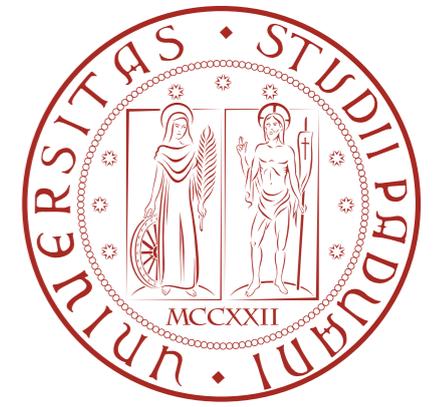




Università degli Studi di Padova
Centro di Ateneo di Studi e Attività Spaziali "Giuseppe Colombo"



PhD XXXIII cycle
Event: Request of admission to the third year of the PhD course

A novel numerical method for fluid-structure interaction problems

PhD student: Federico Dalla Barba

Supervisor: Prof. Francesco Picano

Co-supervisor: Prof. Mirco Zaccariotto

MOTIVATIONS

FLUID STRUCTURE INTERACTION (FSI) PROBLEMS

- Interaction among a fluid flow and rigid or deformable solid structures:
 - Force exchange across sharp and complex interfaces**
 - Time-evolving interfaces**
 - Solid and fluid dynamics is governed by different constitutive laws**



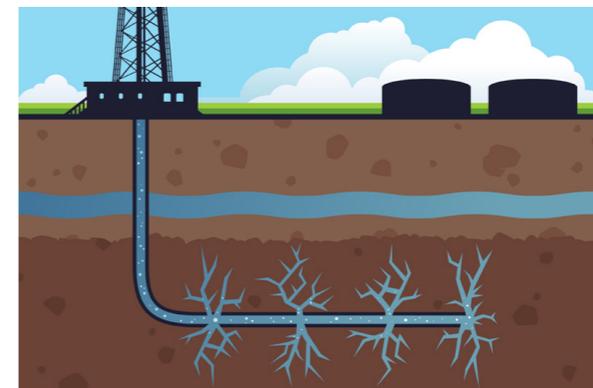
Complex dynamics, multi-physics, strong nonlinearity

FSI is a key problem in aerospace engineering:

- Liquid sloshing in fuel tanks
- Acoustic induced vibration
- Aeroelastic flutter of wings

Additional complexity when solid fracture occurs within a fluid flow:

- Hydraulic fracture**



To date, a satisfactory numerical and theoretical description of FSI problems with hydraulic fracture remains a challenge and the capabilities of existing models for applications are still limited

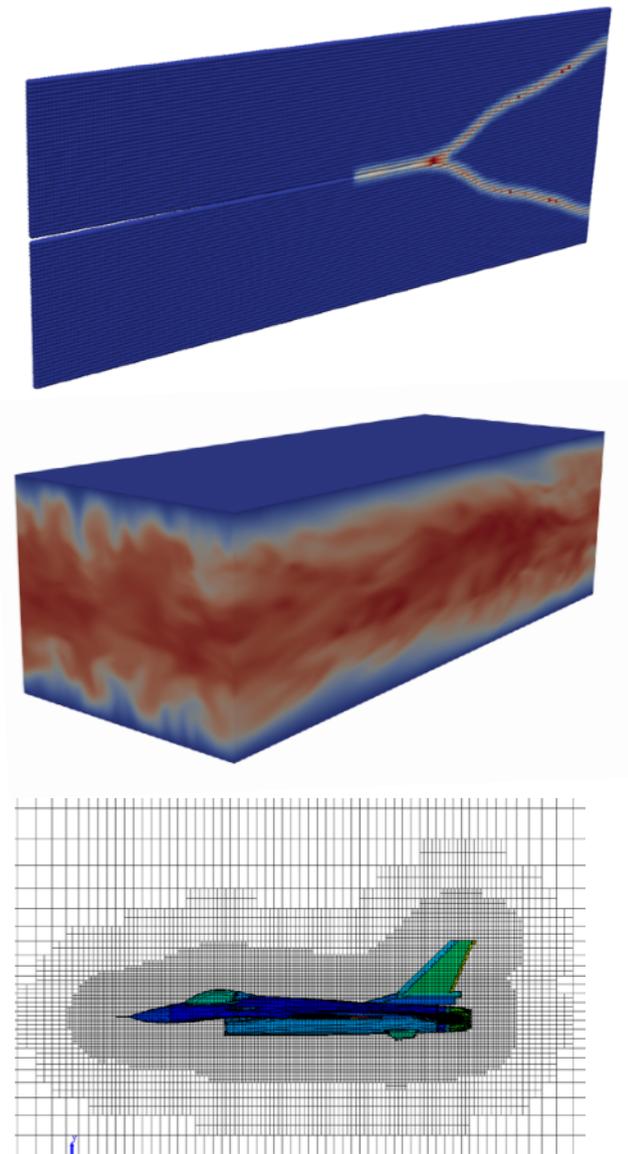
OBJECTIVES AND METHODOLOGY

- **OBJECTIVES:**

- **DEVELOPMENT OF A NUMERICAL TOOL CAPABLE TO REPRODUCE THE PHYSICS OF GENERIC FSI PROBLEMS ACCOUNTING FOR SOLID FRACTURE**
- **INVESTIGATION OF FSI WITH SOLID FRACTURE**

