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Machine Learning algorithms for Wall-model LES of high-speed flows for aerospace applications.

Roberto Dal Monte - 40th Cycle

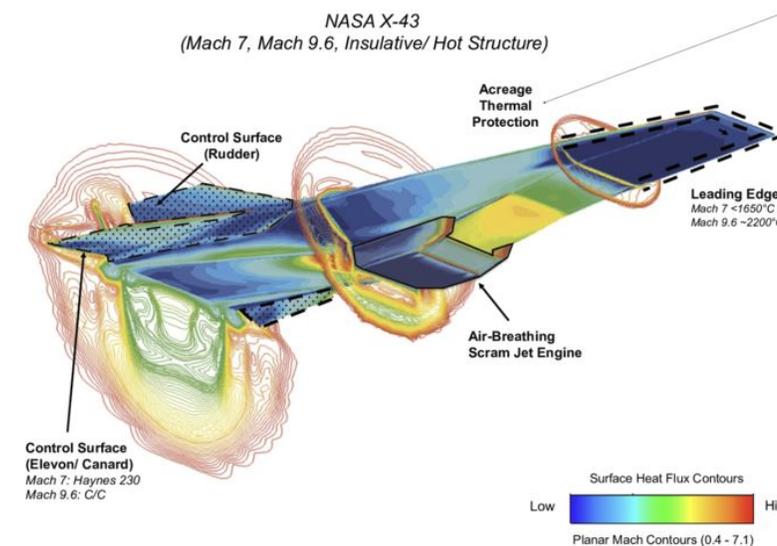
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Co-supervisor: Dott. Michele Cogo

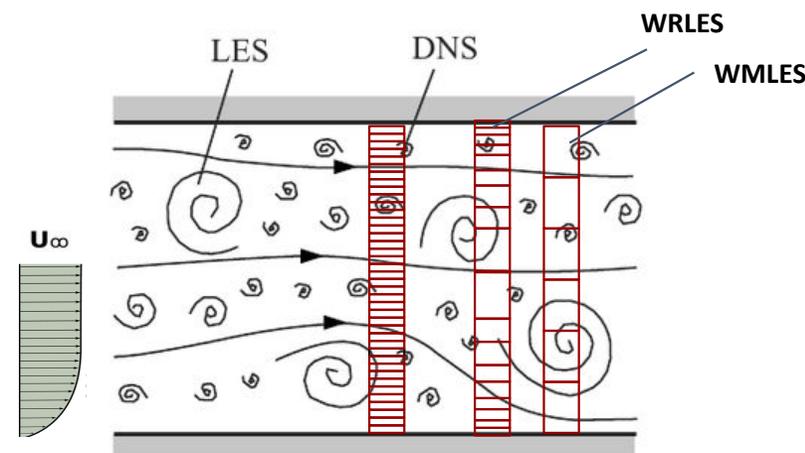
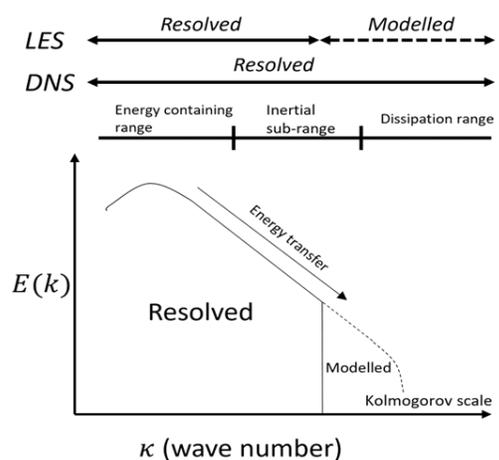
Admission to the second year - 14/10/2025

High-speed flow in aerospace applications.

