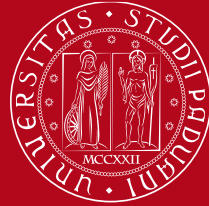


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# Application of autonomous On Orbit Assembly to On Orbit Servicing and Active debris Removal Missions

Federico Basana - 37<sup>th</sup> Cycle

Supervisor: Dr. Francesco Branz

Meeting - 27/10/2021

- On Orbit Activities overview
- Doctoral work objectives
- Research activities
- Work organization

## On Orbit Servicing (OOS)

Non-contact support

Orbit maintenance or modification

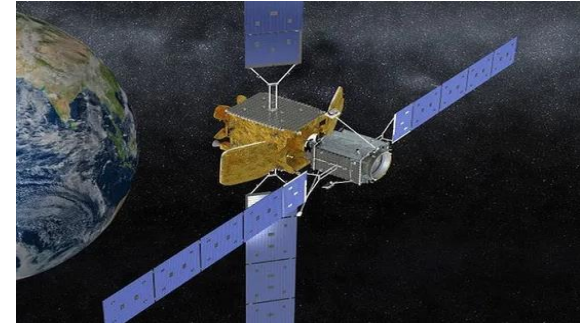
Repair, assembly

Refuelling and commodities replenishment

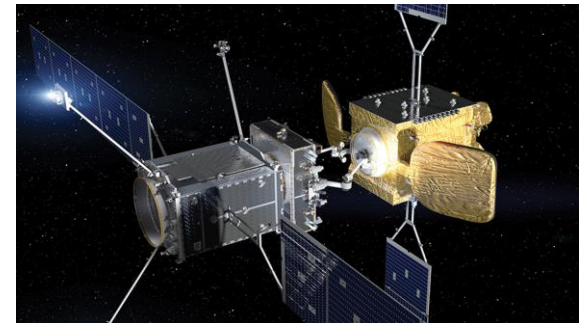
Active Debris Removal



## MEV-1



## Orbital Express - DARPA



## Micro/nano satellites

Micro: mass between 10 – 100 kg  
Nano: mass between 1 – 10 kg (CubeSat)

## On Orbit Assembly

Assembly of large structures in space



## AAReST mission



## Can OOA be applied to OOS/ADR missions?

### Possible advantages:

- High versatility
- Failure resistant
- Cheap technology

### Challenges:

- Not fully developed technology
- Assembly phase
- Close Proximity Operations (CPOs)

## Analysis of OOS/ADR missions employing OOA of micro/nano satellites

An OOS/ADR mission which serves multiple targets will be studied. In the mission the OOA of micro/nano satellites will be employed to service the targets.

## Definition of new strategies for autonomous OOA of micro/nano satellites

Starting from the development of CubeSat sized modules, the assembly architecture will be defined and innovative solutions for autonomous OOA of micro/nano satellites will be investigated and simulated.

## Study of the target capture phase with an assembly

The assembly resulting from the OOA operations will be studied during the capture phase of different targets. Close Proximity Operations will be studied (i.e. from the assembly release to the capture of the target)

## Validation of numerical simulations through experimental activities

## Mission Analysis

- ❖ Multiple targets service mission definition
- ❖ Multiple targets service mission simulation

## Autonomous OOA of micro/nano satellites

- ❖ Definition of new strategies for autonomous OOA of micro/nano satellites
- ❖ Development of modules of the assembly
- ❖ Facility development
- ❖ Validation tests campaign

## Target Capture Phase

- ❖ Close Proximity Operations (CPOs) with robotic arm simulation
- ❖ Assembly Close Proximity Operations (CPOs) study
- ❖ Robotic Arm vs. Assembly comparison
- ❖ Assembly Close Proximity Operations tests

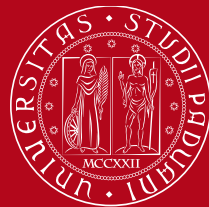


<b>PHD STUDENT</b>	Federico Basana	<b>DATE</b>	22/10/2021
<b>PHD THESIS</b>	Application of autonomous On Orbit Assembly to On Orbit Servicing and Active Debris Removal Missions	<b>ADMISSION TO</b>	First Year

WBS NUMBER	TASK TITLE	% OF TASK COMPLETE	FIRST YEAR				SECOND YEAR				THIRD YEAR								
			T1	T2	T3	T4	T1	T2	T3	T4	T1	T2	T3	T4					
			O N D	J F M	A M J	J A S	O N D	J F M	A M J	J A S	O N D	J F M	A M J	J A S					
1	Mission Analysis																		
1.1	Multiple targets service mission definition	0%	█	█	█	█	█												
1.2	Multiple targets service mission simulation	0%		█	█	█	█												
2	Autonomous OOA of micro/nano satellites																		
2.1	Definition of new strategies for autonomous OOA of micro/nano satellites	0%		█	█	█	█	█	█	█	█	█							
2.2	Development of modules of the assembly	0%		█	█	█	█	█	█	█	█	█							
2.3	Facility development	0%	█	█	█	█	█	█	█	█	█	█							
2.4	Validation test campaign	0%		█	█	█	█			█	█	█	█	█	█				
3	Target capture phase																		
3.1	Close Proximity Operations (CPOs) with robotic arm simulation	0%	█	█	█	█	█			█	█	█							
3.2	Assembly Close Proximity Operations (CPOs) study	0%		█	█	█	█	█	█	█	█	█							
3.3	Robotic Arm vs. Assembly comparison	0%		█	█	█	█			█	█	█							
3.4	Assembly Close Proximity Operations test	0%		█	█	█	█			█	█	█	█	█	█				
4	Writing PhD thesis and reports																		
4.1	Writing reports	0%	█	█	█	█	█	█	█	█	█	█	█	█	█				
4.2	Article redaction	0%	█	█	█	█	█												
4.3	Writing PhD thesis	0%		█	█	█	█	█	█	█	█	█	█	█	█	█	█	█	█

# Thanks for the attention

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