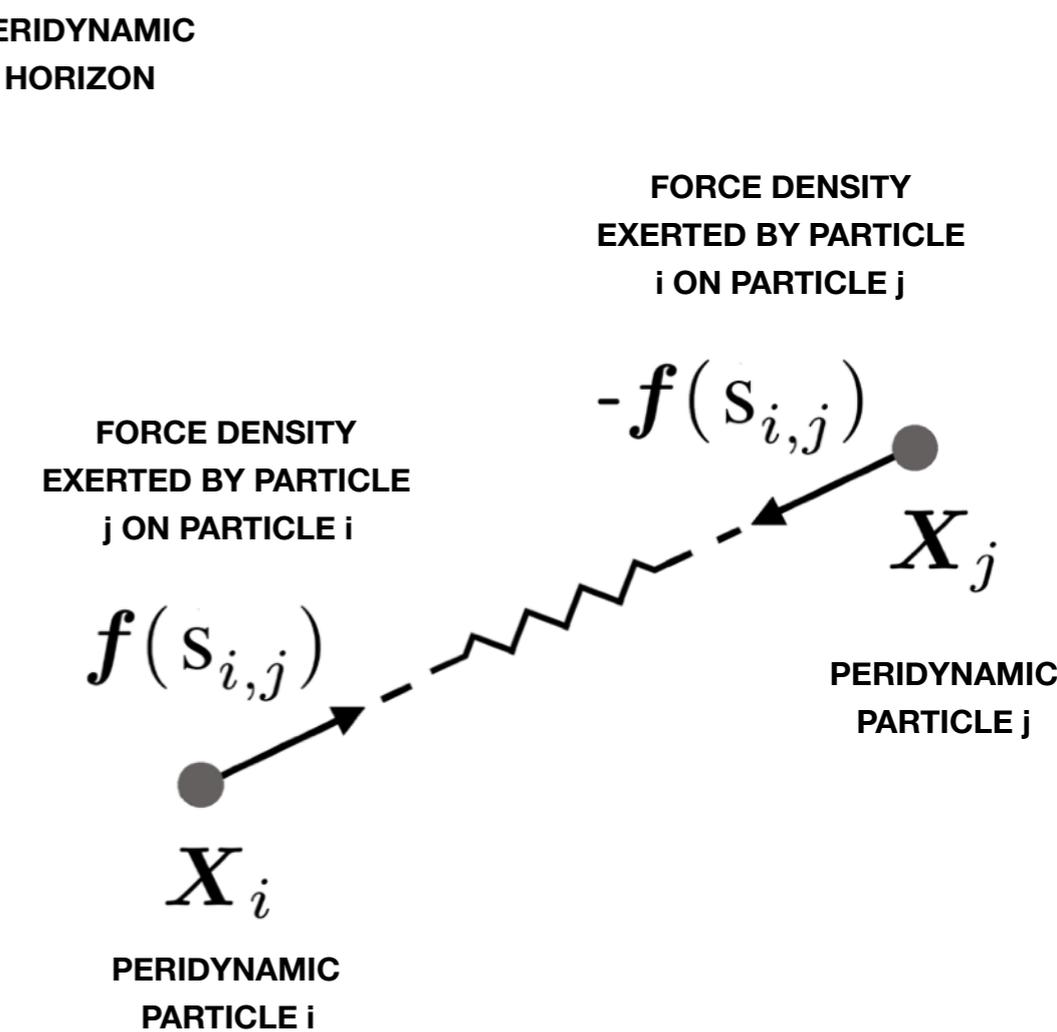
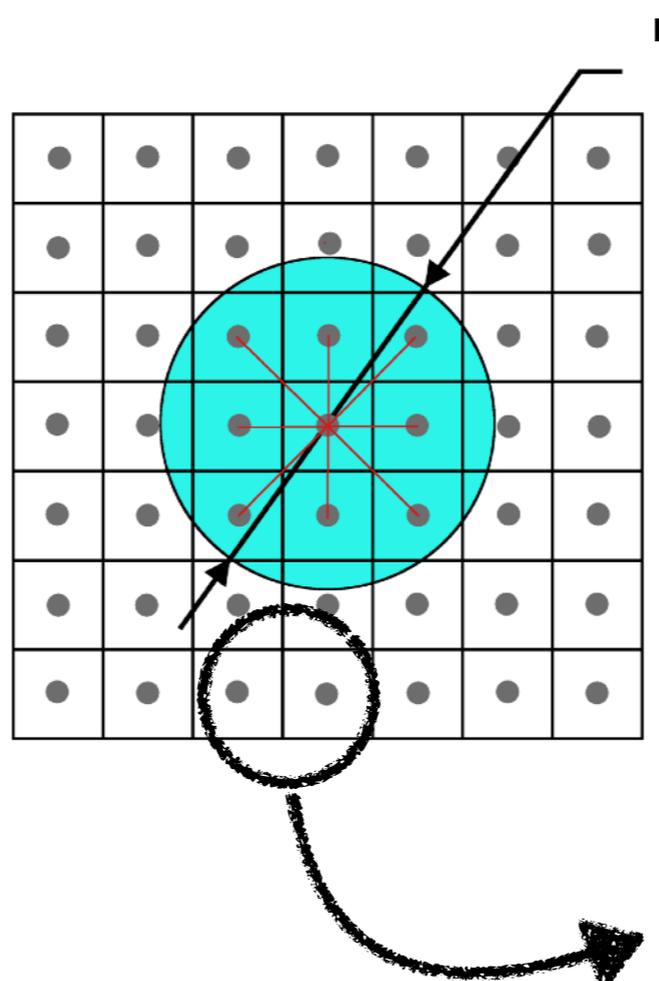
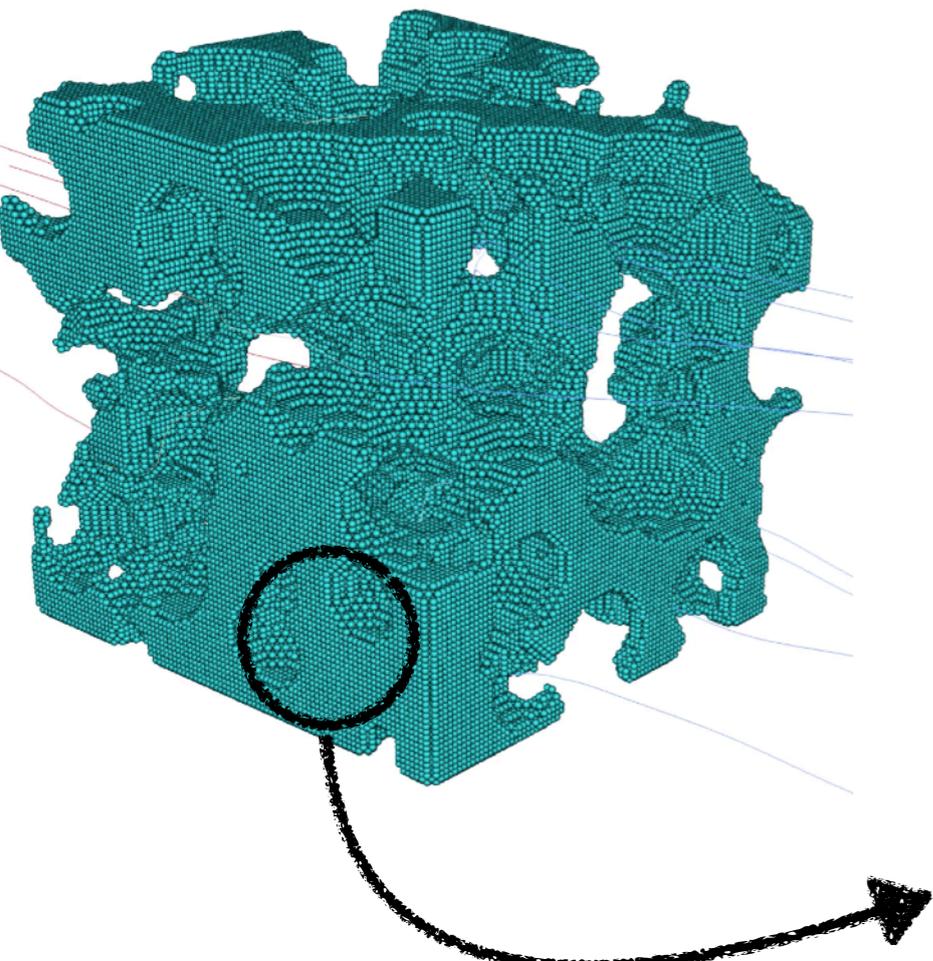
- **METHODOLOGY:**

- **PERIDYNAMICS (PD):** 
 - Crack detection/branching and solid fracture prediction capabilities
- **NAVIER STOKES EQUATIONS (NS)** 
 - Prediction of fluid flow dynamics
- **IMMERSED BOUNDARY METHOD (IBM)** 
 - Coupling and force exchange across complex interfaces



DISCRETE BOND-BASED PERIDYNAMICS: BASIC CONCEPTS

- Peridynamics is a formulation of continuum mechanics based on non-local integral equations:
 - A discretized peridynamic solid is represented by a **set of finite size material particles**
 - Material **particles mutually interact via micro-elastic potentials** that generate bond forces
 - **Interactions (bonds) vanish beyond a threshold distance, the peridynamic horizon, δ**

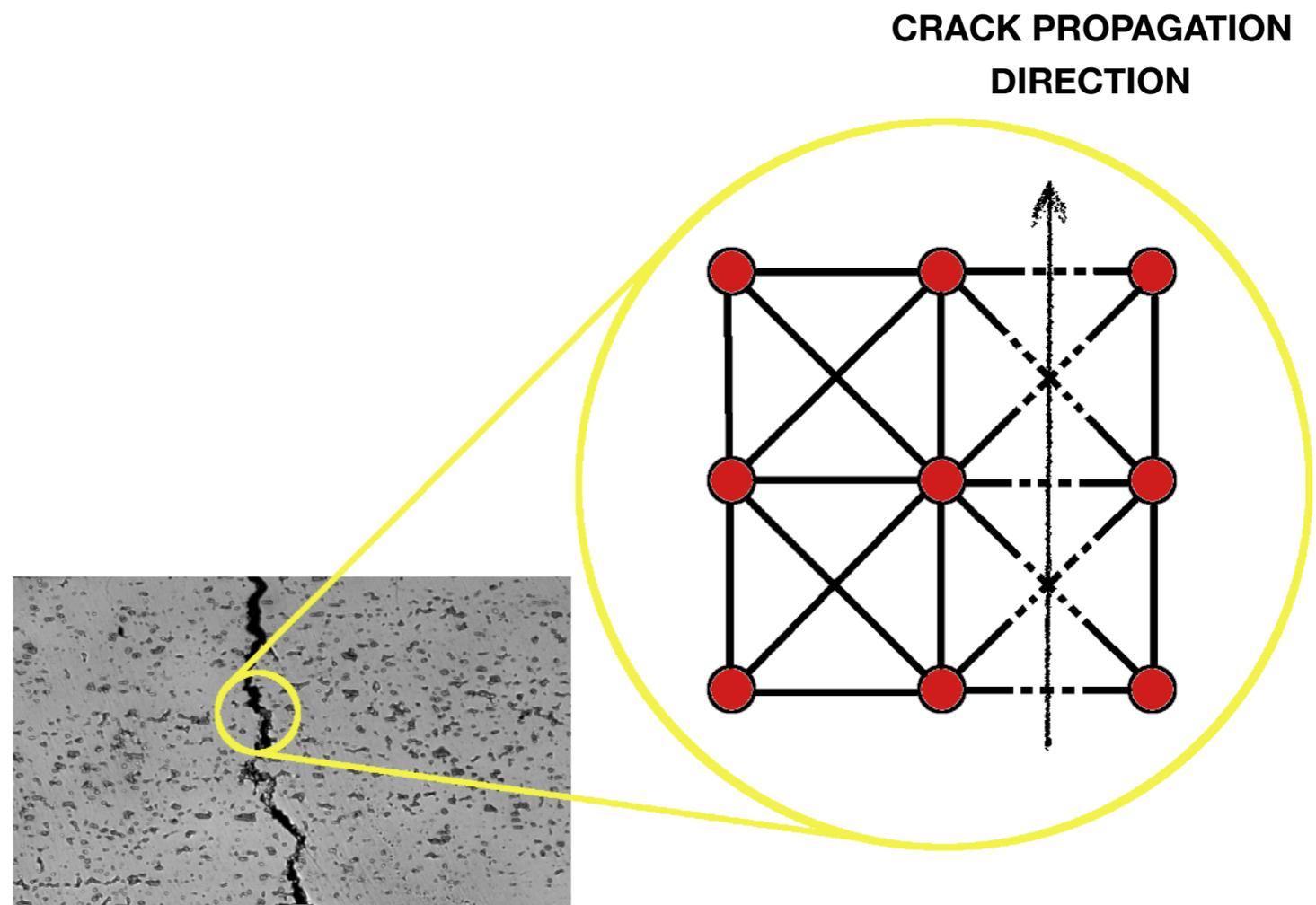
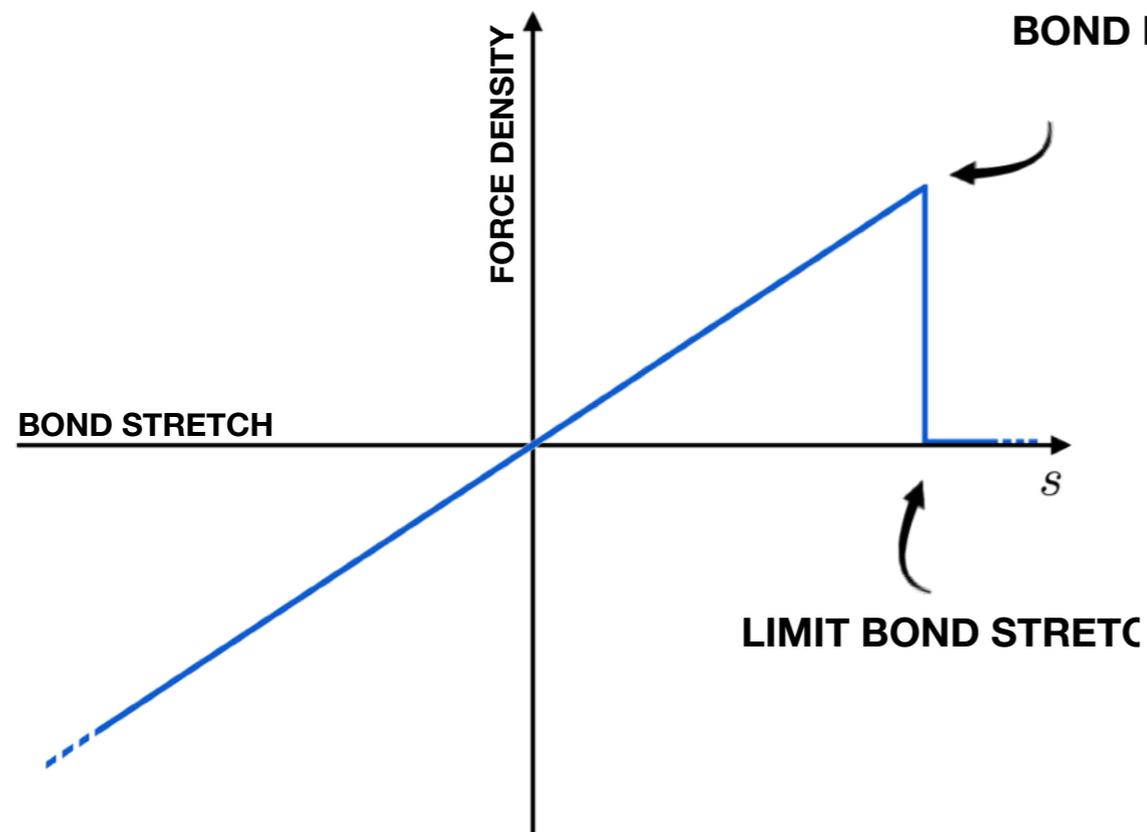