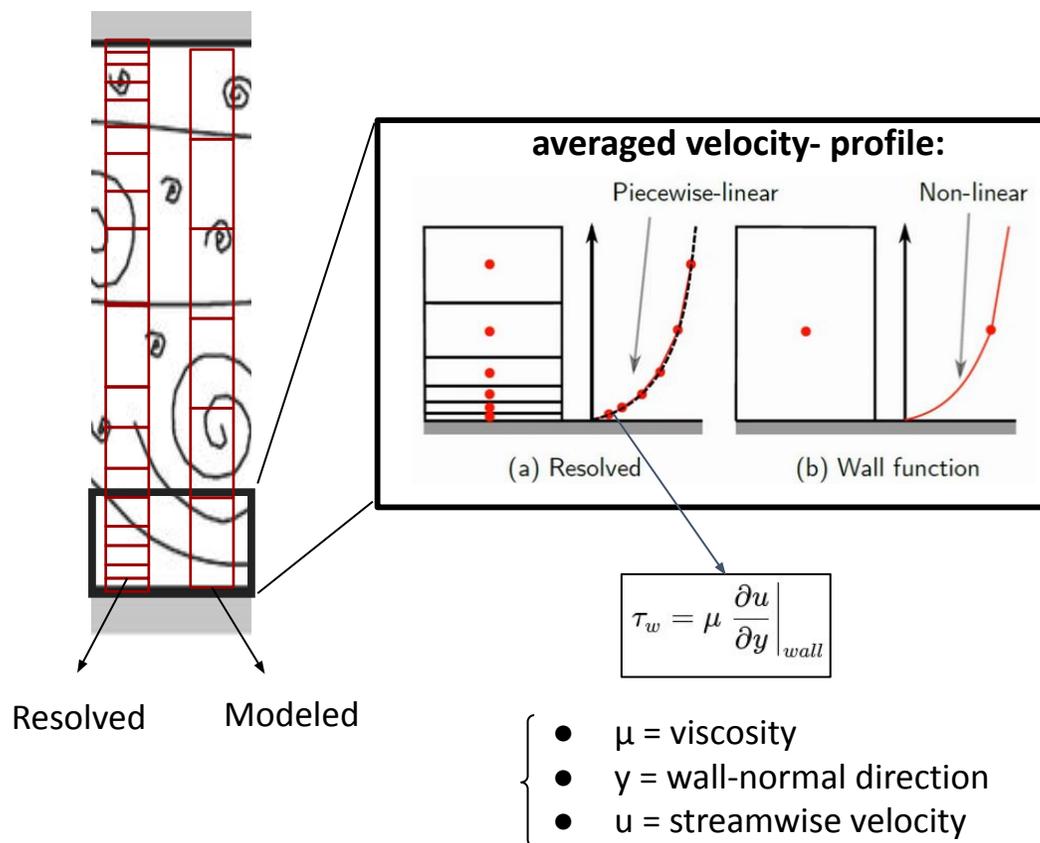
- The presence of turbulent, hot and highly compressible boundary layers increase the mechanical and thermal loads on the vehicle.
- **A detail simulation of the flow dynamics is essential** for the safe design and operation of future missions.
- Solve them directly is computationally intractable, hence **various turbulence closure models have been developed** during the years.



Peters, Adam & Dajie et al. Materials Design for Hypersonics



Limitations of current numerical approach employed to simulate unsteady flow.

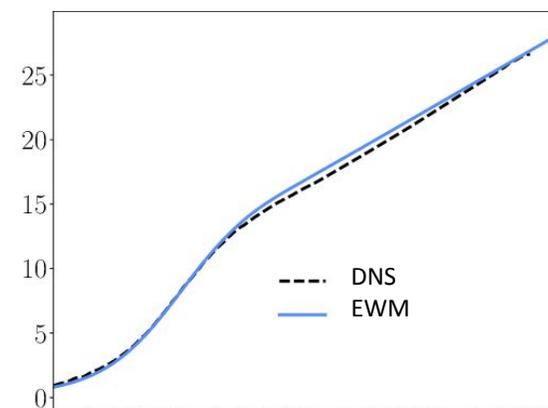


Equilibrium wall model - EWM

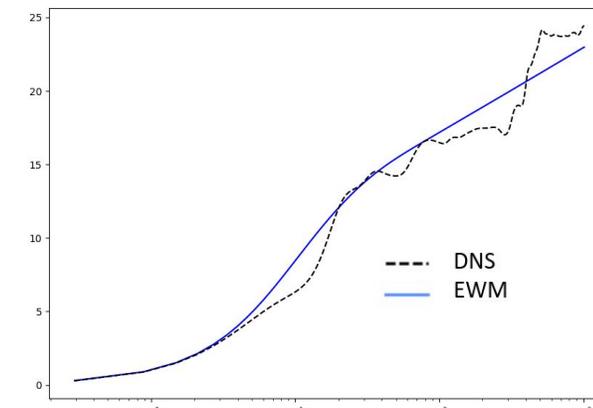
$$u^+ = \frac{1}{\kappa} \ln(1 + \kappa y^+) + C \left[1 - \exp\left(-\frac{y^+}{A}\right) - \frac{y^+}{A} \exp(-0.33 y^+) \right]$$

- averaged profile
- steady, incompressible turbulent flows
- absence of strong pressure gradients
- no flow separation

