



3rd year annual report
24th October, 2016

Dynamic wireless charging of Electric Vehicles



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Containts

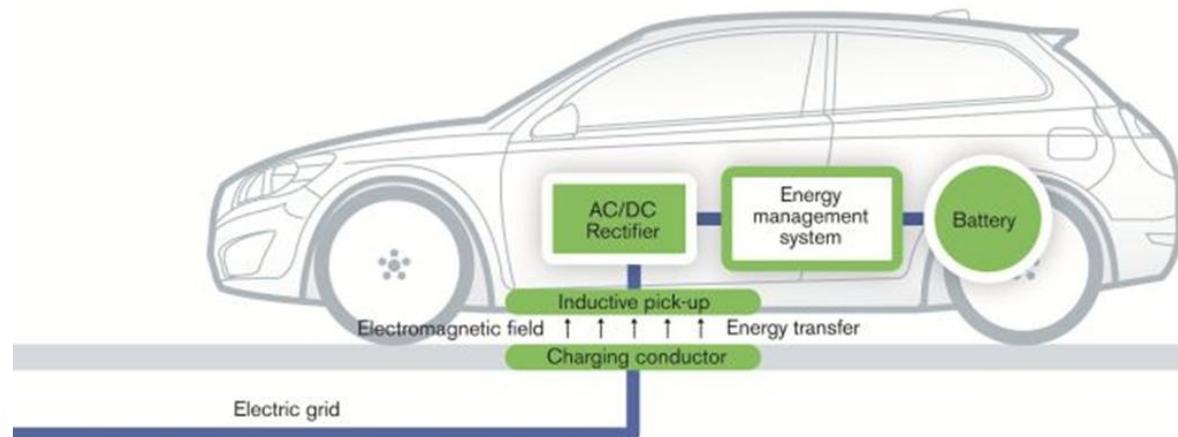
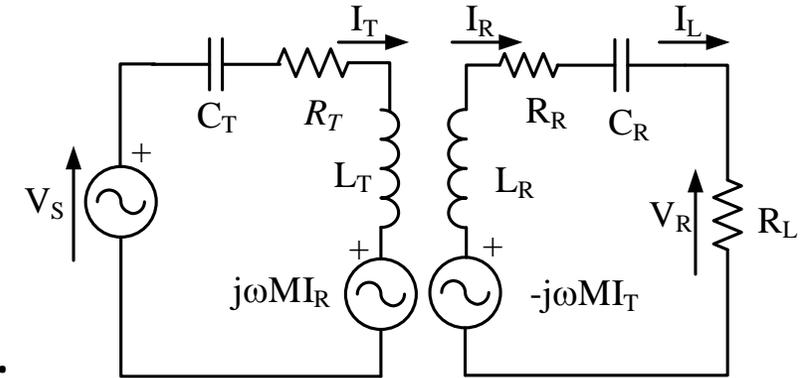
- Wireless battery charging (WBC)
- WPT coils and coupling
- WPT track segmentation
- Reflexive Segmentation
- DD coil for dynamic WBC
- Energy Analysis in Motion
- Unequal DD coil for dynamic WBC



- Inductive power transfer is the most convenient.
- Power transfer efficiency

$$\eta = \frac{1}{1 + \frac{R_T R_R}{\omega_0^2 M^2}}$$

- Higher M and ω_0 improves the efficiency.
- M depends upon coil structure and airgap.
- Resonance (using C_T and C_R) improves efficiency.



- WPT track is buried under road surface.

- Track configurations-

- Stretched coil track
- Lumped coil track

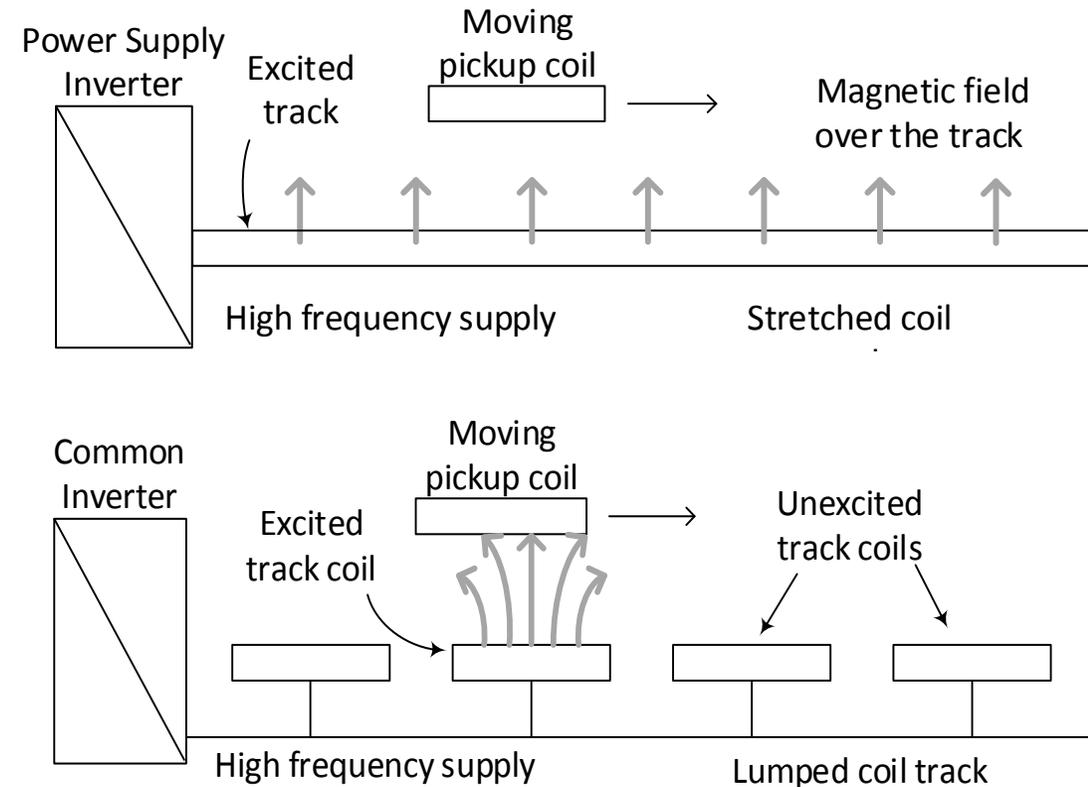
- Coupling Coefficient:

$$M = k\sqrt{L_T L_R}$$

- Attributes of comparison

- Power transfer efficiency
- Segmentation capability

- Lumped coil track has been chosen for further research.



