

Towards a Collaborative Distributed Ground Station for Small CubeSat Teams

11. December, 2015

Lasse Bromose
Anders Ellersgaard Kalør
Jesper Abildgaard Larsen

Department of Electronic Systems
Aalborg University



AALBORG UNIVERSITY
DENMARK

Disposition



Motivation

Overall requirements

Decentralized coordination

Receiving from multiple ground stations

Implementation

Simulation results

Conclusions

Experience from AAUSAT5

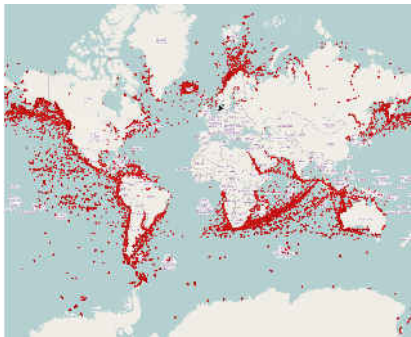
Acknowledgements

- ▶ AAU CubeSat - 2003
- ▶ AAUSAT-II - 2008
- ▶ AAUSAT3 - 2013
- ▶ AAUSAT5 - 2015
- ▶ AAUSAT4 - 2016



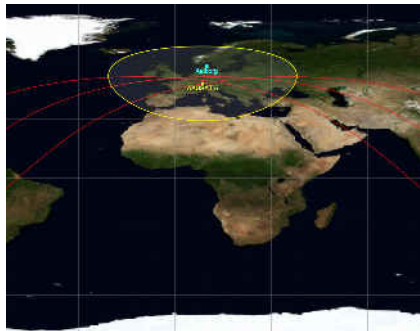
Experience from AAUSAT3

- ▶ More payload data was produced that we were able to download



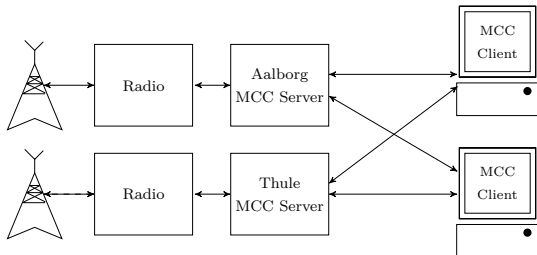
AAUSAT5

- ▶ AAUSAT5 was ejected into ISS orbit
- ▶ 52° inclination
- ▶ Aalborg is located at $+57^\circ$ latitude, resulting in short passes



The previous setup

Two ground stations, one in Aalborg (Denmark) and one in Thule (Greenland)



Scalability

- ▶ Long term goal of including radio amateurs

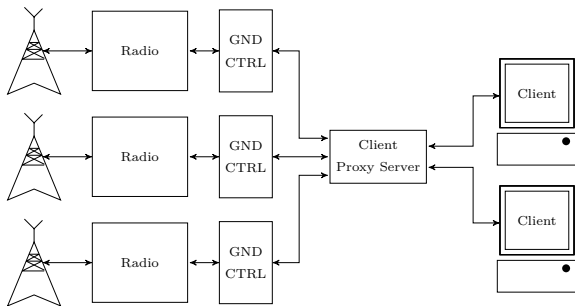
Decentralized and fault-tolerant coordination

- ▶ No single point of failure

Data-link protocol independent

- ▶ Support for multiple protocols, e.g. AX.25 and CSP

The new setup



- ▶ Requires coordination
- ▶ Allows for multiple receivers

Decentralized coordination



- ▶ Must be highly scalable
- ▶ Tolerant of sporadic crashes
- ▶ Should not introduce high delays

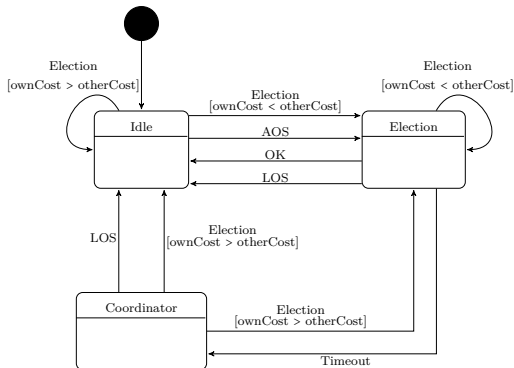


- ▶ Must be highly scalable
- ▶ Tolerant of sporadic crashes
- ▶ Should not introduce high delays
- ▶ Can be seen as a distributed leader election
- ▶ A modified bully algorithm has been implemented