averaged velocity profile



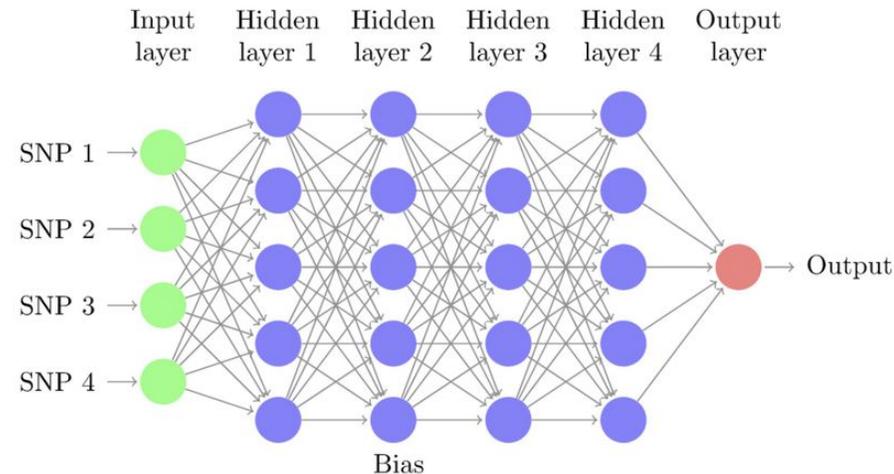
instantaneous velocity profile



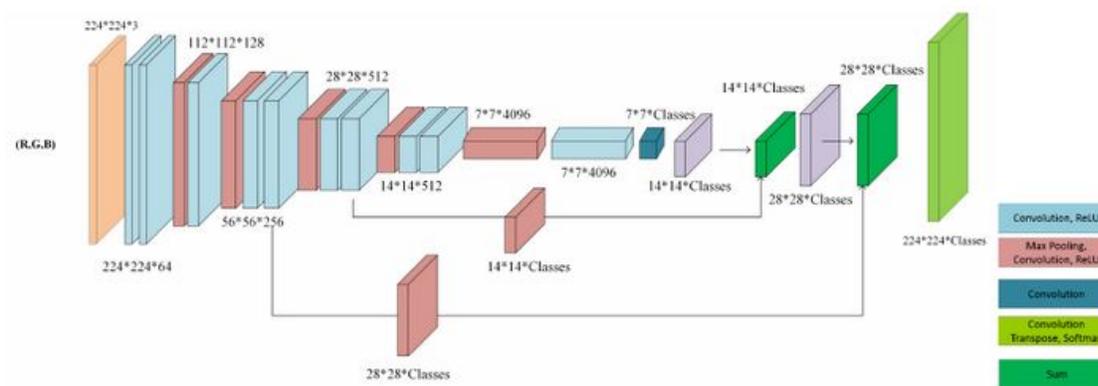
Machine Learning to overcome the limitations of cutting-edge CFD methodologies:

Machine Learning (ML) and Deep Learning (DL) are computational approaches that **enable systems to automatically learn patterns and make predictions from data.**

They are widely used in scientific research to analyze complex datasets, uncover hidden relationships, and accelerate discoveries across fields such as physics, biology, and medicine.



Pérez-Enciso, Miguel & Zingaretti, Laura. (2019). A Guide on Deep Learning for Complex Trait Genomic Prediction.

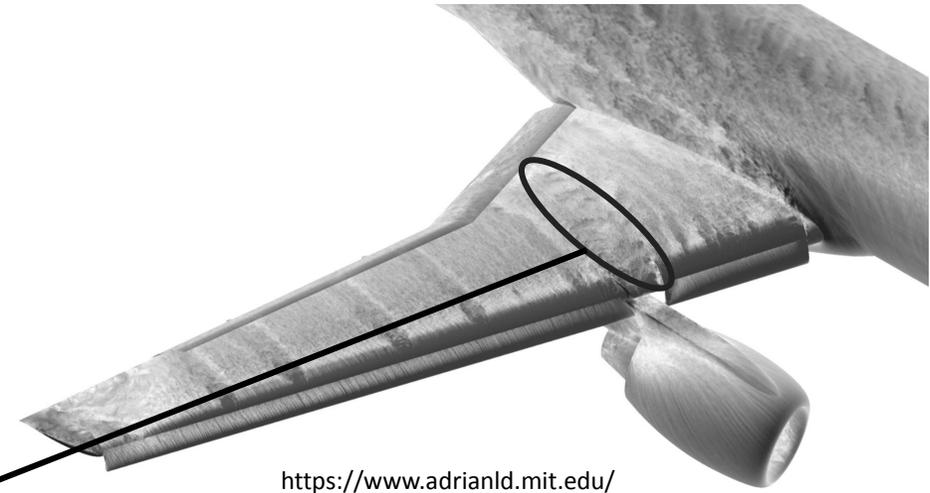


Piramanayagam. Supervised Classification of Multisensor Remotely Sensed Images Using a Deep Learning Framework. Remote Sensing.

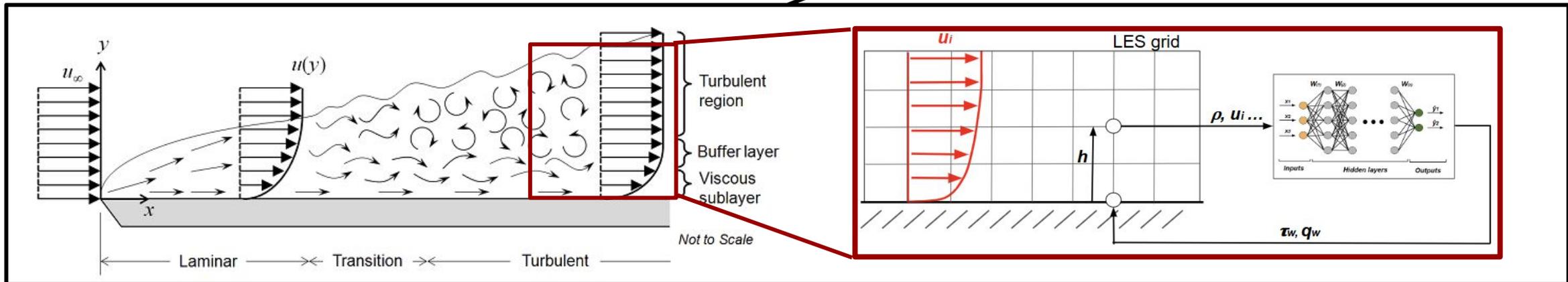
Machine Learning based methods for turbulence modeling.