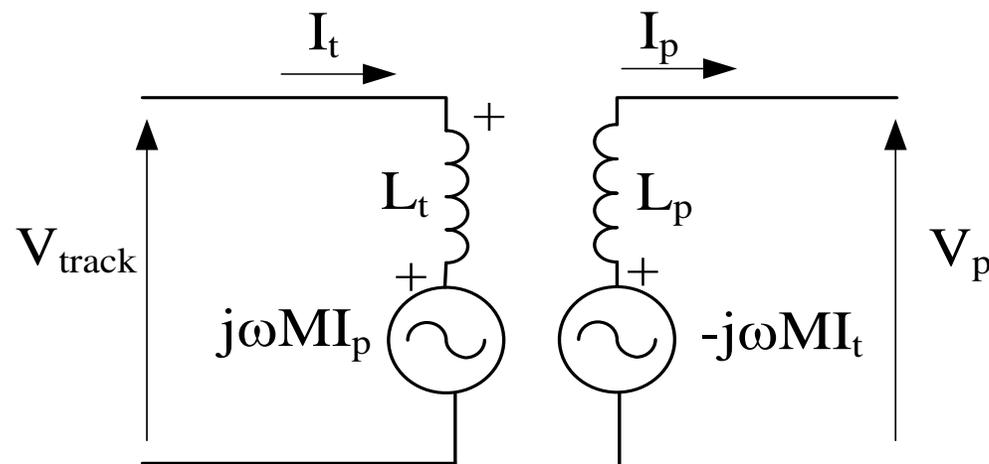
- WPT track is divided in segments for safety purpose.
- Flux density over OFF segments must be $< 6.25 \mu\text{T}$. (ICNIRP guideline)
- Sensing and switching arrangement makes it operational.
- Reflected impedance from pickup coil can be used for segmentation.
- Reflexive method is inherently automatic and switches free.

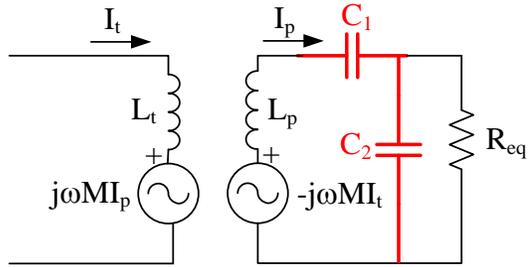


- Pickup reflects impedance into the coupled track coil.

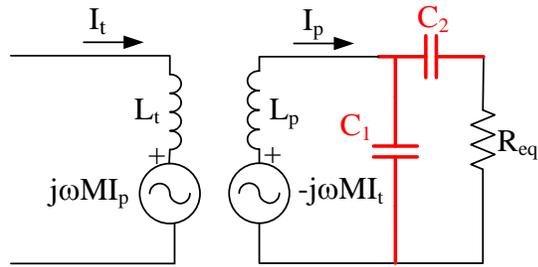
$$Z_r = \frac{j\omega M I_p}{I_t} = \frac{\omega^2 M^2}{Z_p}$$

- Compensation in pickup can define the behaviour of Z_p and Z_r .
- Commonly used single capacitor compensation is not adequate.
- Two element topologies have been considered and analysed.

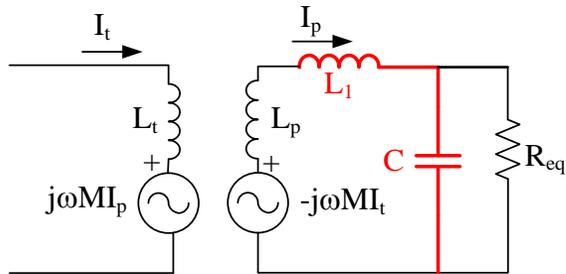




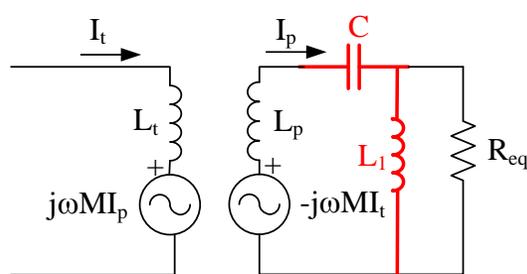
CC series-parallel (CCsp)



CC parallel-series (CCps)



LC series-parallel (LCsp)



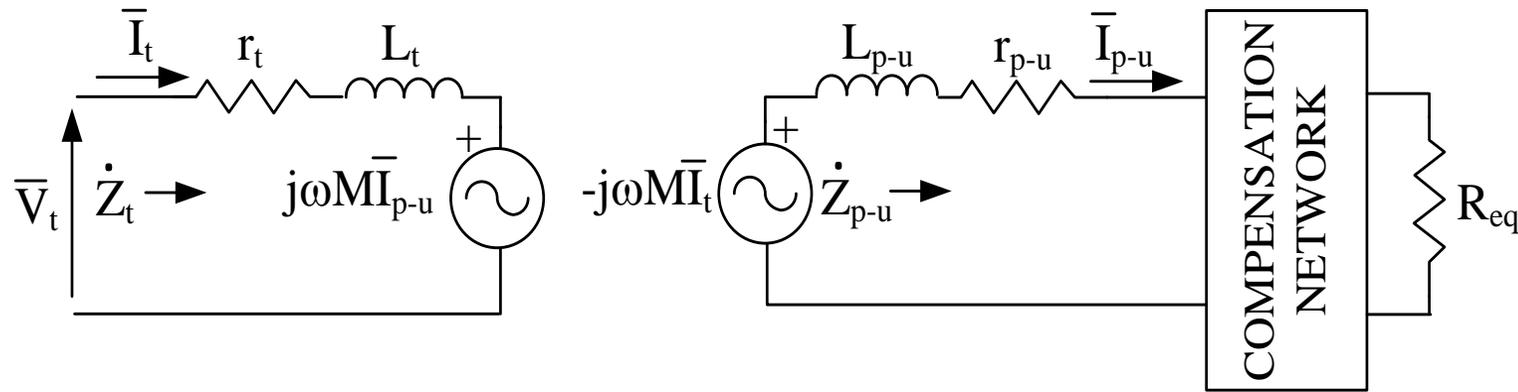
CL series-parallel (CLsp)

- Desired reflected impedance can
 - Fully compensates the track reactance
 - Prevent the resistance rise.

Factors	CCsp	CCps	LCsp	CLsp
Segmentation ability	✓	✓	✗	✓
Reflected R_{eq} is limited	✓	✓	✗	✗

- Current gain in coupled state is prime factor of selection.
- Nature of reflected real load affect the current gain.
- CCsp and CCps have candidature for application.



