

Development of tether-in-space technology for propellant-less propulsion and artificial gravity

Anese Giovanni - 39th Cycle Meeting - 19/10/2023



Research activities





Tethered satellites

Two modules connected by a tether.

Propellant-less propulsion.

Different types:

- Electro Dynamic Tethers (EDTs).
- Momentum Exchange Tethers (METs).
- Artificial Gravity Spinning System (AGSS).





Main objectives





1. Development of software for simulation.

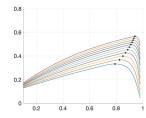


Tethered satellites



2. Study systems performances.

3. Optimize systems characteristics.





4. Study different applications.



Electro Dynamic Tethers

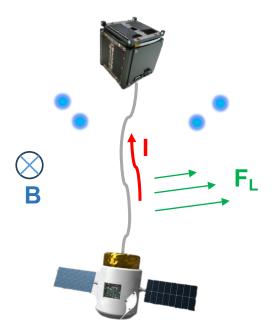




Tethered satellites

EDTs

- Conductive tether able to collect electrons from the ionosphere.
- Lorentz Force.
- Passive and active systems.
- Deorbiting and thrust.
- · Orbital Maneuvers.





Electro Dynamic Tethers





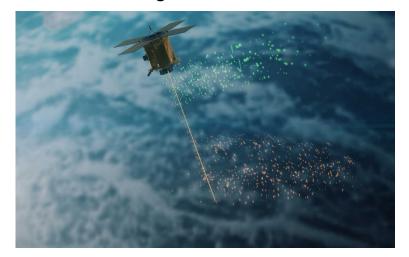
Tethered satellites

EDTs

- E.T.PACK-F project.
- FLEXSIM and FLEX software packages.



- Test the system.
- Demonstration flight in 2025.



Anese Giovanni 5



Artificial Gravity Spinning Systems





Tethered satellites

EDTs

AGSS

- Slow spinning system (1-2 rpm).
- Generation of a centripetal acceleration similar to the gravity on the Earth.
- Improve comfort for the astronauts.
- Reduce the non desired health effects due to wheigthlessness.







Momentum Exchange Tethers





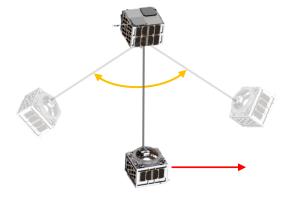
Tethered satellites

EDTs

AGSS

METs

- Conservation of angular momentum.
- Generation of ΔV.
- Orbital maneuvers.





Research activity



Development of tether-in-space technology for propellant-less propulsion and artificial gravity

Year of PhD	Activity	Goals
First year	Electro Dynamic Tethers	Software developmentPassive and active EDTsOrbital maneuvers
Second year	Artificial Gravity Spinning Systems	Software developmentSystem optimizations
Third year	Momentum Exchange Tethers	Software developmentOrbital maneuvers

Anese Giovanni 8

Thanks for the attention





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