Key idea: use data-driven **ML algorithms** to develop new turbulence models with:

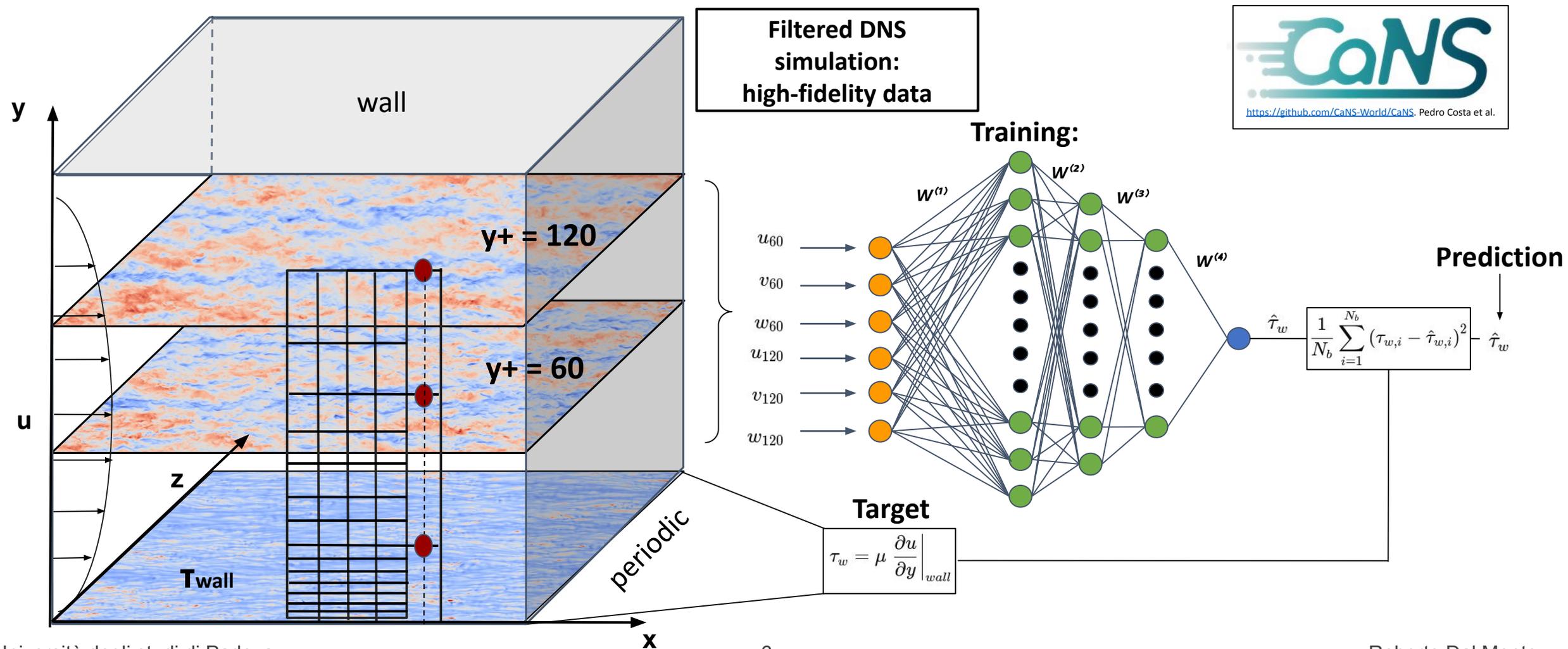
- **increase accuracy**
- **greater generalization**
- **applicable to complex scenarios** relevant for aerospace applications.



<https://www.adrianld.mit.edu/>



MultiLayer Perceptron (MLP) for predicting friction shear stresses knowing the velocity field far from the wall