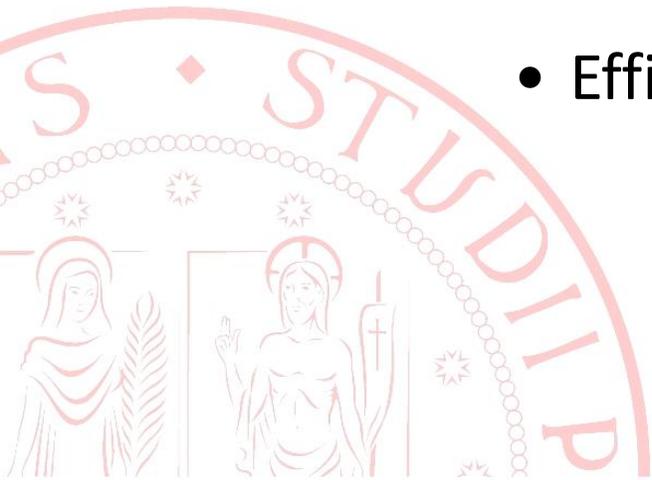


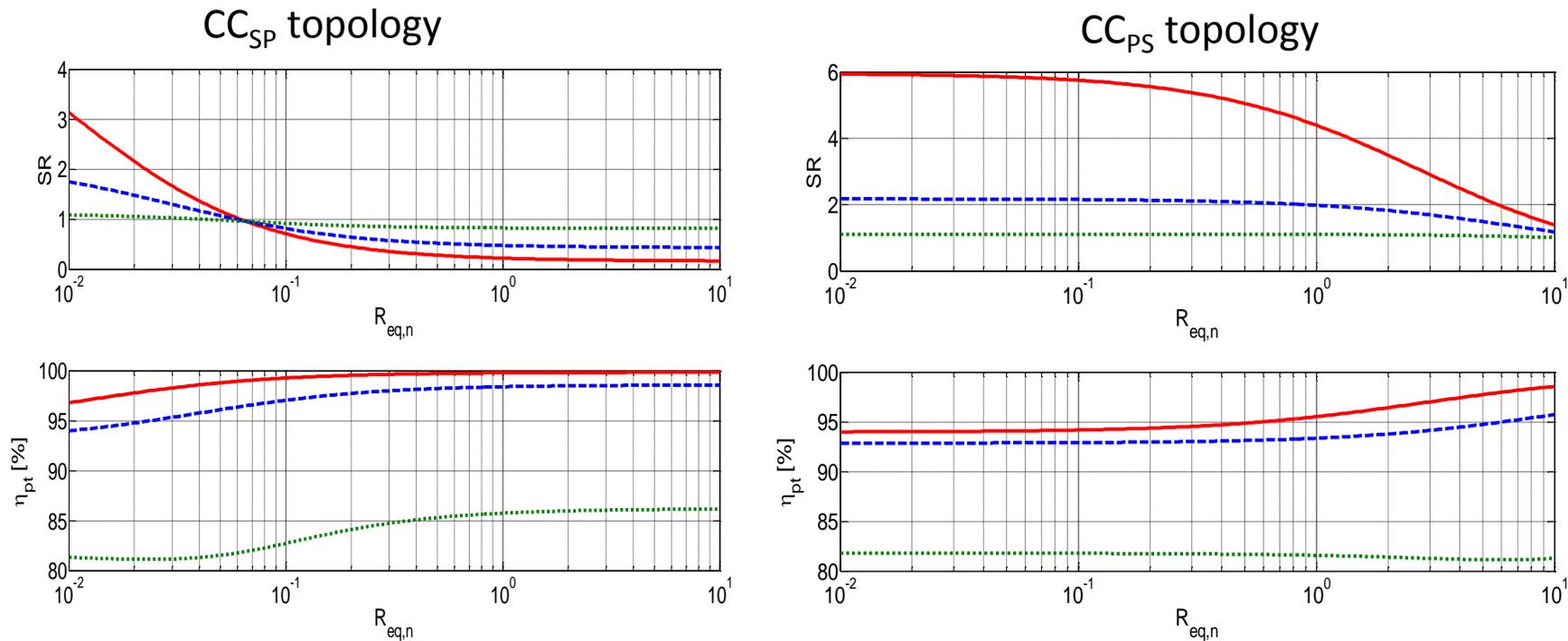
- Performance is analyzed with different compensation network.
- Segmentation ration

$$SR \triangleq \frac{|\bar{I}_{t,c}|}{|\bar{I}_{t,nc}|}$$

- Efficiency

$$\eta_{pt} = \frac{P_{p-u}}{P_s} = \frac{R_{ref}}{r_t + R_{ref}}$$

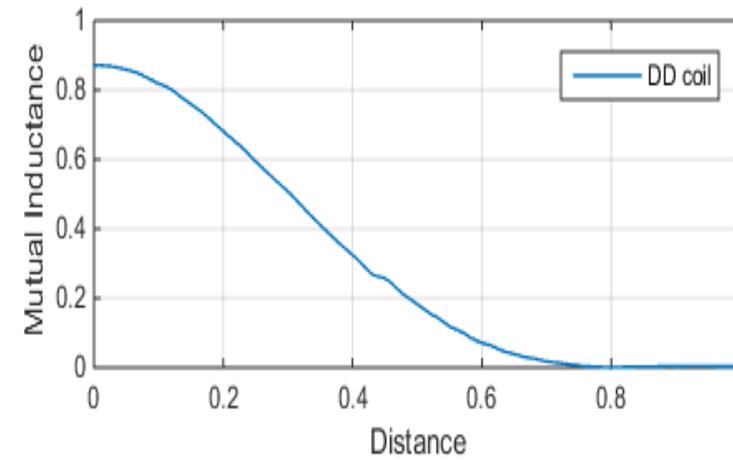
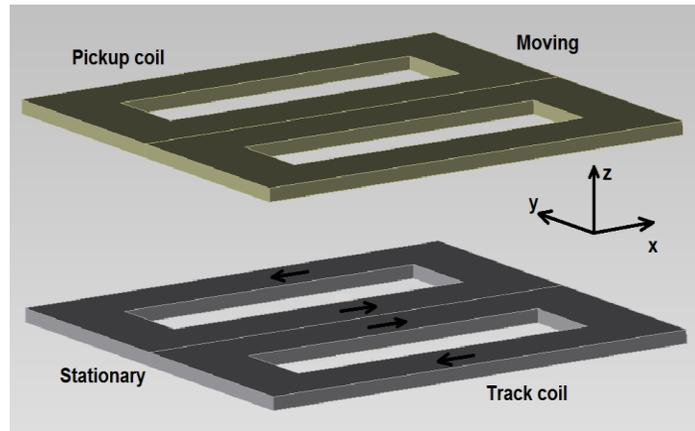