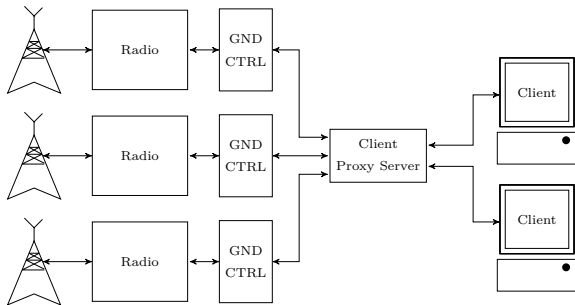
The modified Bully algorithm



- ▶ Uses a dynamic cost function, based on elevation and pass duration
- ▶ Triggers election on AOS and LOS
- ▶ Triggers election periodically during passes

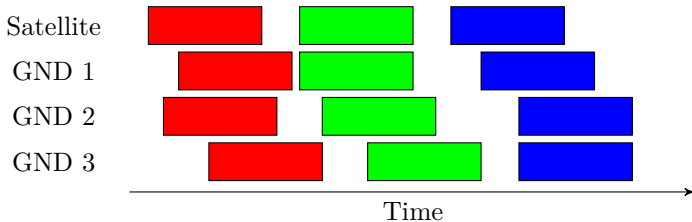


Receiving from multiple ground stations

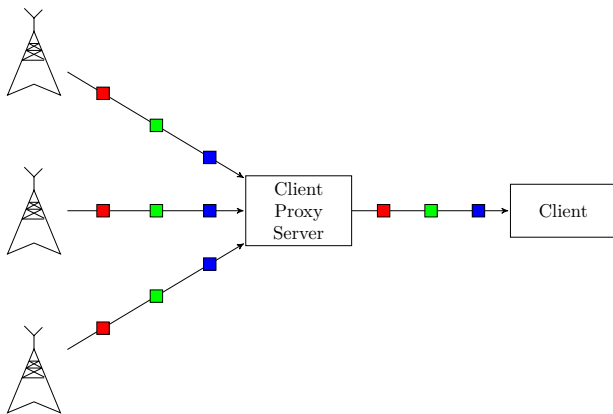


- ▶ Requires coordination
- ▶ Allows for multiple receivers

Frame alignment



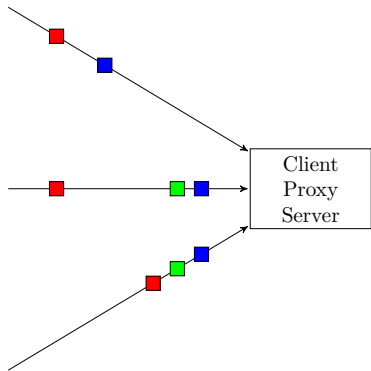
Receiving from multiple ground stations



Receiving from multiple ground stations



- ▶ It is unknown how many frames were received
- ▶ By estimating the network delay a probabilistic upper bound can be found



GND CTRL

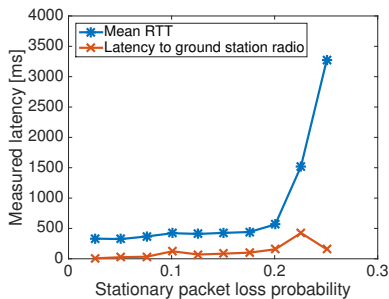
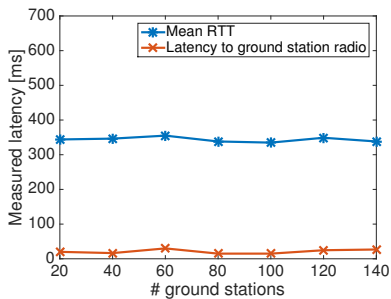
- ▶ In Java, with Akka Actors
- ▶ Generic radio interface

Client Proxy Server

- ▶ In Java, with Akka Actors
- ▶ MongoDB to keep track of connected ground stations and satellites
- ▶ Packet alignment and combining
- ▶ RabbitMQ for communication between ground stations and the Client Proxy Server

Simulation results

- ▶ Highly scalable
- ▶ Tolerant of packet loss and latency



- ▶ Highly scalable design
 - ▶ Increasing number of nodes does not influence performance
- ▶ Tolerant to packet losses
- ▶ The decentralized coordination based on a simple model
 - ▶ The model could be extended with data from the ground stations
- ▶ GNU Radio interface in development

- ▶ Running 3 ground stations; AAU, Austria, Germany
- ▶ Decentralized coordination functioning
- ▶ Weak signals from AAUSAT5; frame alignment and combining not tested
- ▶ Still undergoing evaluation

Acknowledgements



Questions?