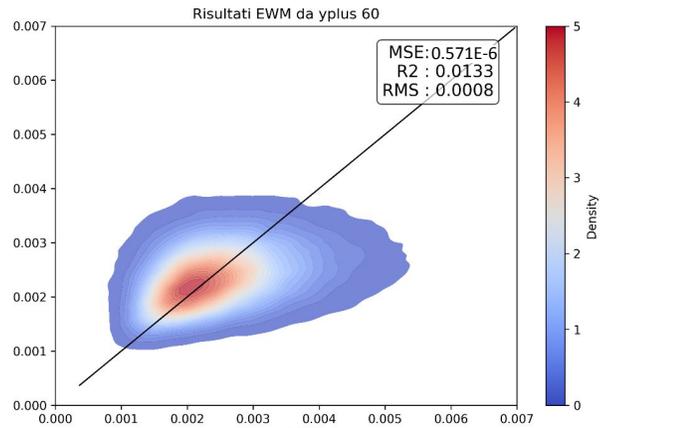


Activity Breakdown: Task #1

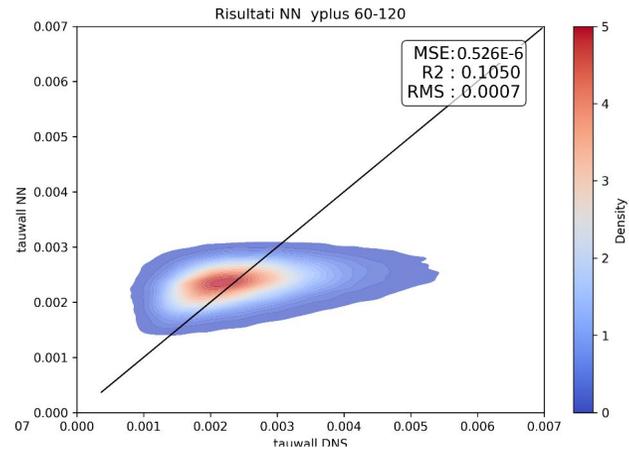


MLP vs EWM: *a priori* analysis

EWM results (reference):

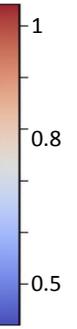
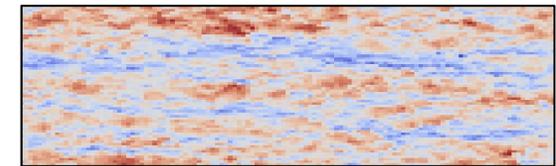


MLP results:

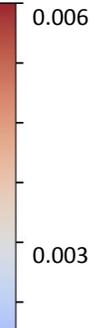
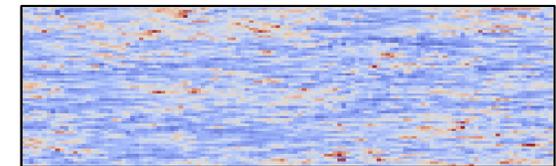


single slice (MLP prediction):

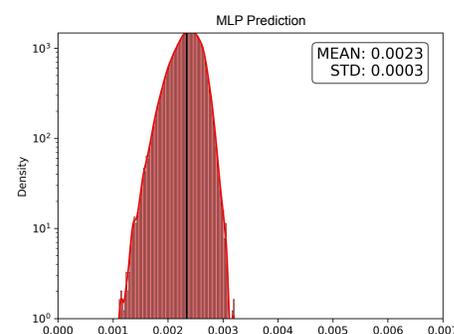
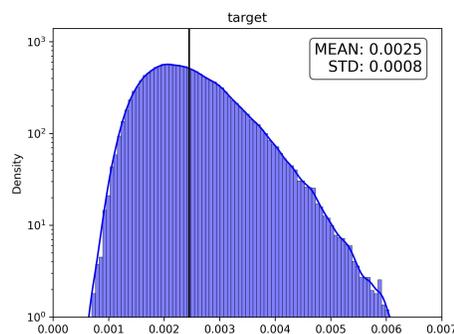
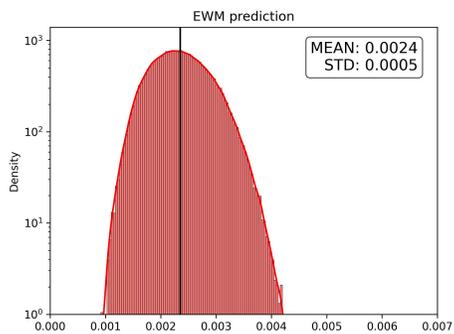
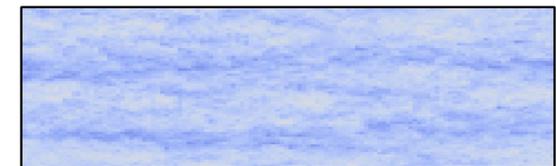
u at y+ = 60 & 120 (input):



Tw reference



Tw predicted



Metrics for evaluating the performance of MLP against EWM: *a priori* analysis

	MLP	EWM
MSE	5.26 E-7	5.71 E-7
R2	0.105	0.0133
RE_u+ (*)	1.48 %	1.92 %
RMS_u+ (*)	2.99%	3.88 %

- MLP model shows slightly better accuracy compare to EWM
- As EWM, MLP struggles to reproduce target variance
- Fine tuning techniques didn't lead to an improvement of accuracy → **probably the model has reached its maximum performances in term of accuracy and generalizability**



Improvements are expected considering models able to learn spatial correlations in addition to single input-output mapping

$$* \text{RE}_{u^+} : E_{\langle u \rangle^+} = \frac{|\langle u_{NN} \rangle^+ - \langle u_{DNS} \rangle^+|}{\langle u_{DNS} \rangle^+}, \quad * \text{RMS}_{u^+} : E_{u_{RMS}^+} = \frac{|u_{RMS,NN}^+ - u_{RMS,DNS}^+|}{u_{RMS,DNS}^+},$$