Silling S.A., Epton M., Weckner O., Xu J. & Askari E. *Peridynamic states and constitutive modeling*. Journal of Elasticity (2007).

Silling S.A. *Reformulation of elasticity theory for discontinuities and long-range forces*. Journal of Mechanics and Physics of Solids (2000).

DISCRETE BOND-BASED PERIDYNAMICS: MATERIAL DAMAGE DETECTION

- Automatic crack detection and crack branching:
 - A bond breaks when its stretch overcomes a threshold value, the limit bond stretch s_0
 - The limit bond stretch, s_0 , is a function of a macroscopic property of the material, the energy release rate, G
 - Bond breakage is permanent



Silling S.A., Epton M., Weckner O., Xu J. & Askari E. *Peridynamic states and constitutive modeling*. Journal of Elasticity (2007).

Silling S.A. *Reformulation of elasticity theory for discontinuities and long-range forces*. Journal of Mechanics and Physics of Solids (2000).

NAVIER STOKES EQUATIONS AND IBM

- Liquid phase governed by **incompressible formulation of NS equations**.
- **Fixed Eulerian grid and moving Lagrangian grid** on liquid-solid interface.
- Force exchange accounted for via **Immersed Boundary Method (IBM)**.

$$\nabla \cdot \mathbf{u} = 0$$

$$\rho_f \left(\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) = -\nabla p + \mu_f \nabla^2 \mathbf{u} + \rho_f \mathbf{f}$$

IBM FORCING ON THE LIQUID PHASE

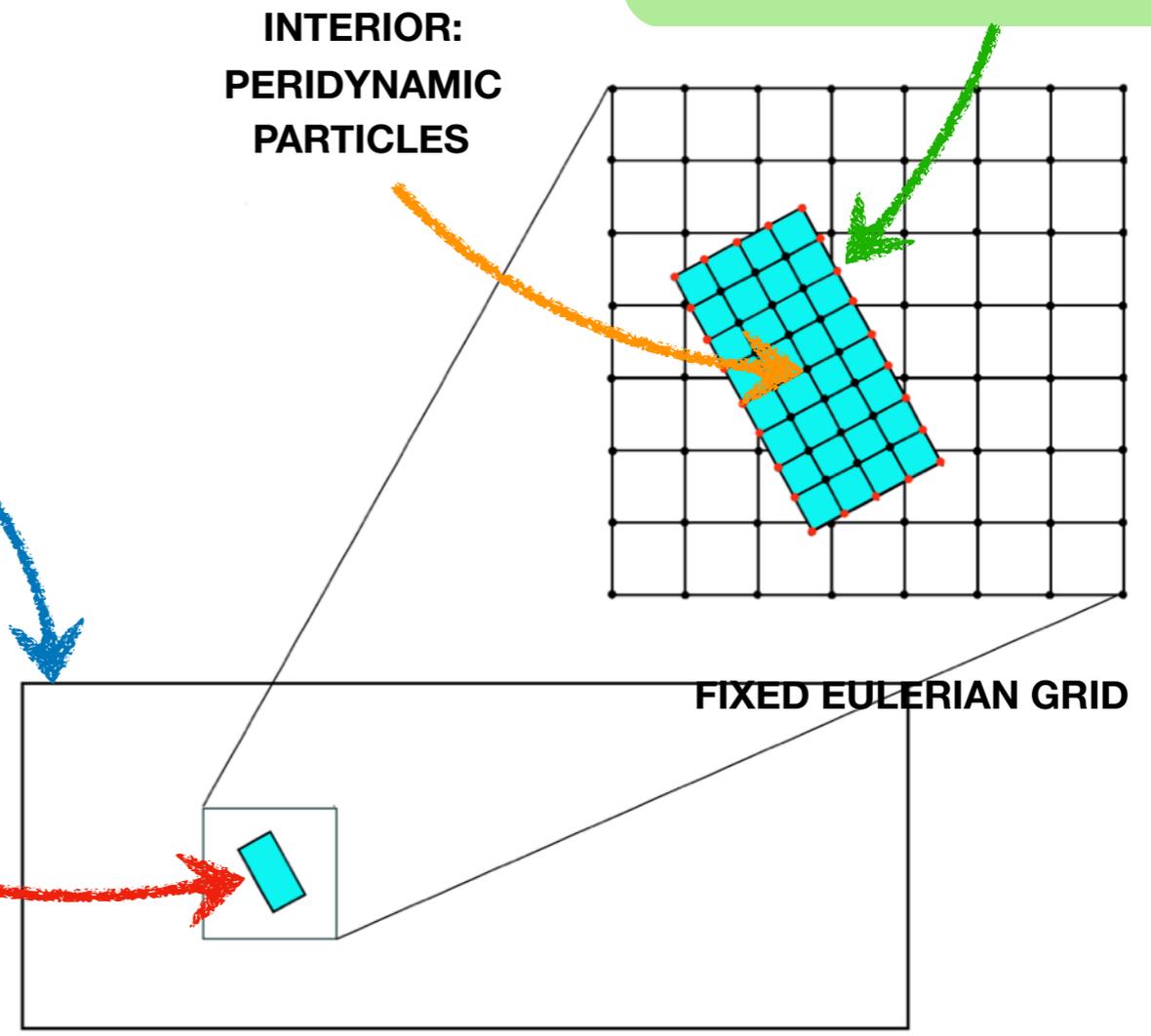
BCs are directly imposed by means of ghost nodes at the limit boundaries of the computational domain

PROBLEM: We have to impose no-slip and no-penetration boundary conditions for the fluid on the solid-liquid interface, but grid nodes do not coincide with the interface!

IBM: a distributed force is used to impose BCs at the liquid-solid interfaces.

- IBM advantages:
 - Eulerian and Lagrangian grids are non conforming!
 - Force exchange across complex interfaces!