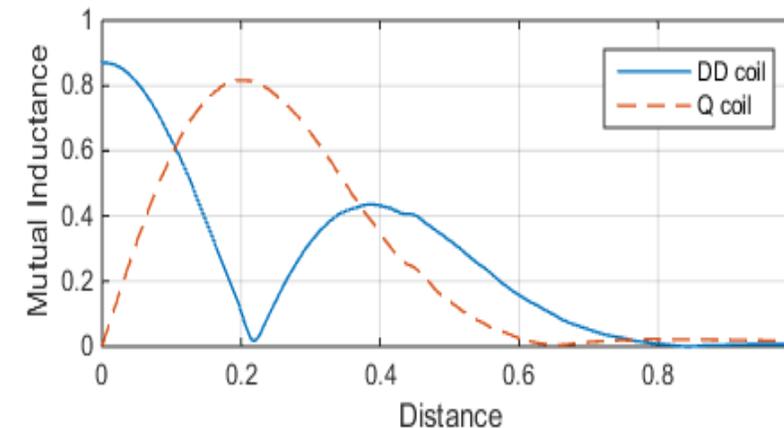
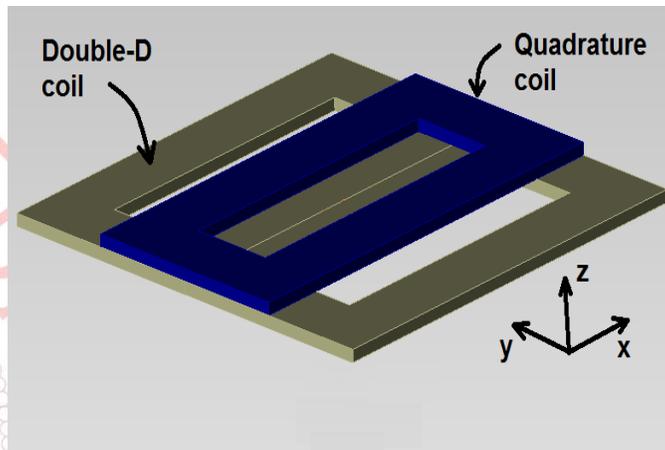
Curves are traced for normalized track coil resistance ($r_{t,n}$) 0.01 (red), 0.03 (blue) and 0.1 (green)

Parameters are normalized with respective coil reactance (ωL_{p-u} for pickup and ωL_t for track).

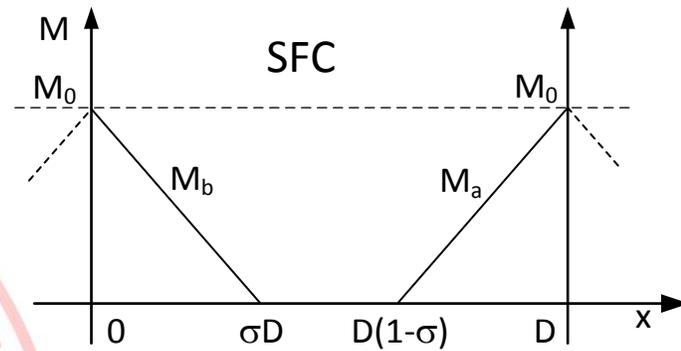
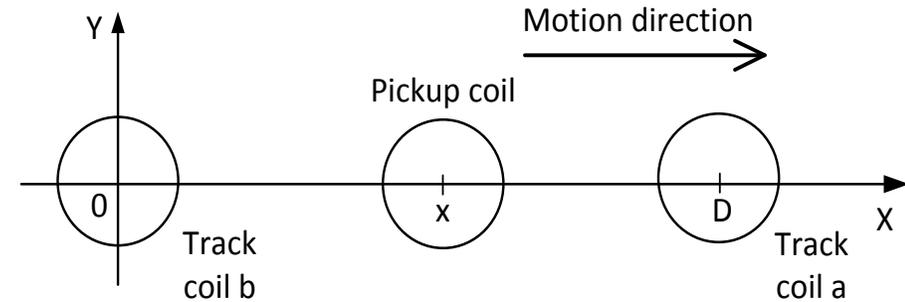
- Reflected resistance in CC_{PS} topology is much lower than CC_{SP} .
- Lower R_{ref} resistance reduces η_{pt} but makes high Segmentation Ratio (SR).
- Parasitic resistance significantly deteriorates the performance.



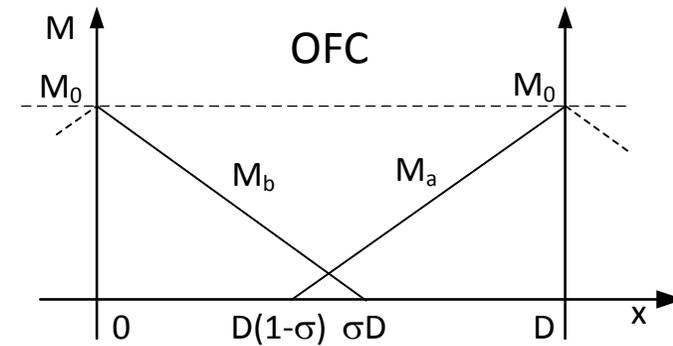
- Opposite poles are in same face of the coil.
- Behaviour of mutual inductance depends upon the direction of misalignment.
- Quadrature coil (Q-coil) can compensate the null power effect.
- JMAG data is plotted.



- Energy analysis while pickup is moving b/w two track coils.
- Induced voltage in pickup $V_I = \omega_s I_t [M_b(x) + M_a(x)]$
- Two analysis conditions
 - Separate flux coverage (SFC)
 - Overlapped flux coverage (OFC)
- σ is the coefficient to define SFC ($\sigma < 0.5$) and OFC ($\sigma > 0.5$).



$$E_{SFC} = 2\sigma D \frac{KM_0^2}{3U}$$



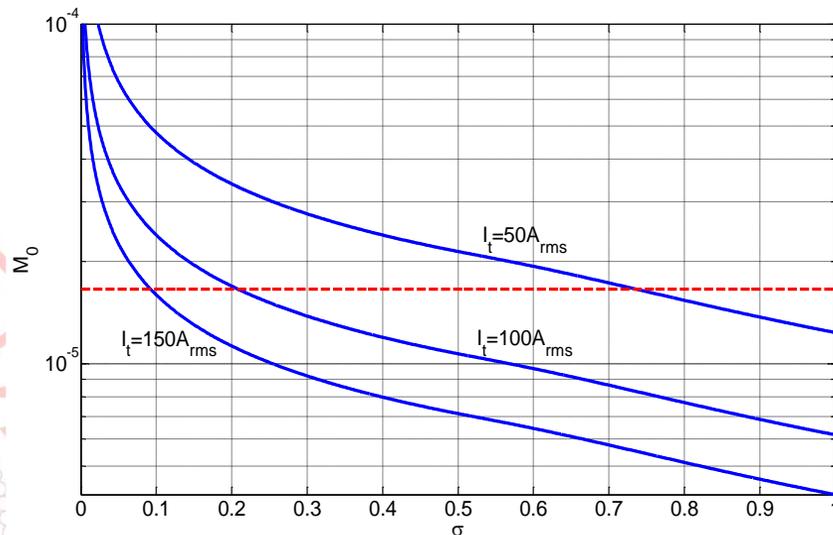
$$E_{OFC} = 2\sigma D \frac{KM_0^2}{3U} \left(5 + \frac{3}{\sigma^2} - \frac{1}{2\sigma^3} - \frac{6}{\sigma} \right)$$

- Per km energy transfer (E_{km}) can be written as

$$E_{km_SFC} = \frac{1000}{3U} \frac{\omega_s^2 I_t^2 M_0^2}{R_L} \sigma$$

$$E_{km_OFC} = \frac{1000}{3U} \frac{\omega_s^2 I_t^2 M_0^2}{R_L} \sigma \left(5 + \frac{3}{\sigma^2} - \frac{1}{2\sigma^3} - \frac{6}{\sigma} \right)$$

- For a fixed E_{km} , relation among M_0 , I_t and σ is plotted.
- This diagram gives a guideline to design a track layout.
- Considering 4 pairs of coils, track design is reported in the table.



