

# Study and Development of Throttleable Hybrid Rocket Motors

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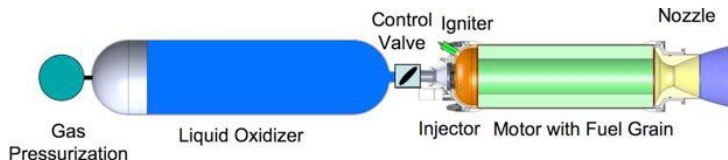
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# Introduction to Hybrid Rocket Motors



## Main characteristics

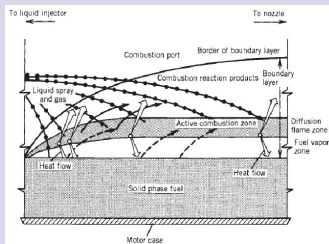
- Oxidizer in the tank, Fuel in the combustion chamber
- One controllable feeding line
- Different technological solutions and propellant formulations

# Pros & Cons of Hybrid Rocket Motors

## Advantages

- Safety during the handling and manufacturing  
⇒ Low operative cost
- Oxidizer flow control  
⇒ Mission abort and throttability
- Simpler than liquid engines  
⇒ Low manufacturing cost
- Reduced pollution and toxicity (Green propellants)
- Safety during development  
⇒ Low development cost

## Disadvantages



- Low regression rates
- Combustion efficiency
- $O/F$  shift ⇒ Lower specific impulse
- Unburned fuel sliver

# Why throttleability



- trajectory efficiency
- peculiar mission profiles

## Throttling methods

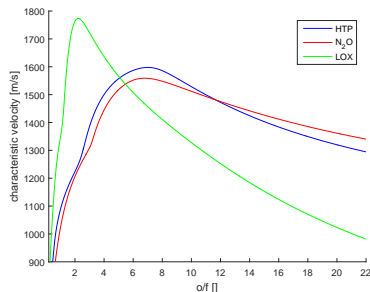
Methods derived from the liquid propulsive technology

- Variable injection area
  - ⇒ Maximum atomization
  - ⇒ Manufacturing requirements
  - ⇒ No catalytic injection
- Pressure drop
  - ⇒ Simple
- Variable area cavitating venturi
  - ⇒ Dissipative method
  - ⇒ Tank-CC uncoupling

# Present work

- HRM throttleability general considerations;
- Throttling method selection;
- Fixed throat cavitating venturi fluid dynamic analysis;
- Numerical simulations arrangement and validation;
- Variable area cavitating venturi design (just started).

# Throttleability of Hybrid Rocket Motors



$$o/f = \frac{\dot{m}_{ox}^{1-n} D_{port}^{2n-1}}{4^n \pi^{1-n} a \rho_f L}$$

Arbitrary throttling  $\Rightarrow$  o/f shift  $\Rightarrow$  Performance reduction

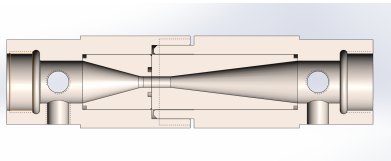
	LOX	N <sub>2</sub> O	HTP
max c* [m/s]	1773	1559	1598
c* sensitivity [m/s]	-369.9	-19.4	-22.3
Throttling 95% c*	5.6	6.2	5.3
Throttling 90% c*	15	18	13
Throttling 85% c*	37	45	30
Throttling 80% c*	90	165	70

Launch  $\frac{T_{max}}{T_{min}} \sim 3 ;$

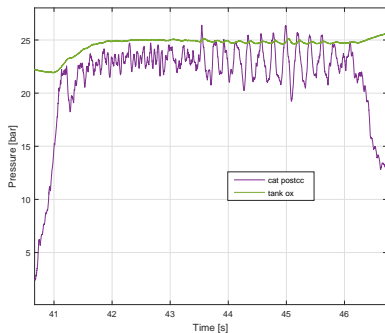
Soft Landing  $\frac{T_{max}}{T_{min}} \sim 15 ;$

# Cavitating venturi: principles

A venturi tube operating with a throat pressure equal to the vapor pressure. In this condition the venturi is choked.