MOVING LAGRANGIAN GRID
≡
SURFACE PERIDYNAMIC PARTICLES

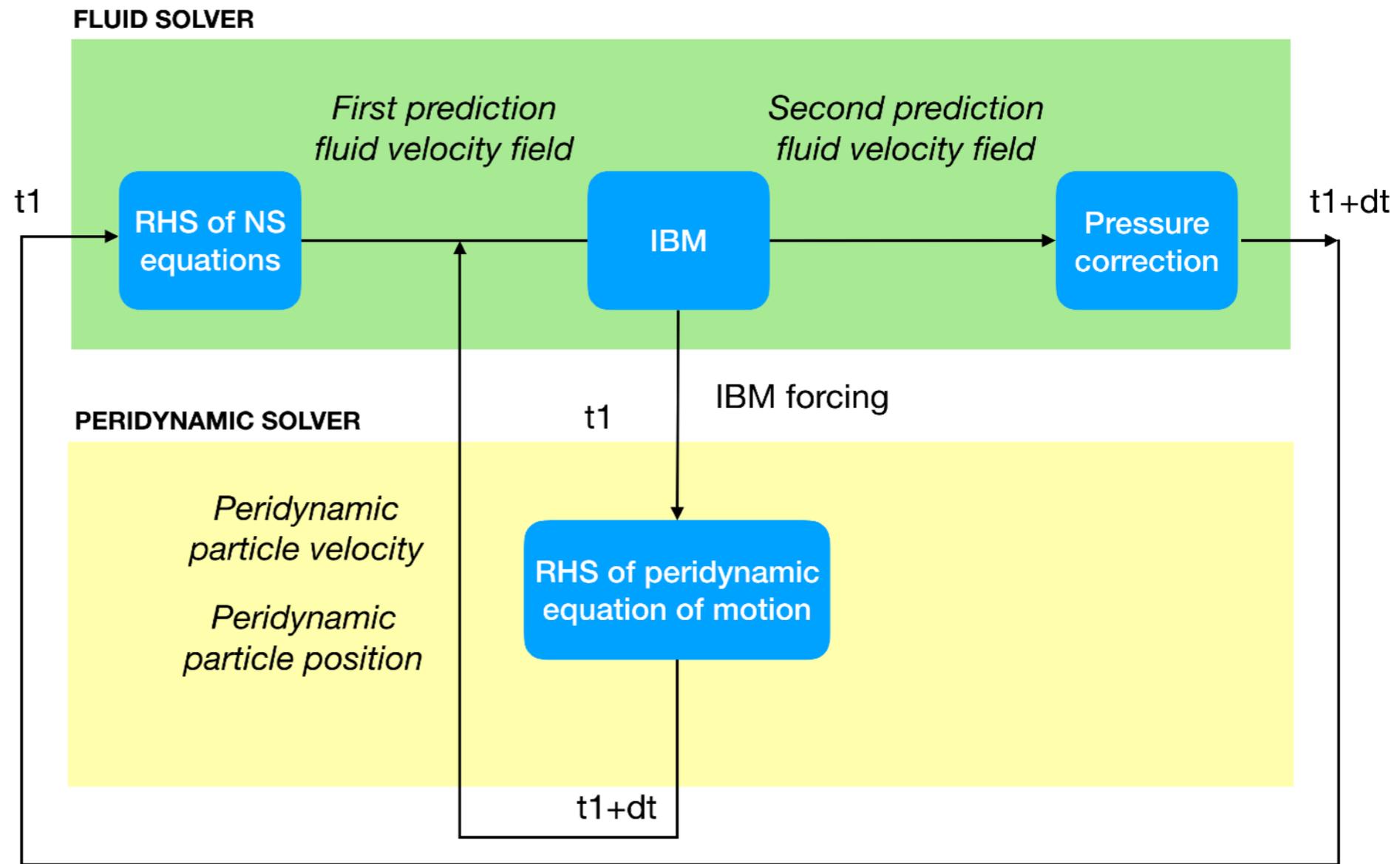
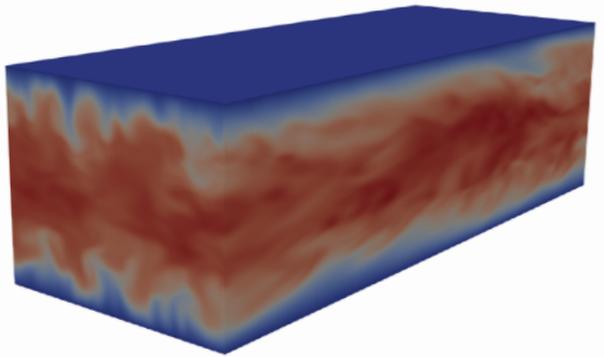


IMPLEMENTATION: AN OVERVIEW

- **FLUID SOLVER (CaNS by Pedro Costa):**
 - Pressure correction algorithm
 - Second order finite difference schemes for space discretization
 - Third order, low storage Runge-Kutta time marching algorithm

- **PERIDYNAMIC SOLVER:**
 - Fully explicit algorithm
 - Fictitious damping of relative motions to filter high frequency vibrations
 - Third order, low storage Runge-Kutta time marching algorithm

- **IBM:**
 - Multidirect forcing scheme (3 steps)



Costa P. A FFT-based finite-difference solver for massively-parallel direct numerical simulations of turbulent flows. arXiv preprint (2018).

IMPLEMENTATION: IBM

- **PROBLEM:** We have to impose boundary conditions on the solid-liquid interface:
 - **No-slip**
 - **No-penetration**
- We want to compute a fictitious force field to be applied to the fluid flow such that, near the interface, the fluid is forced to move with the same local velocity of the solid body
- Iterative procedure:

1) Interpolation of fluid velocity at the interface

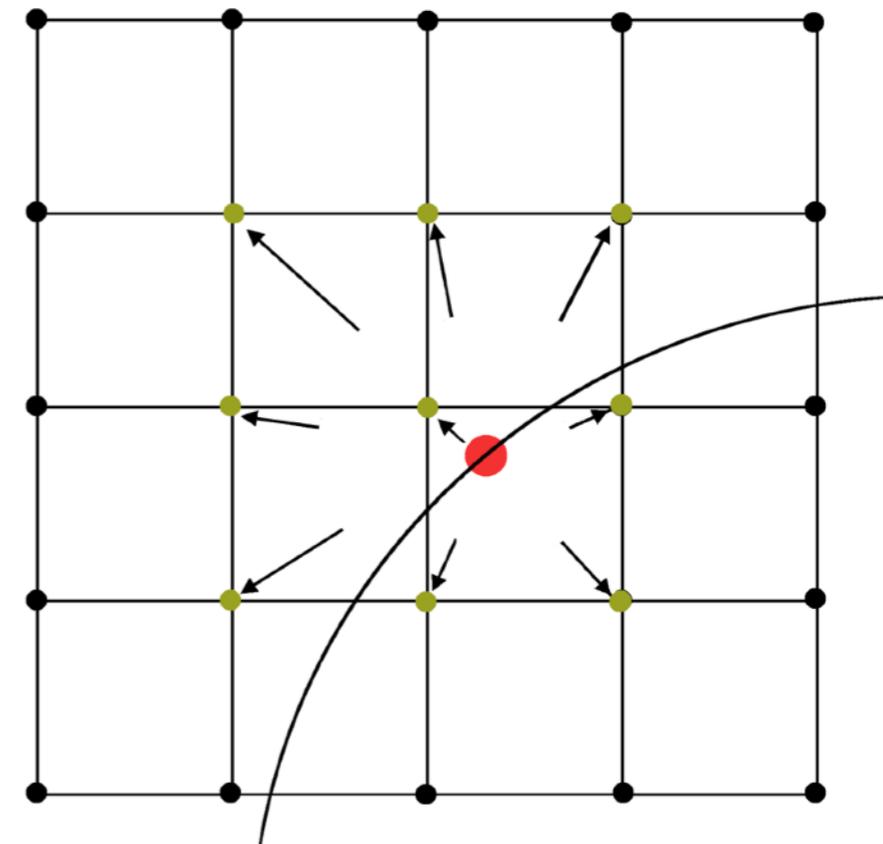
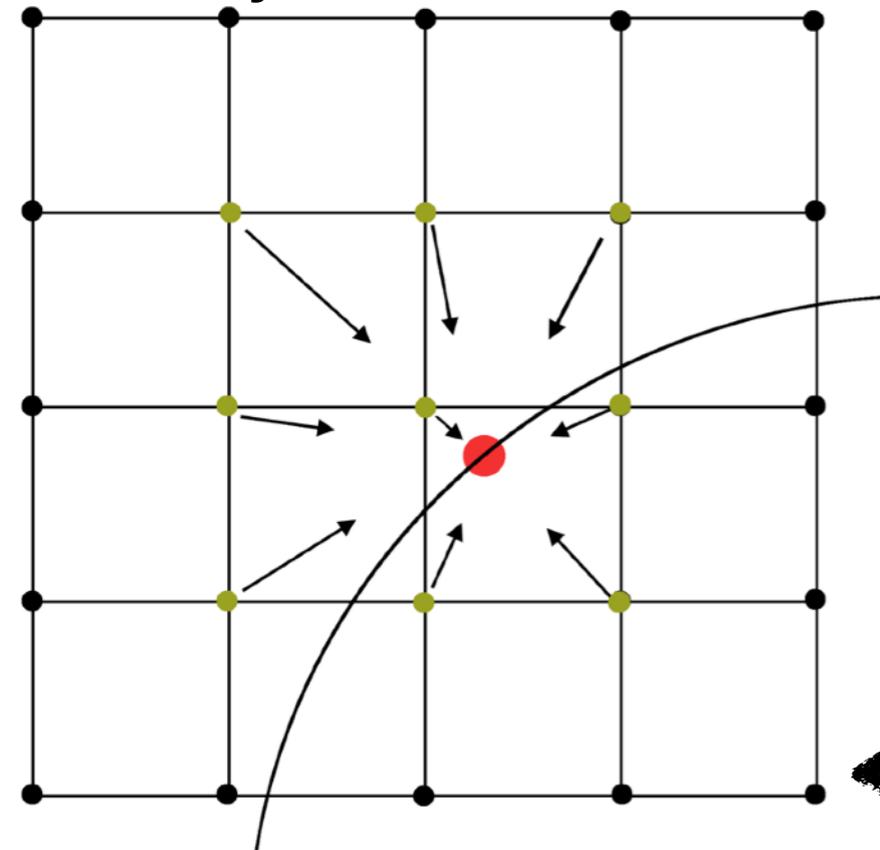