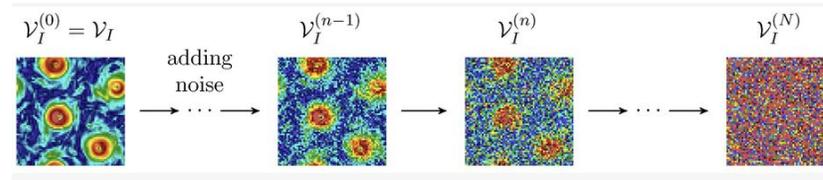
$\langle u_{DNS} \rangle^+$ refers to filtered DNS-data

Denoising Diffusion Probabilistic Model (DDPM) to overcome MLP limitations

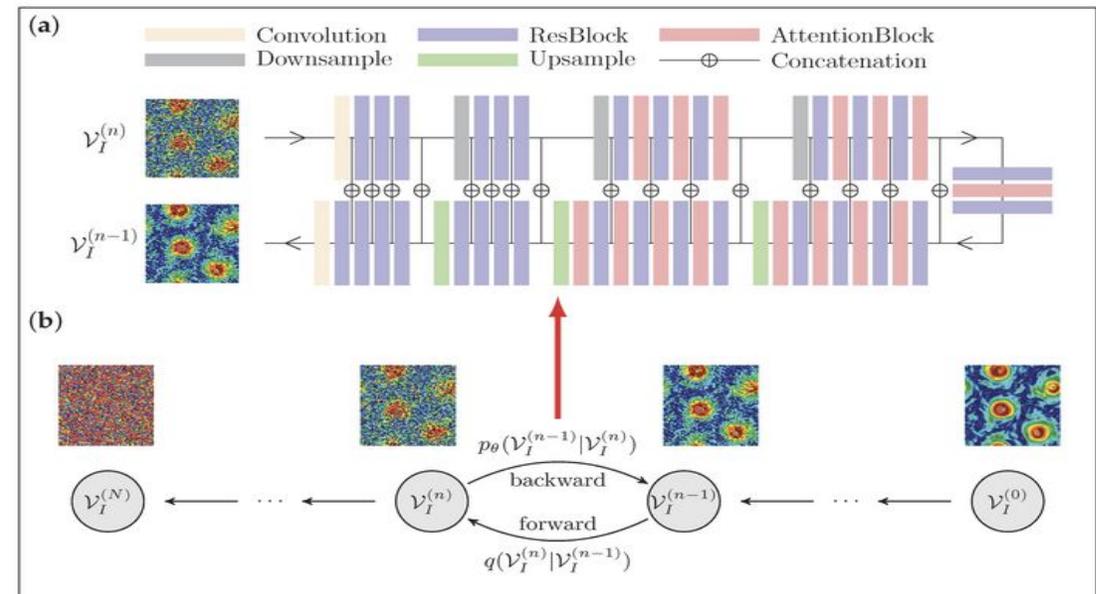
Denoising Diffusion Probabilistic Models (DDPMs) are generative models that **learn data distributions** by gradually corrupting samples with noise (forward process) and then training a neural network to reverse this process (reverse process).

Through iterative denoising, **they can generate highly realistic samples that capture complex, high-dimensional relationships** present in the training data.

Forward process:

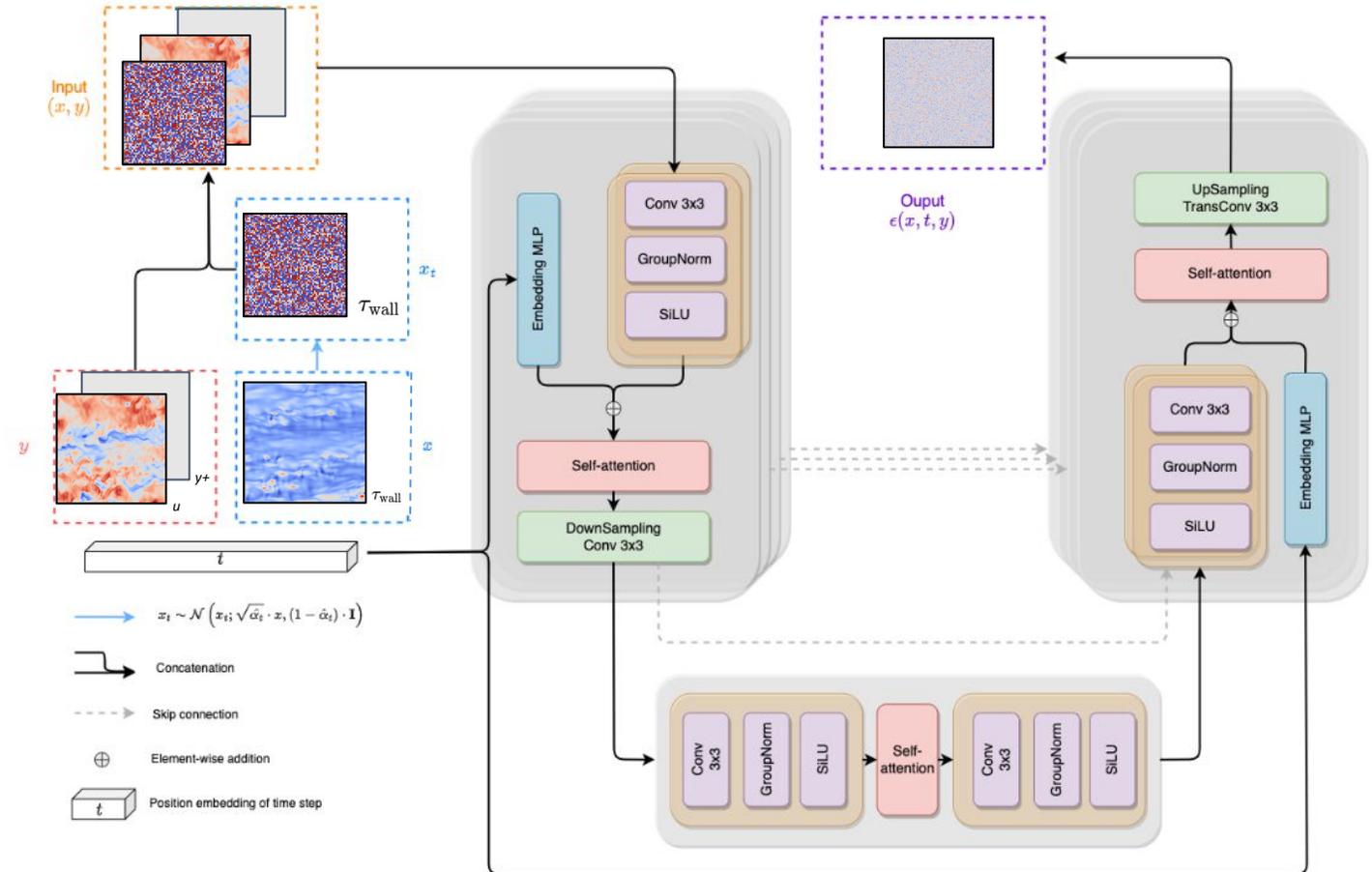


Reverse process:

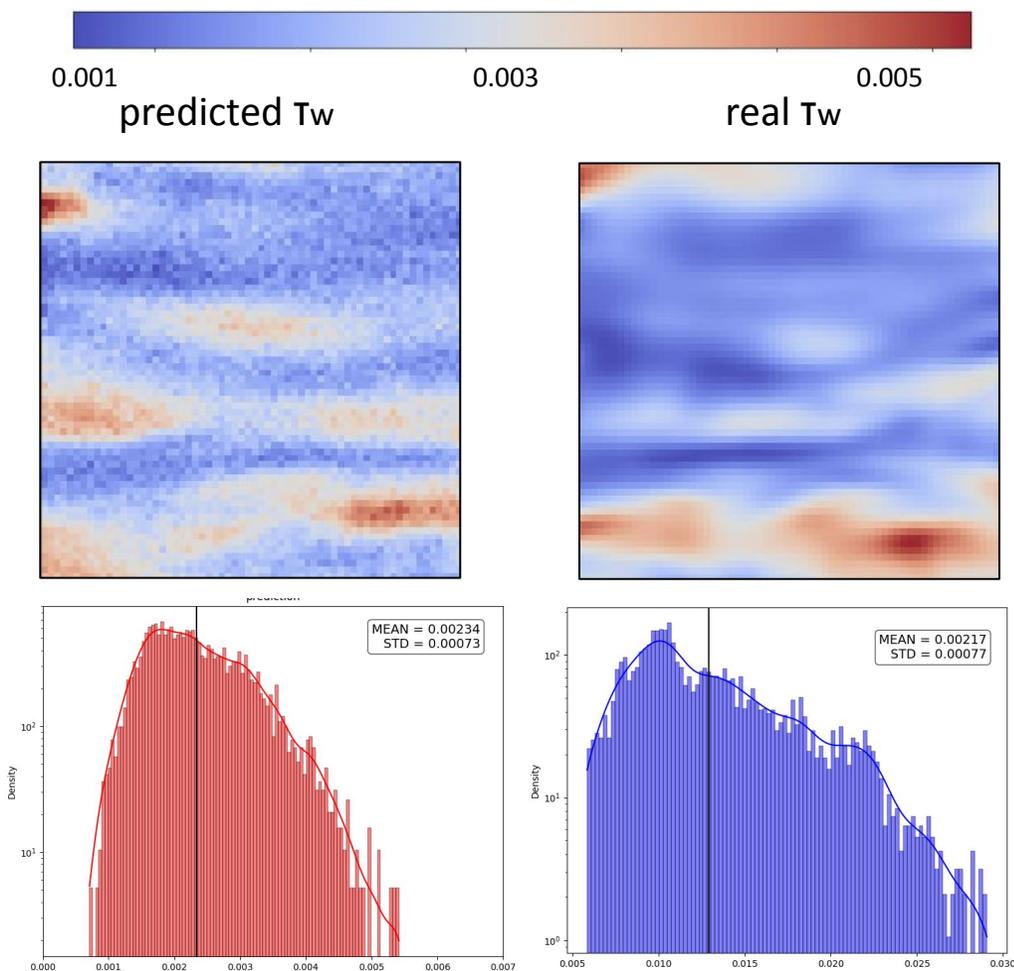


Conditioned DDPM for friction shear stress prediction

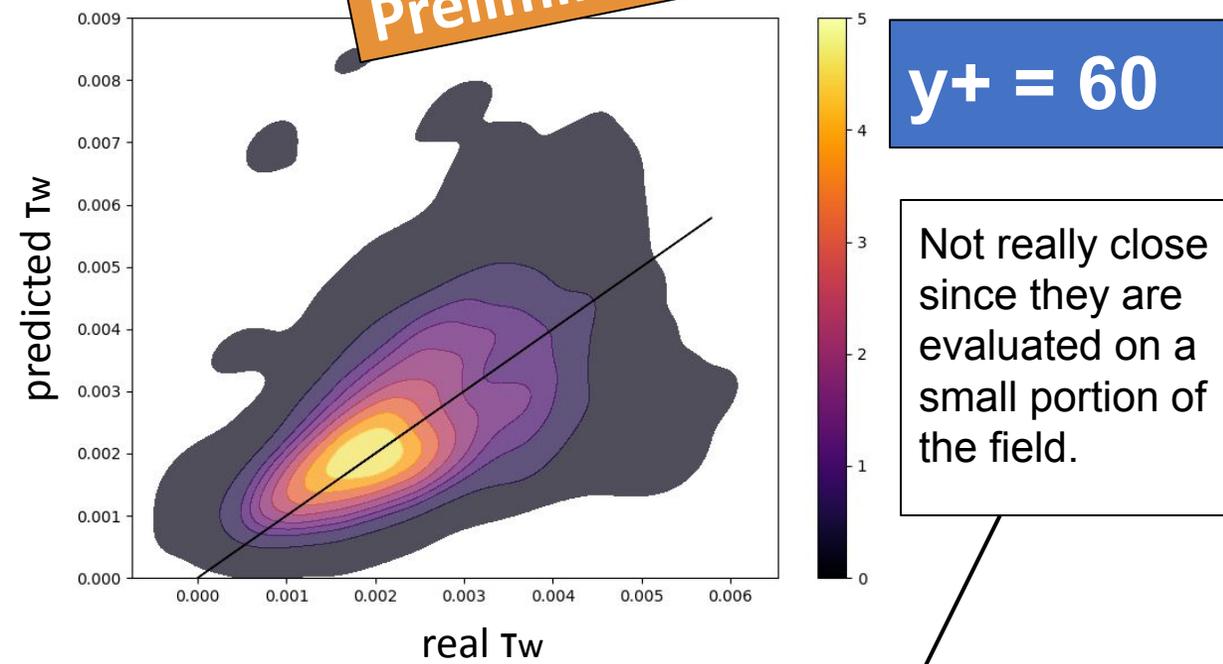
- **Input:** small noised portion of τ_w field
- **Conditions:** corresponding portion of a velocity field and the related matching locations (y^+)
- **Training:** learn how to re-obtain the real τ_w reversing the forward process (addition of noise) using the guidance given by the conditions
- **Inference:** generate realistic tauwall that agree with the velocity field given as condition



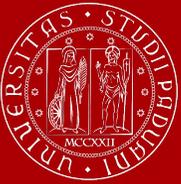
Conditioned DDPM for predicting friction shear stresses: *a priori* analysis



Preliminary Results



	prediction	target
Mean	0.00234	0.00217
Std	0.0073	0.0077



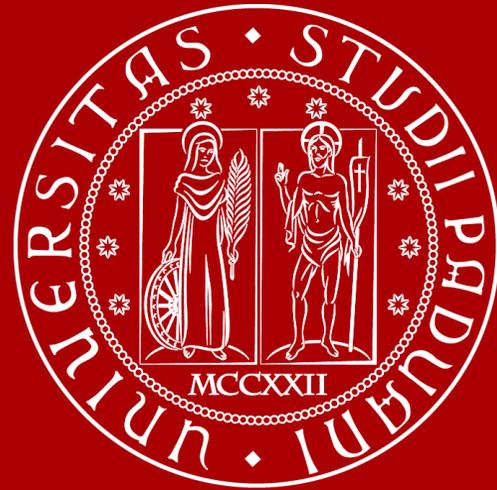
Conclusion:

- Simple MLP shows slightly better performances compare to EWM but struggles to represent the rare value of τ_w that are far from the mean
- Diffusion Models are able to learn spatial correlations, hence they describe the τ_w distribution better compare to MLP and EWM

Next Steps:

- Improve current Diffusion Model (fine-tuning the hyperparameters, introduce physical constraints)
- Perform *a priori* analysis on different cases for assessing model generalizability
- Explore different types of Diffusion Models (Score-based, Latent diffusion etc.)
- Explore different strategies to speed-up the inference phase and perform *a posteriori* analysis

Thanks for the attention



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