Coil pair	M_0 (μH)	Current [A_{rms}]	σ	n [coil/km]
#1	16.6	50	0.736	294
		100	0.208	83
		150	0.093	37
#2	9.7	50	n.a.	n.a.
		100	0.595	397
		150	0.269	179
#3	6.3	50	n.a.	n.a.
		100	0.981	981
		150	0.623	623
#4	5.8	50	n.a.	n.a.
		100	n.a.	n.a.
		150	0.683	455

- The power needed to run a car at constant speed U on a horizontal road is

$$P_{tract} = (F_d + F_{roll})U$$

- The power supplied by the battery or DC link can be written as

$$P_{DC} = \frac{P_{tract}}{\eta_{PT}} + P_{aux}$$

- Requisite energy per km can be written as

$$E_{tract} = \frac{1000 P_{tract}}{U}$$

- Peak power transfer in WPT is

$$P_0 = \frac{\omega_s^2 I_t^2 M_0^2}{2R_L}$$

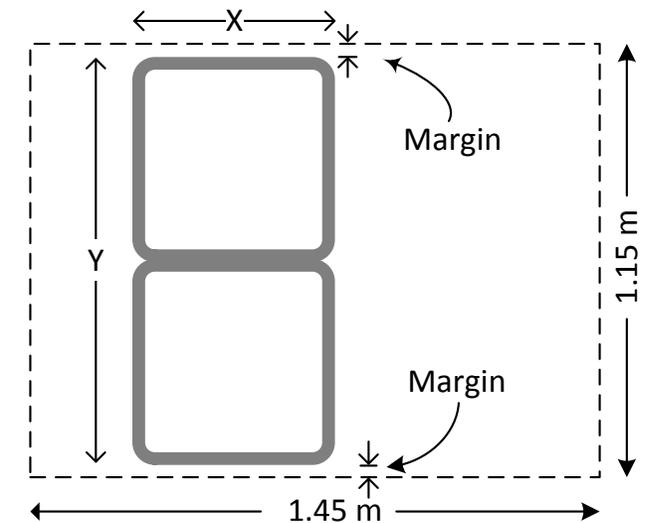
- An overall efficiency of 80% is assumed for the EV powertrain,

$$R_L = \frac{8}{\pi^2} \frac{V_B^2}{P_{avg}}$$



- Electric vehicle: ENEA Urbe.
- DD coil set is designed for DWC.
- System power rating is 5 kw.
- Requisite energy per km is 207 kJ.
- Under body space is available for pickup coil.

Quantity	Values
Mass	756 kg
Maximum speed	50 km/h
Air drag coefficient	0.28
Front area	2.1 m ²
Rolling friction coefficient	0.01
Ground Clearance	17 cm



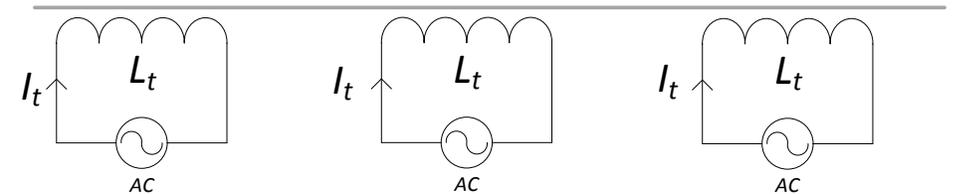
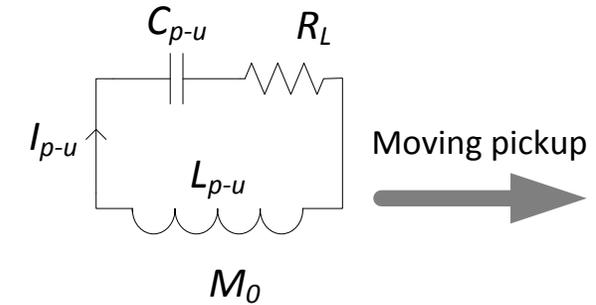
- Peak power is achieved when coils are perfectly aligned.
- Desired mutual inductance for requisite peak power is

$$M_0 = 15 \mu\text{H}$$

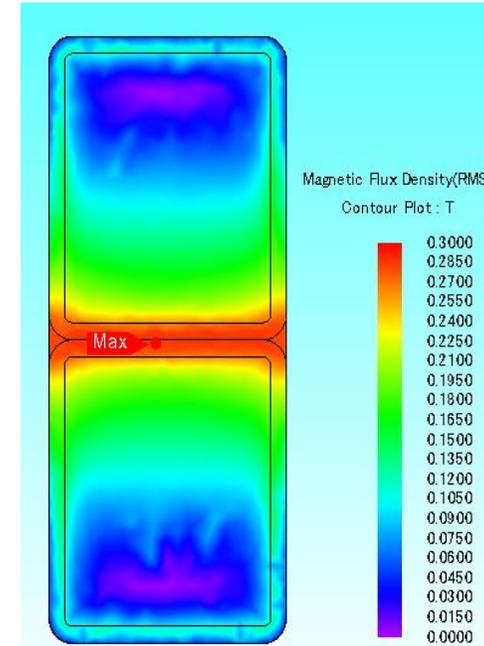
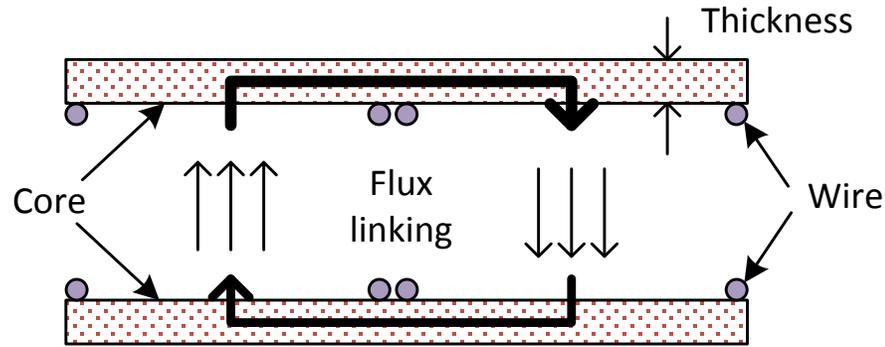
- Load equivalent resistance in pickup side is