2) Computation of the IBM forcing term

$$F = \frac{U_l - U_s}{\Delta t}$$

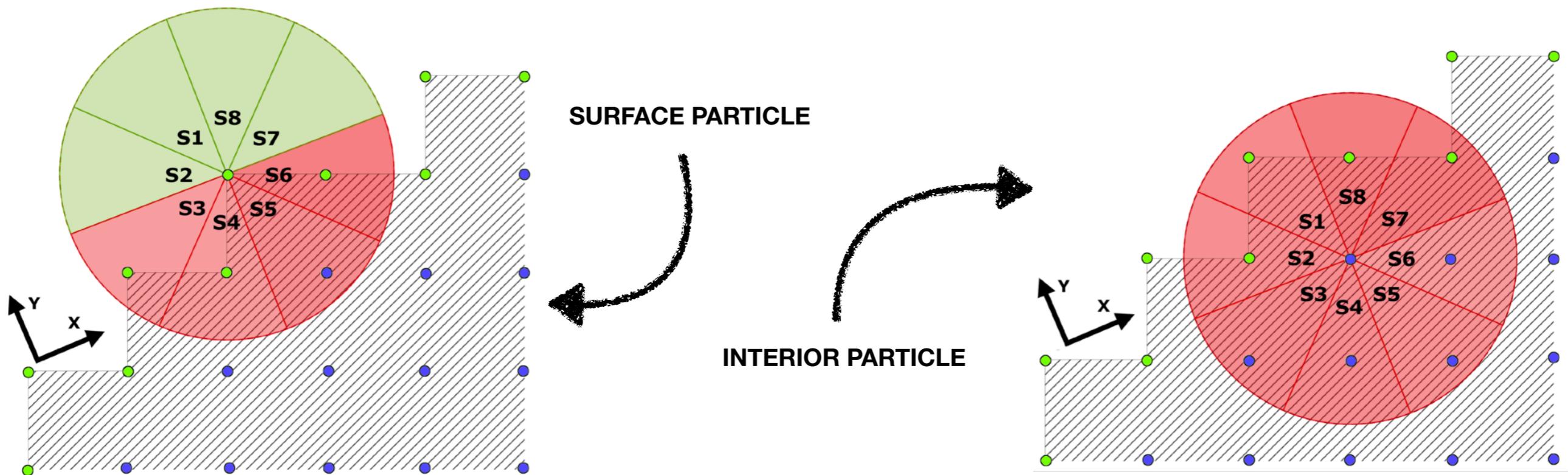


3) Spreading of the IBM forcing on the fluid grid



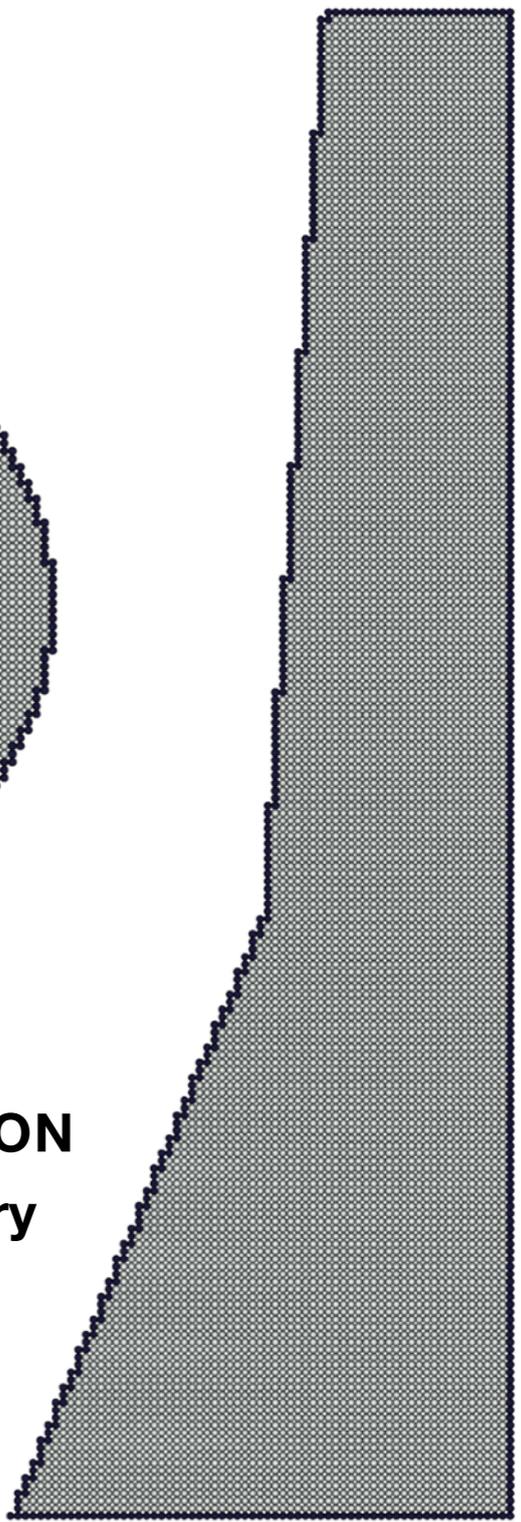
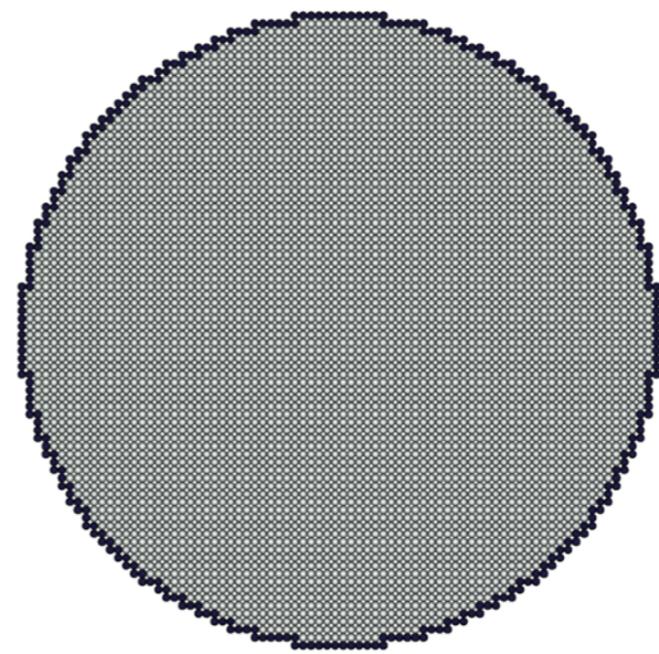
IMPLEMENTATION: SURFACE DETECTION ALGORITHM

- A 3D surface detection algorithm is used to check if a peridynamic particle is located on the liquid-solid interface or in the solid interior. The detection of surfaces is used to:
 - **Build the Lagrangian grid for the IBM algorithm**
 - **Compute normal and shear stresses exerted by the fluid on the surface of the solid body**
 - **Compute contact forces between solid bodies**
- Principle (2D case):
 - For each peridynamic particle, the surrounding space is divided in 8 circular sectors
 - Each particle in the horizon of the selected particle is associated with one of the sectors
 - **CRITERION: a particle is on the interface if 2 or more consecutive sectors are empty (90°)**