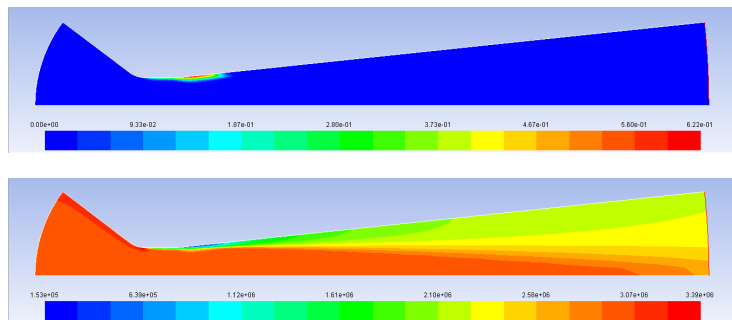
$$\dot{m}_{ox} = C_d A_{th} \sqrt{2 \rho_{ox} (p^{\circ} - p_{sat})}$$



## Peculiarities

- variable area  $\Rightarrow$  throttling
- if  $p_{up}^{\circ} > 0.9p_{down}^{\circ} \Rightarrow$  tank - combustion chamber uncoupling

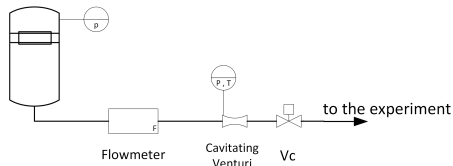
# Cavitating venturi: numerical simulations



- 2D RANS Numerical simulations of fixed throat CV
- Schnerr-Sauer model: 2 parameters



# Experimental activity: set-up & results



- Pressurized oxidizer tank
- Ultrasound flowmeter
- Fixed throat cavitating venturi
- Pneumatic valve

test n°	1	2	3	4	5	6	7	8
$\dot{m}_{ox}$ [kg/s]	2.347	2.182	2.288	2.319	2.053	1.978	2.068	1.968
$p_{up}^o$ [bar]	29.15	26.76	28.64	28.87	23.17	21.89	23.37	22.30
exp. $C_D$ []	0.9185	0.8912	0.9046	0.9132	0.9026	0.8933	0.9038	0.8850
unc. $C_D$ []	0.0266	0.0257	0.0271	0.0283	0.0275	0.0307	0.0269	0.0273
num1 $C_D$ []	0.9544	0.9491	0.9398	0.9473	0.9588	0.9456	0.9544	0.9360
num2 $C_D$ []	0.9125	0.9088	0.9138	0.8953	0.9047	0.9047	0.9082	0.8968

# Experimental activity: set-up



# Future work

- Conclude the fluid dynamic design and analysis of the variable area cavitating venturi, using the same cavitation model of the fixed throat venturi;
- Quasi-stationary characterization of the variable area cavitating venturi;
- Pintle position automatic control;
- Dynamic characterization VACV;
- VACV integration with the existing oxidizer line;
- Motor throttling tests

# Activity organization

Level	Activity (Work Package)	hours	year I				year II				year III			
<b>1   0   0</b>	<b>State of the art analysis</b>	<b>270</b>	<b>230</b>	<b>40</b>										
1   1   0	Bibliographical research	70	70											
1   2   0	Numerical methods of design	100	80	20										
1   3   0	Experimental methods of analysis	100	80	20										
<b>2   0   0</b>	<b>Numerical Analysis</b>	<b>990</b>	<b>30</b>	<b>220</b>	<b>260</b>	<b>240</b>	<b>170</b>	<b>70</b>						
2   1   0	Definition of the driving parameters	80		80										
2   2   0	Design of the throttling systems	200	20	80	80	20								
2   3   0	Design of the engine	150	10	20	80	40								
2   4   0	Throttling Numerical Analysis	310		40	100	90	80							
2   5   0	Engine Numerical Analysis	250				90	90	70						
<b>3   0   0</b>	<b>Experimental Analysis</b>	<b>1680</b>				<b>20</b>	<b>150</b>	<b>230</b>	<b>290</b>	<b>270</b>	<b>240</b>	<b>240</b>	<b>160</b>	<b>80</b>
3   1   0	Experimental set-up arrangement	410				20	130	30	30	140	30	30		
3   2   0	Test campaign (Throttling device)	410					20	180	180	30				
3   3   0	Test campaign (Whole engine)	340								20	130	130	60	
3   4   0	Data analysis and validation	520						20	80	80	80	80	100	80
<b>4   0   0</b>	<b>Exploitation</b>	<b>120</b>											<b>20</b>	<b>100</b>
4   1   0	Cost-effective solutions	60											20	40
4   2   0	Deep-throttling main ascent/descent engines	30												30
4   3   0	Sounding rockets and small boosters	30												30
<b>5   0   0</b>	<b>Compilation of Thesis and Reports</b>	<b>690</b>					<b>20</b>	<b>50</b>	<b>50</b>	<b>70</b>	<b>100</b>	<b>100</b>	<b>150</b>	<b>150</b>

# Conclusion

Thank you! Any question?