$$R_L = \frac{8}{\pi^2} \frac{V_B^2}{P_{av}} \cong 0.65 \Omega$$

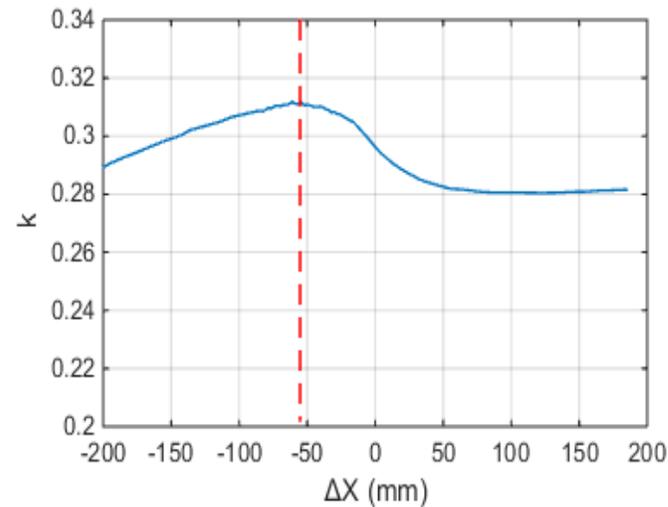
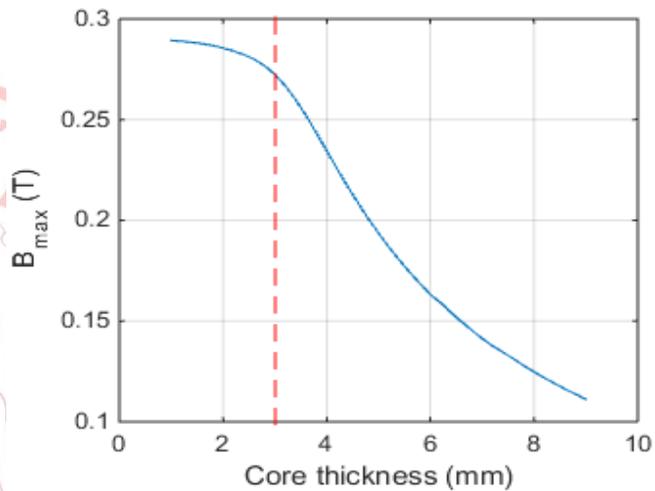
- Increasing coil turns, reduces coil area.
- For fixed M_0 , various coils have been designed.



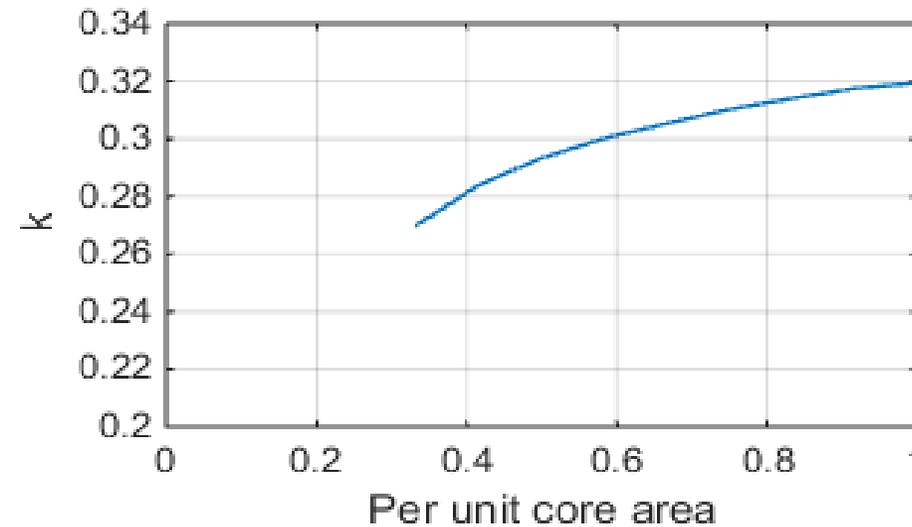
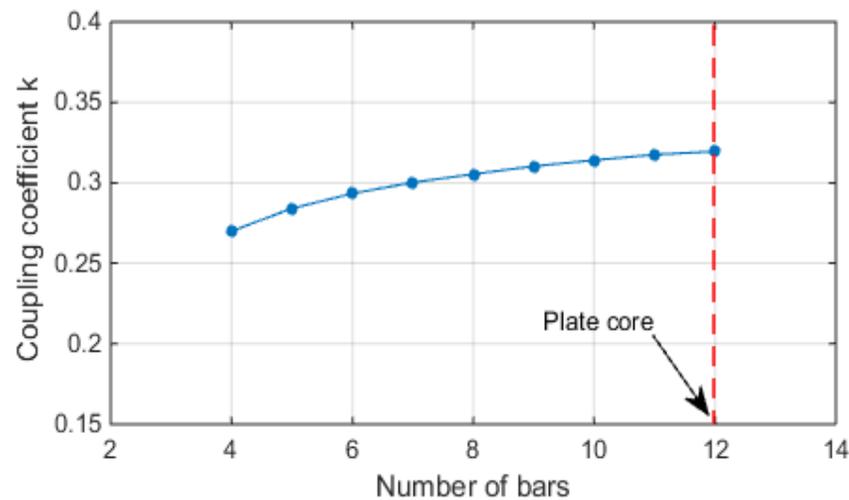
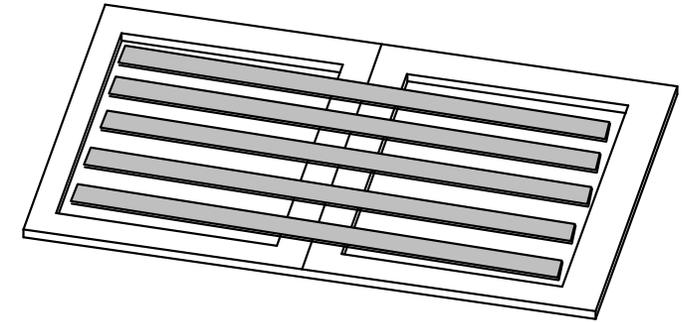
#turns	X (mm)	Y (mm)	L (μH)	M (μH)	k
1	1450	950	19,66	8,91	0,45
2	820	950	41.53	15.11	0.36
3	415	950	49.33	15.15	0.31
4	275	950	59.24	15.15	0.26
5	211	950	70.45	15.11	0.21

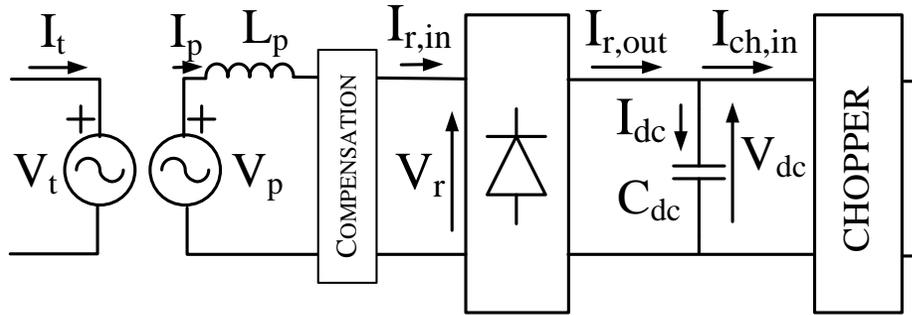


- Ferrite plates are used for flux path.
- Core thickness is designed by FEM results.
- Core plate area is optimized.