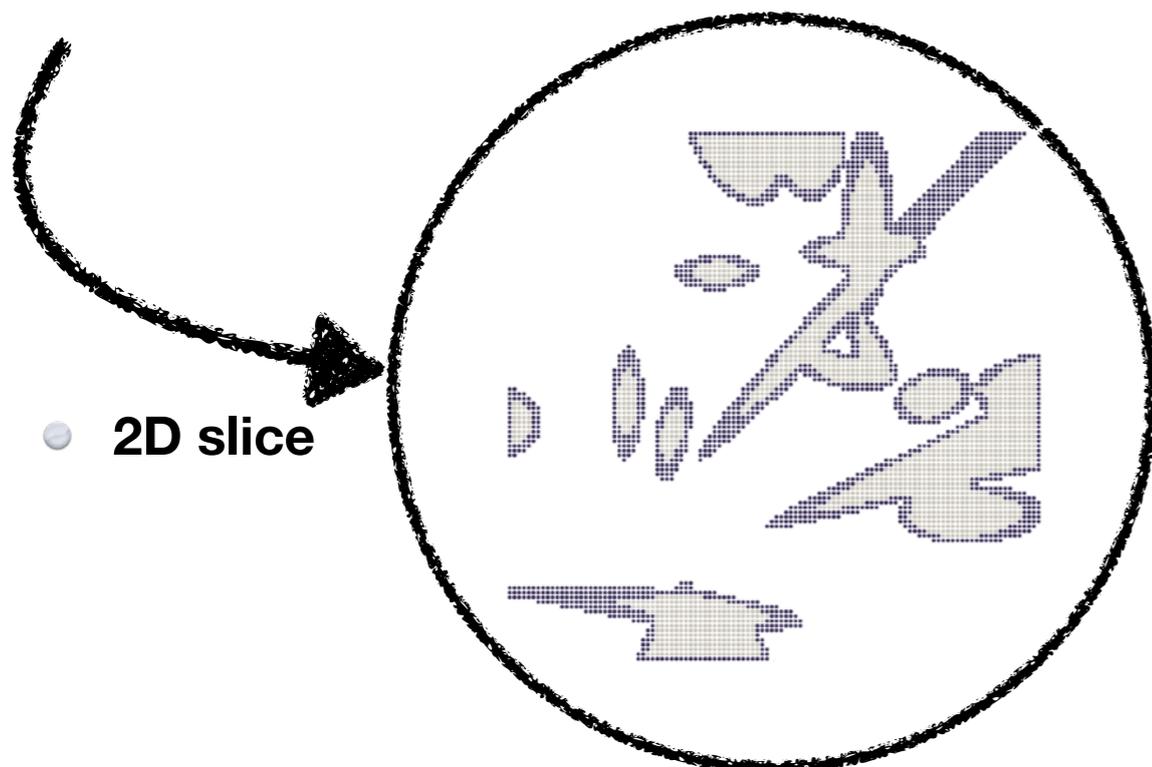


IMPLEMENTATION: SURFACE DETECTION ALGORITHM - EXAMPLES

- **SURFACE DETECTION TESTING: 3D set of cylindrical fibers with variable section**



- **SURFACE DETECTION TESTING : 2D geometry**

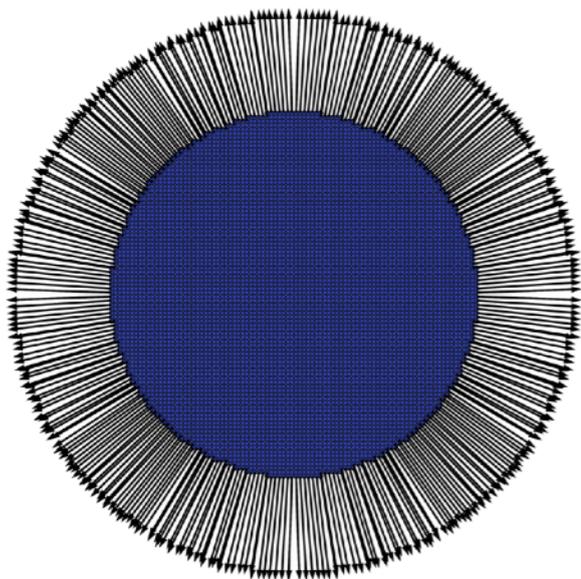
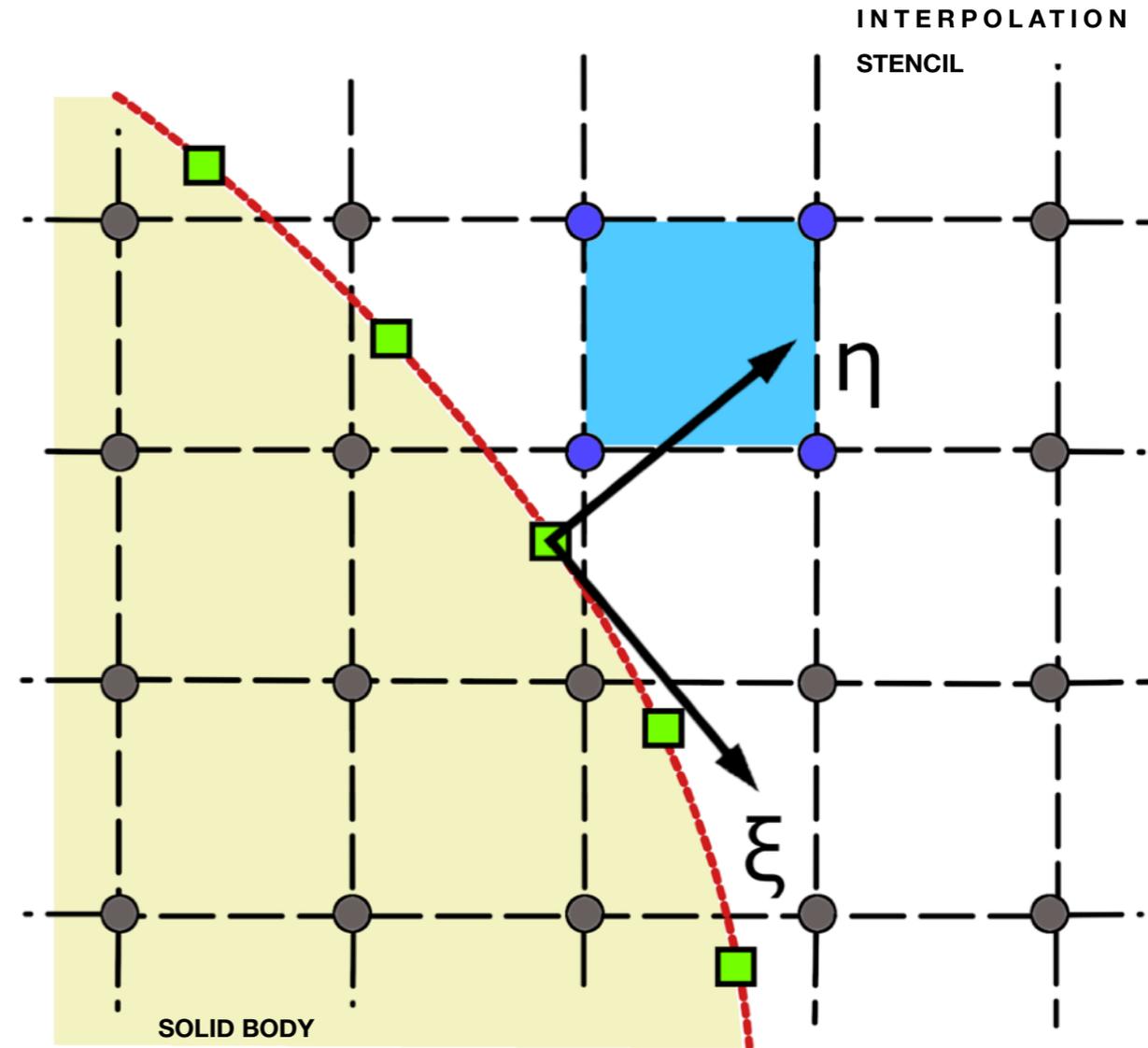


- **2D slice**

IMPLEMENTATION: COMPUTATION OF HYDRODYNAMIC FORCES

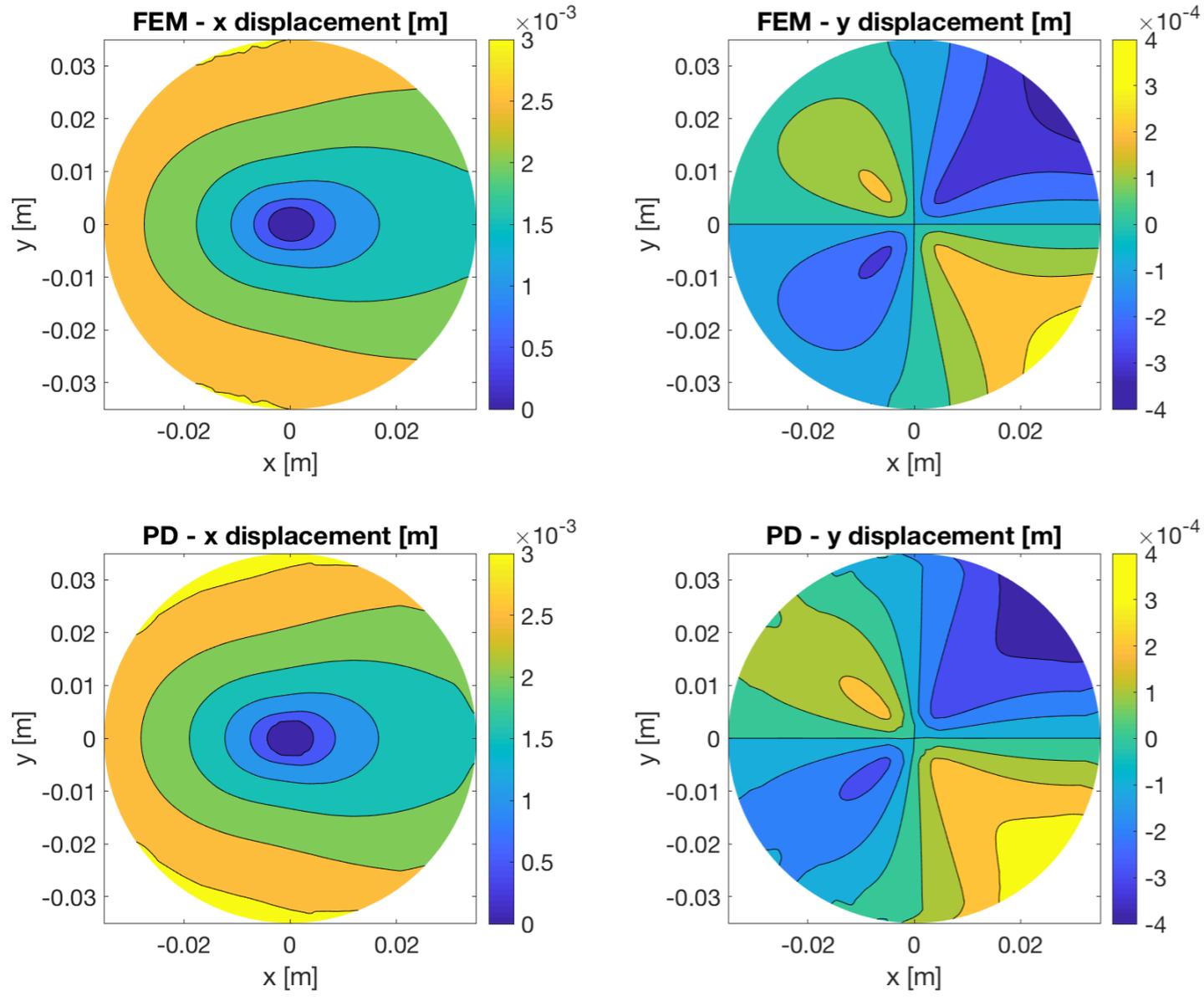
- In order to compute the force exerted by the liquid phase on the solid the normal probe method is used:

- Surface normal vector is computed for each peridynamic particle located on the interface
- Stress tensor is computed on the Eulerian grid
- **Stress tensor components are interpolated at the tip of each normal vector**
- Shear and normal stress on the surface are computed via the stress tensor and passed to the peridynamic solver
- Transformation between local (ξ, η) and global coordinate system (x, y) is needed.



- Surface normal vectors for a 2D cylinder

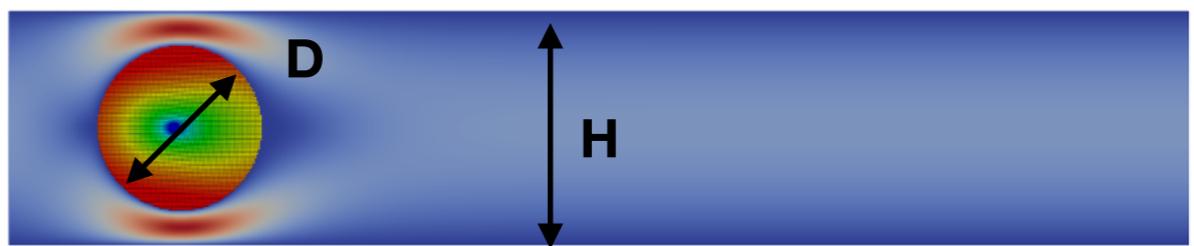
VALIDATION - COMPARATIVE TEST



Elastic cylinder in laminar channel flow:

- 2D laminar flow: $Re_B = 20$
- Inflow-outflow-wall BCs (Poiseuille flow prescribed at inflow)
- 7K Lagrangian points
- 640 x 128 grid nodes in flow and wall normal directions
- 6h x h x 0.2h computational domain in flow, wall normal and span-wise directions
- $D/H = 0.7$
- $E = 10^6$ Pa

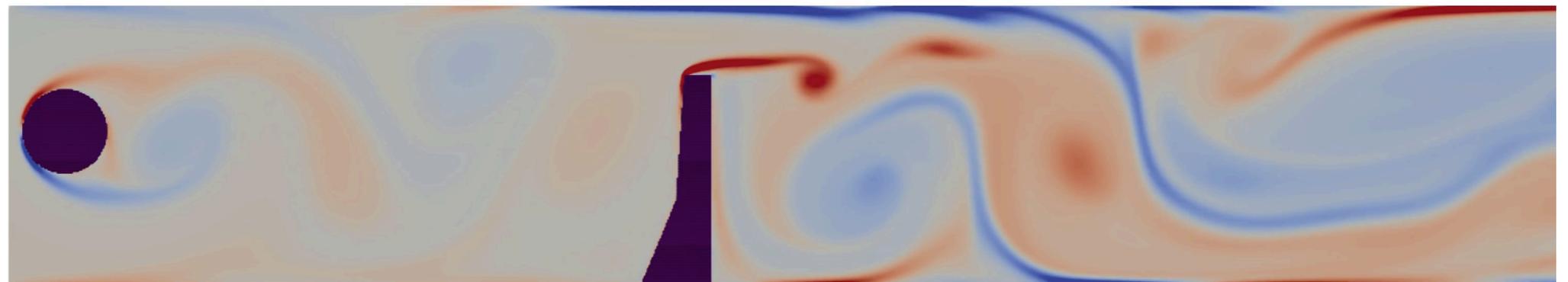
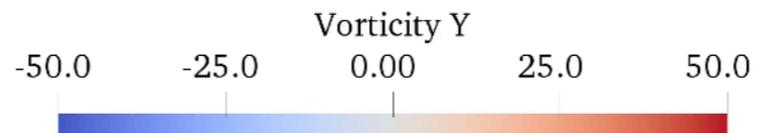
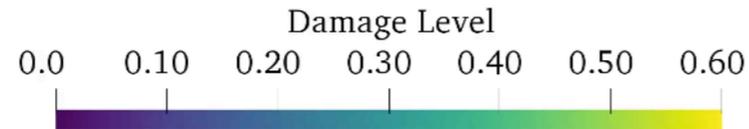
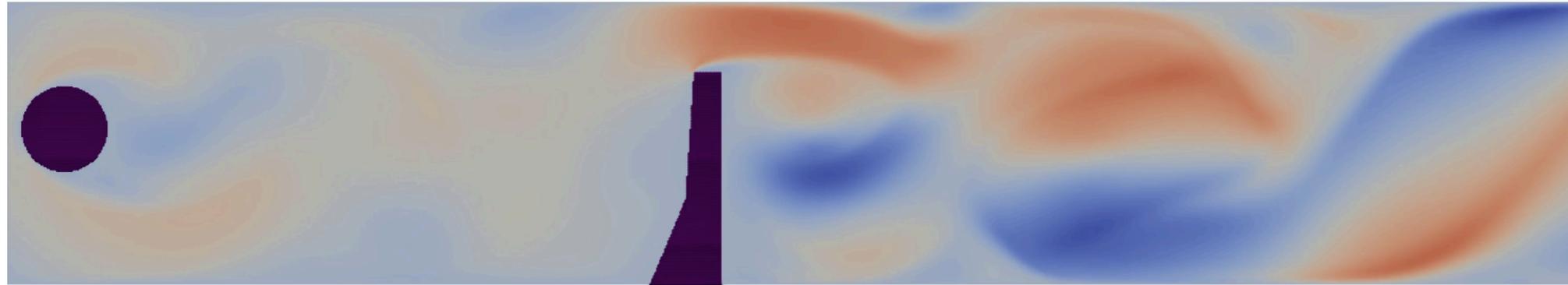
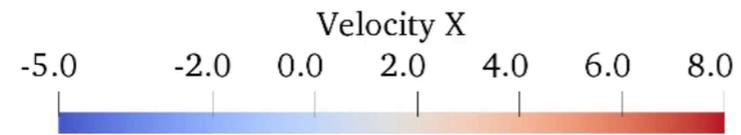
x displacement
0.0e+00 1.0e-3 2.0e-3 3.0e-03



