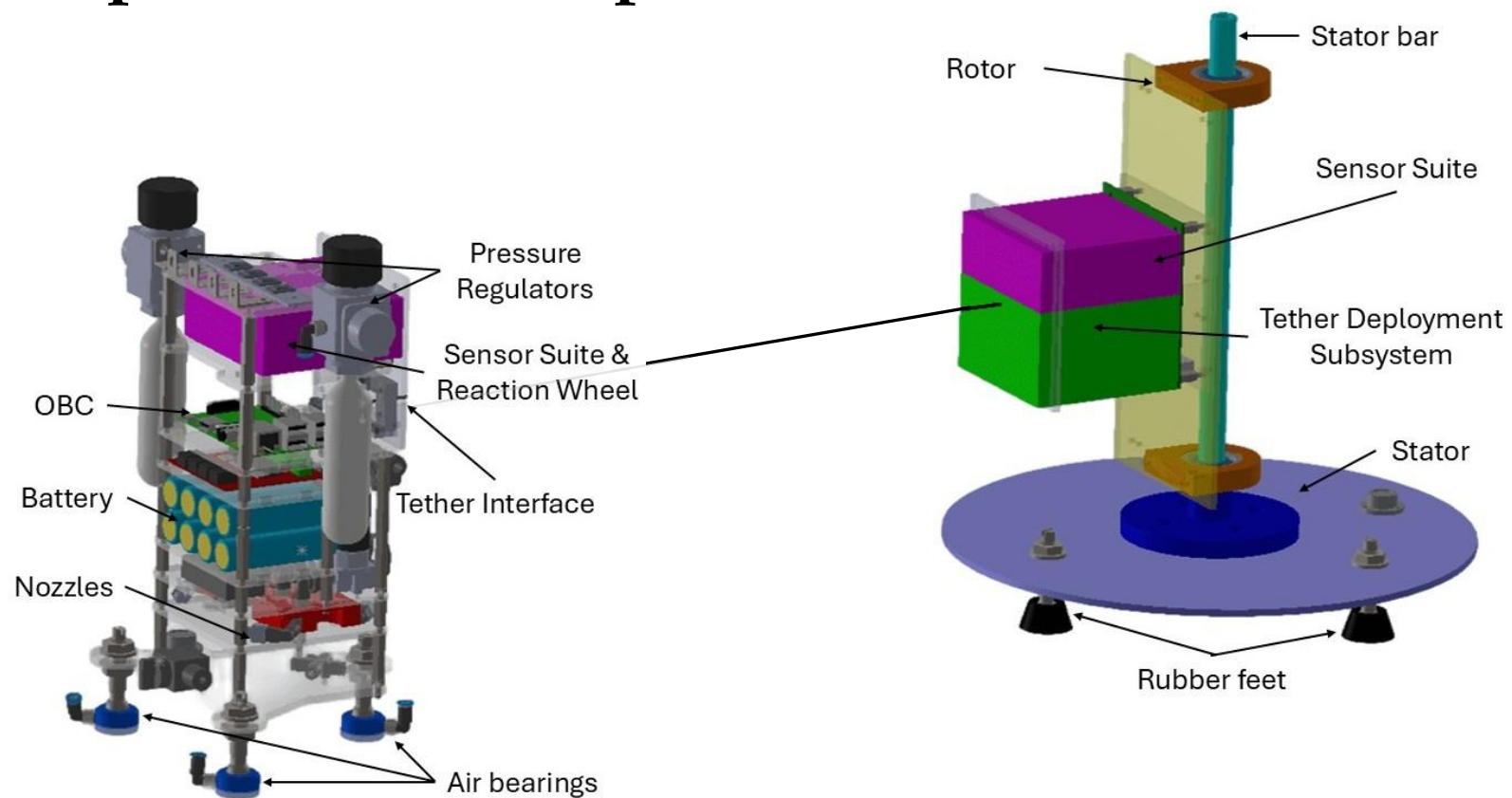
Spin-up



Reel-out



Experimental setup



Deployment mechanism



- **EDTs**

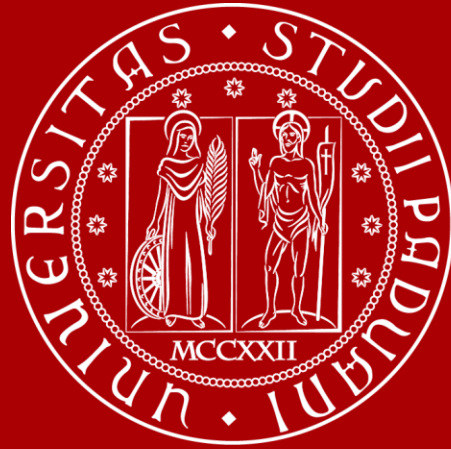
- Continue with the E.T.COMPACT project

- **Artificial Gravity**

- Optimization of the interplanetary correction maneuvers for spinning systems

- **METs**

- Investigate their potentials
- Develop a simulation tool
- Evaluate possible applications



UNIVERSITÀ
DEGLI STUDI
DI PADOVA

THANK YOU FOR THE ATTENTION!

Anese Giovanni
giovanni.anese@phd.unipd.it