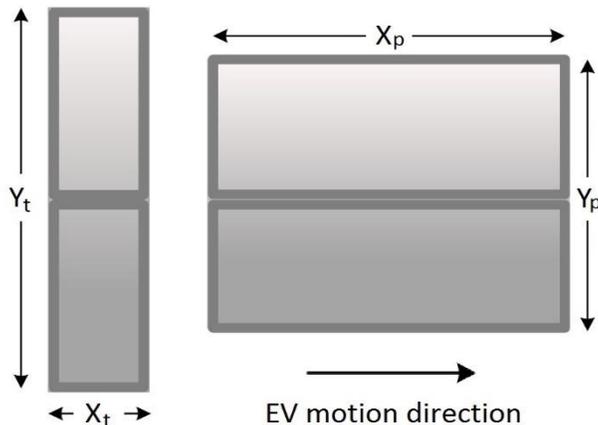


- The core plate is divided into 12 bars.
- One by one bars are removed with keeping equal spacing.
- Change in coupling coefficient is plotted.
- Material can be saved by paying reduction in coupling

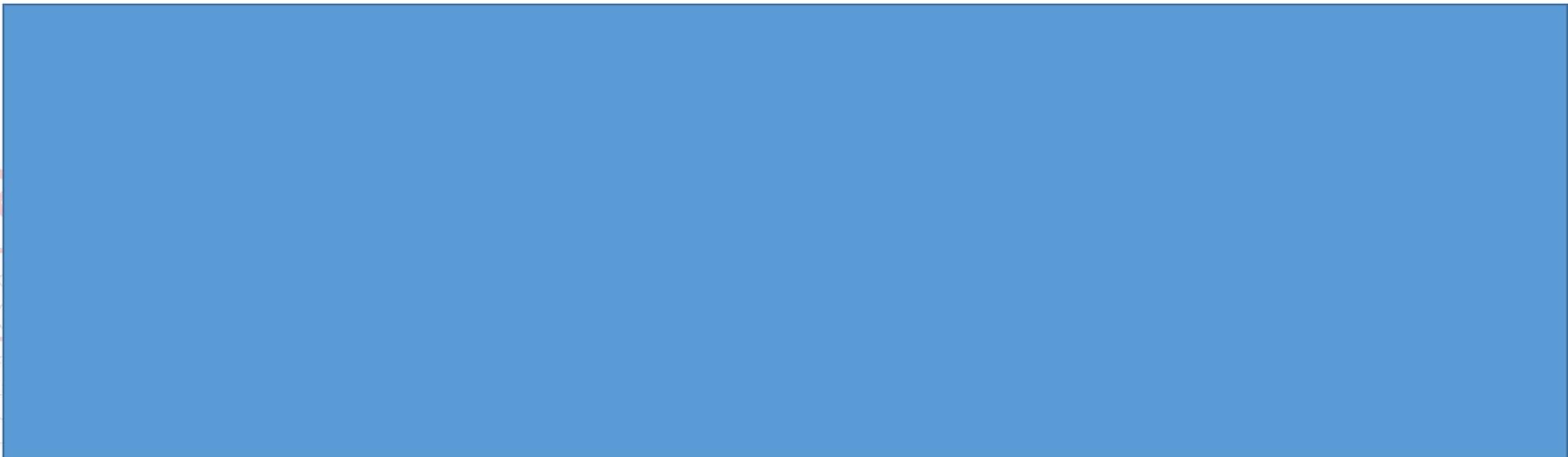




- Triangular waveform with the DD coil set.
- V_m corresponds to minimum DC link voltage.
- Higher peak voltage makes larger charging span.



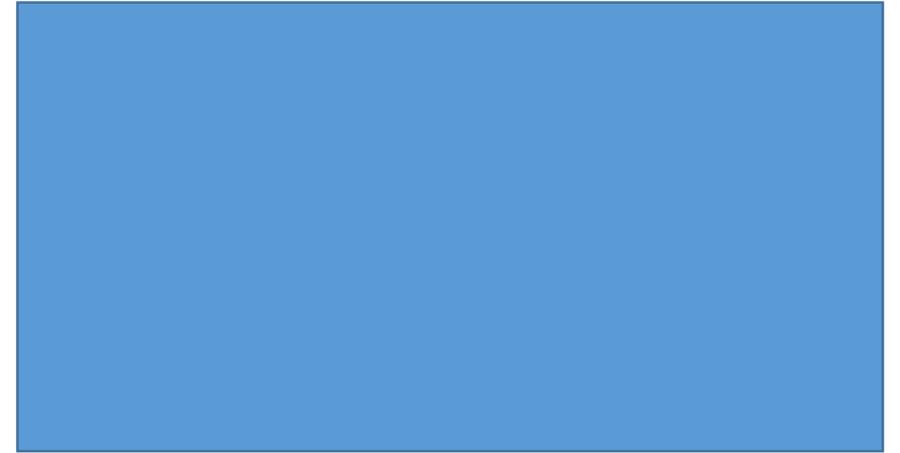
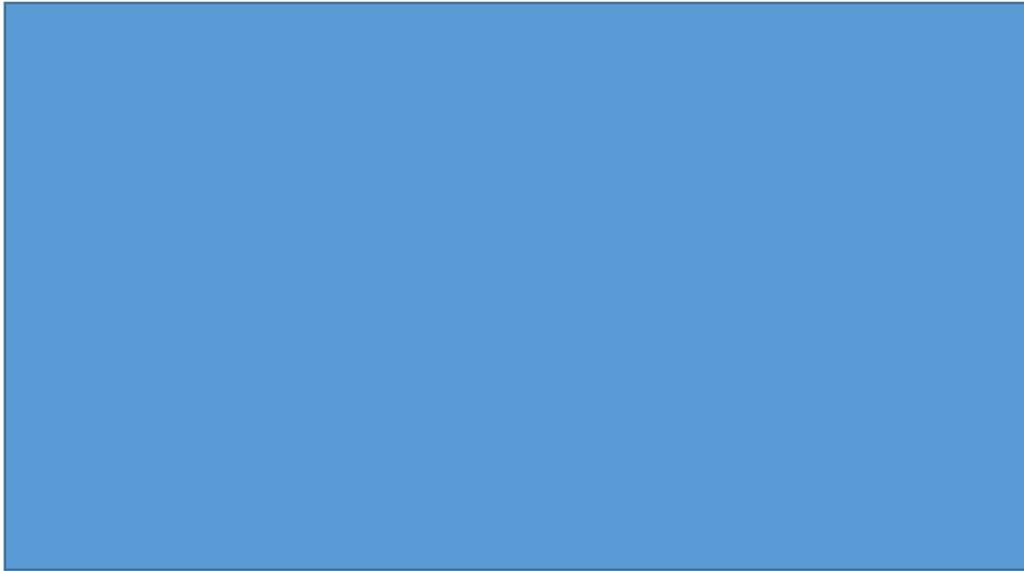
- M_0 increases by lengthening pickup.
- Unequal DD coil set shows flat-topped M-profile.
- Taking fixed track coil size, four pickup are analysed.
 - Track X-dimension= 0.40 m.
 - Track Y-dimension= 0.95 m.
- Pickup dimensions are chosen such that M_0 remains same for comparison.