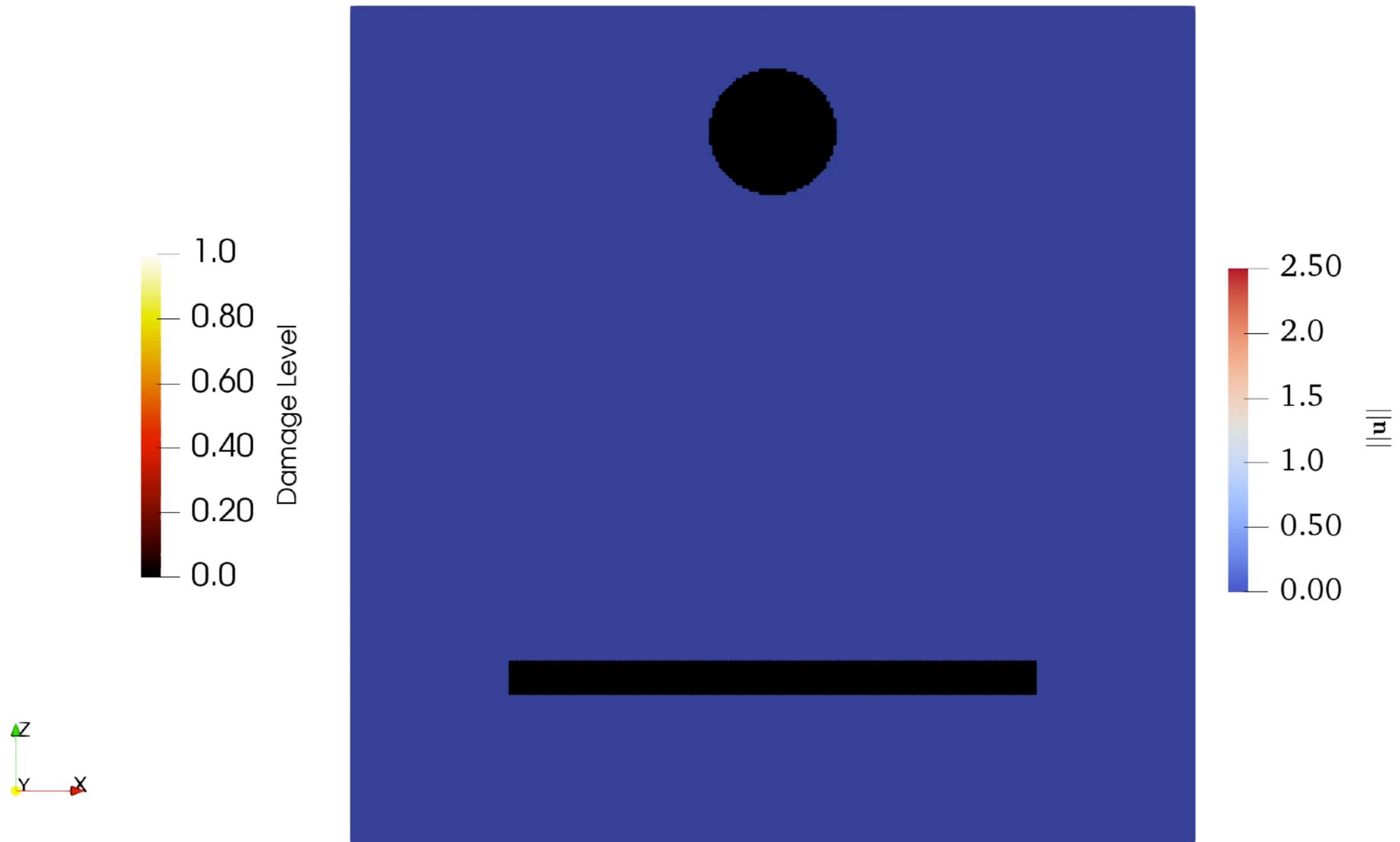
|| v ||
0.0 1.0 2.0 3.0 4.0 5.0

- Comparison with Ansys Mechanical APDL (Finite Element Method) + Ansys Fluent (upper figures).

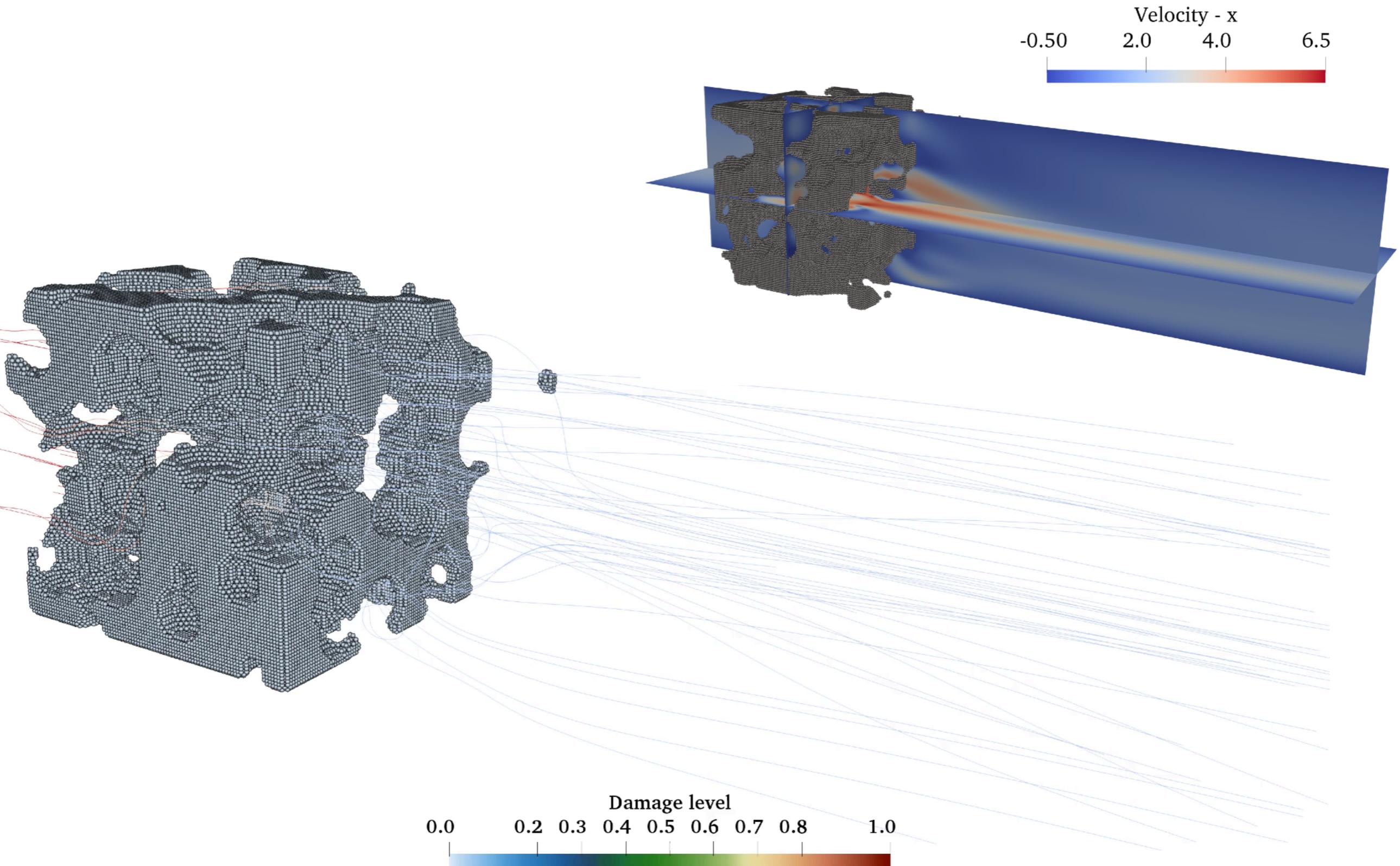
TEST CASE: IMPACT IN 2D POISEUILLE FLOW



TEST CASE: FALLING SPHERE IN AIR AT REST

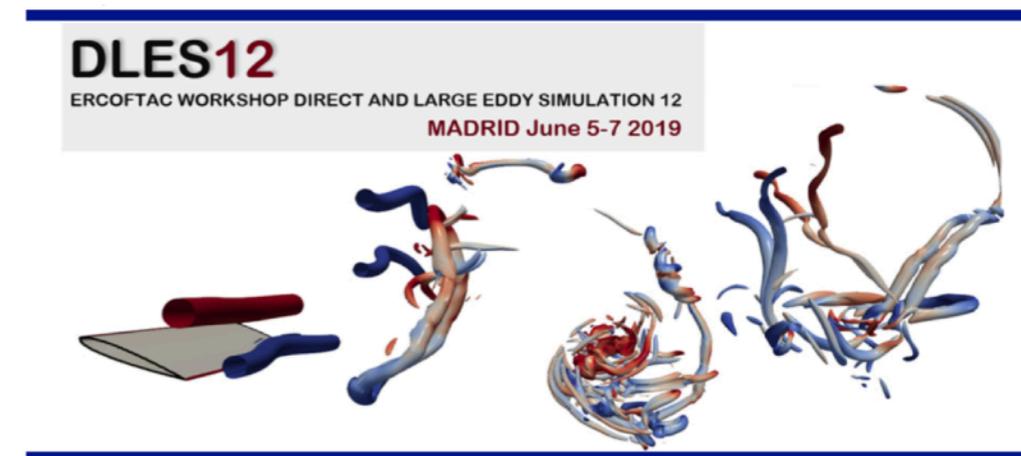


TEST CASE: FRACTURE OF POROUS MEDIA IN LAMINAR FLOW



REPORT OF TASKS COMPLETED IN THE SECOND YEAR OF PhD COURSE

- **TASK 1: IMPROVEMENT OF THE COUPLING BETWEEN THE FLUID AND THE SOLID SOLVERS**
 - Implementation of the normal probe method
 - Testing of different coupling strategies
- **TASK 2: IMPROVEMENT OF THE FLUID SOLVER AND MPI PARALLELIZATION:**
 - Major modifications required to improve the coupling between the solid and the fluid solver
 - Major modifications to improve the performances of the code on distributed memory systems
- **TASK 3: TESTING CAMPAIGN FOR THE NEW SOLVER**
 - Porous media fracture: simulation of the break up of a porous media using more than 1024 cores on Marconi cluster at Cineca
 - Impact of solid objects in incompressible flows
- **TASK 4: Presentation at Direct and Large Eddy Simulation (DLES12) Madrid. The abstract has been selected for the Special Issue of FTaC, to comprise around 15 papers, selected from a total of the 108 papers that were presented orally at DLES12.**
- **TASK 5: Writing of a journal paper (work in progress)**





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THANK YOU FOR YOUR ATTENTION!