Power and Energy Analysis of UDD Coil

- Separate flux coverage (SFC) and overlapped flux coverage (OFC) are defined based on σ_2 .
- Wider charging span.



- Coil length ration $\lambda = \frac{X_p}{X_t}$, where $X_p=1.2$ m fixed.
- $\lambda > 1$ for UDD and $\lambda = 1$ for DD coil set.
- Both DD and UDD coils have SFC, OFC₁ and OFC₂ arrangements.
- UDD coils allows higher V_m/V_0 and shorter track coils for all the three cases.
- Table shows that UDD coils reduce the cost of the track to less than half without impairing the performances of DWC system.





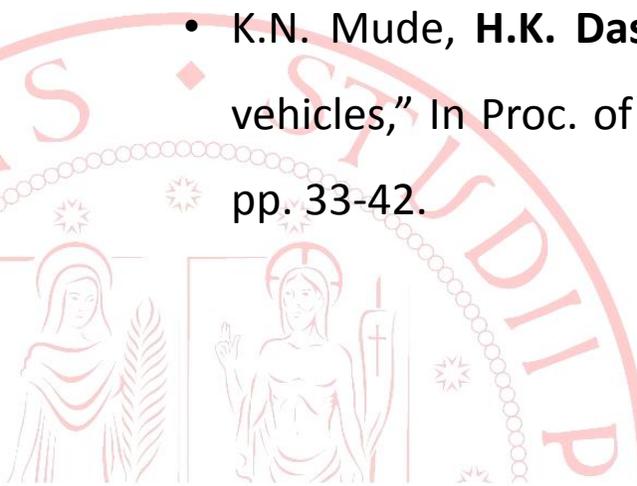
Conclusion of the Thesis

- Wireless charging of moving electric vehicles is discussed.
- WPT track and automatic track segmentation analysed.
- Power and energy analysis is explained to built a track layout.
- Special coil configuration is proposed and analysed.





- G. Buja, M. Bertoluzzo, and **H.K. Dashora**, “Lumped Track Layout Design for Dynamic Wireless Charging of Electric Vehicles,” IEEE Trans. on Industrial Electronics, Vol. 63, No. 10, pp. 6631-6640, Oct. 2016.
- **H.K. Dashora**, S. Giacomuzzi, M. Bertoluzzo, and G. Buja, “Performance Analysis of Reflexive Segmentation Topologies in DWC systems”, accepted for IEEE Industrial Electronics International Conference (IECON), 2016.
- **H.K. Dashora**, M. Bertoluzzo, G. Buja, “Reflexive properties for different pick-up circuit topologies in a distributed IPT track,” In proc. of IEEE International Conference on Industrial Informatics (INDIN), 2015, pp. 69-75.
- K.N. Mude, **H.K. Dashora**, M. Bertoluzzo, and G. Buja, “From wired to in-moving charging of the electric vehicles,” In Proc. of International Conference on Development, Energy, Environment and Economics, 2014, pp. 33-42.



ATTIVITA' DIDATTICHE ATTIVATE DALLA SCUOLA							
Corso/Seminario (Periodo/Data)	Docente	Durata (ore) del corso / seminario	Crediti ECTS acquisibili	Frequenza (SI/NO)	Accertamento (SI/NO e tipo)*	Sessione di accertamento**	Crediti ECTS acquisiti
Fundamentals of measurements for engineering	Prof. <u>Debei</u>	10	2.4	Si	SI (Write-up)	Nov, 2014	2.4
Space Optics and detectors	Prof. <u>Naletto</u>	20	4.8	Si	SI (Exam)	Nov, 2015	4.8
Spaceflight mechanics and control	Prof. <u>Lorenzini</u>	10	2.4	Si	SI (<u>Write-up+interview</u>)	Nov, 2014	2.4
Measuring instruments for diagnostics and control	Prof. Rossi	10	2.4	Si	SI (Write-up)	Nov, 2014	2.4
Preparation of a research proposal	Prof. G. <u>Naletto</u>	10	2.4	Si	SI (Write-up proposal)	Nov, 2014	2.4
PC-based measurement system development	Prof. M. <u>Lancini</u>	20	4.8	Si	SI (Project)	June, 2015	4.8
Electric Road Vehicles	Prof. G. Buja	48	6.0	Si	SI (Exam)	Nov, 2015	6.0
Technological Advancement in Electro mobility	Prof. G. Buja	6	1.2	Si	Seminar & discussion	June, 2014	1.2
Design, realization & calibration of the Stereo Camera	Prof. Dadeppo	4	0.4	Si	Seminar & discussion	May, 2016	0.4
Danno da radiazione in dispositivi elettronici	Prof. D. Bisello	4	0.4	Si	Seminar & discussion	Mar, 2016	0.4
Recenti sviluppi nella navigazione satellitare	Prof. A. Caporali	4	0.4	Si	Seminar & discussion	Mar, 2016	0.4
Dispersed Multiphase flows: intro. & adv. aspects	Prof. F. Picano	4	0.4	Si	Seminar & discussion	June, 2016	0.4
Tidal evolution in the solar system	<u>Prof. Christos</u>	4	0.4	Si	Seminar & discussion	Oct, 2016	0.4
ALTRE ATTIVITA' DIDATTICHE							
Corso/Seminario (Periodo/Data)	Docente	Durata (ore) del corso / seminario	Crediti ECTS acquisibili	Frequenza (SI/NO)	Accertamento (SI/NO e tipo)*	Sessione di accertamento**	Crediti ECTS Acquisiti
Presentation research program and attendance	Prof. G. <u>Naletto</u>	2	0.5	Si	Si	May, 2014	0.5
Presentation of the activities done during 1 st year	Prof. G. <u>Naletto</u>	2	0.5	Si	Si	Nov, 2014	0.5
Presentation of the activities done during 2 nd year	Prof. G. <u>Naletto</u>	2	0.5	Si	Si	Nov, 2015	0.5
CISAS annual presentation	Prof. G. <u>Naletto</u>	2	0.5	Si	Si	Sept, 2016	0.5
Presentation of the activities done during Ph.D. course	Prof. G. <u>Naletto</u>	2	0.5	Si	Si	Oct, 2016	0.5
Attendance to Conference	Various	75	3	Si	Si	Oct, 2016	3
Totale crediti ECTS acquisibili in attività didattiche (>30):			33.9	Totale crediti ECTS acquisiti in attività didattiche alla data 04/11/2016:			33.9



Thanks!!

